

Service Manual

Pioneer

DEH-P8000R/UC



ORDER NO.
CRT2344

MULTI-CD/DAB CONTROL HIGH POWER CD PLAYER WITH RDS TUNER

DEH-P8000R

UC

MULTI-CD CONTROL HIGH POWER CD PLAYER WITH FM/AM TUNER

DEH-P8050

ES

COMPACT
disc
DIGITAL AUDIO

- See the separate manual CX-916(CRT2300) for the CD mechanism description, disassembly and circuit description.
- The CD mechanism employed in this model is one of S8 series.

SERVICE PRECAUTION

In the first production, the following parts had been mounted temporarily to support the microcomputer
<DEH-P8000R/UC> IC601 (PD5487A): R591 (RS1/16S473J), R592 (RS1/16S102J), and IC591 (Non spare part).
When replacing IC601 PD5487A, use PD5487B as IC601, and then remove the 3 parts listed above.
<DEH-P8050/ES> IC601 (PD5488A): R591 (RS1/16S473J), R592 (RS1/16S102J), and IC591 (Non spare part).
When replacing IC601 PD5488A, use PD5488B as IC601, and then remove the 3 parts listed above.

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● CD Player Service Precautions

1. For pickup unit(CXX1285) handling, please refer to "Disassembly"(see page 51).
During replacement, handling precautions shall be taken to prevent an electrostatic discharge(protection by a short pin).
2. During disassembly, be sure to turn the power off since an internal IC might be destroyed when a connector is plugged or unplugged.
3. Please checking the grating after changing the service pickup unit(see page 49).

1. SAFETY INFORMATION

CAUTION

This service manual is intended for qualified service technicians; it is not meant for the casual do-it-yourselfer. Qualified technicians have the necessary test equipment and tools, and have been trained to properly and safely repair complex products such as those covered by this manual.

Improperly performed repairs can adversely affect the safety and reliability of the product and may void the warranty. If you are not qualified to perform the repair of this product properly and safely; you should not risk trying to do so and refer the repair to a qualified service technician.

WARNING

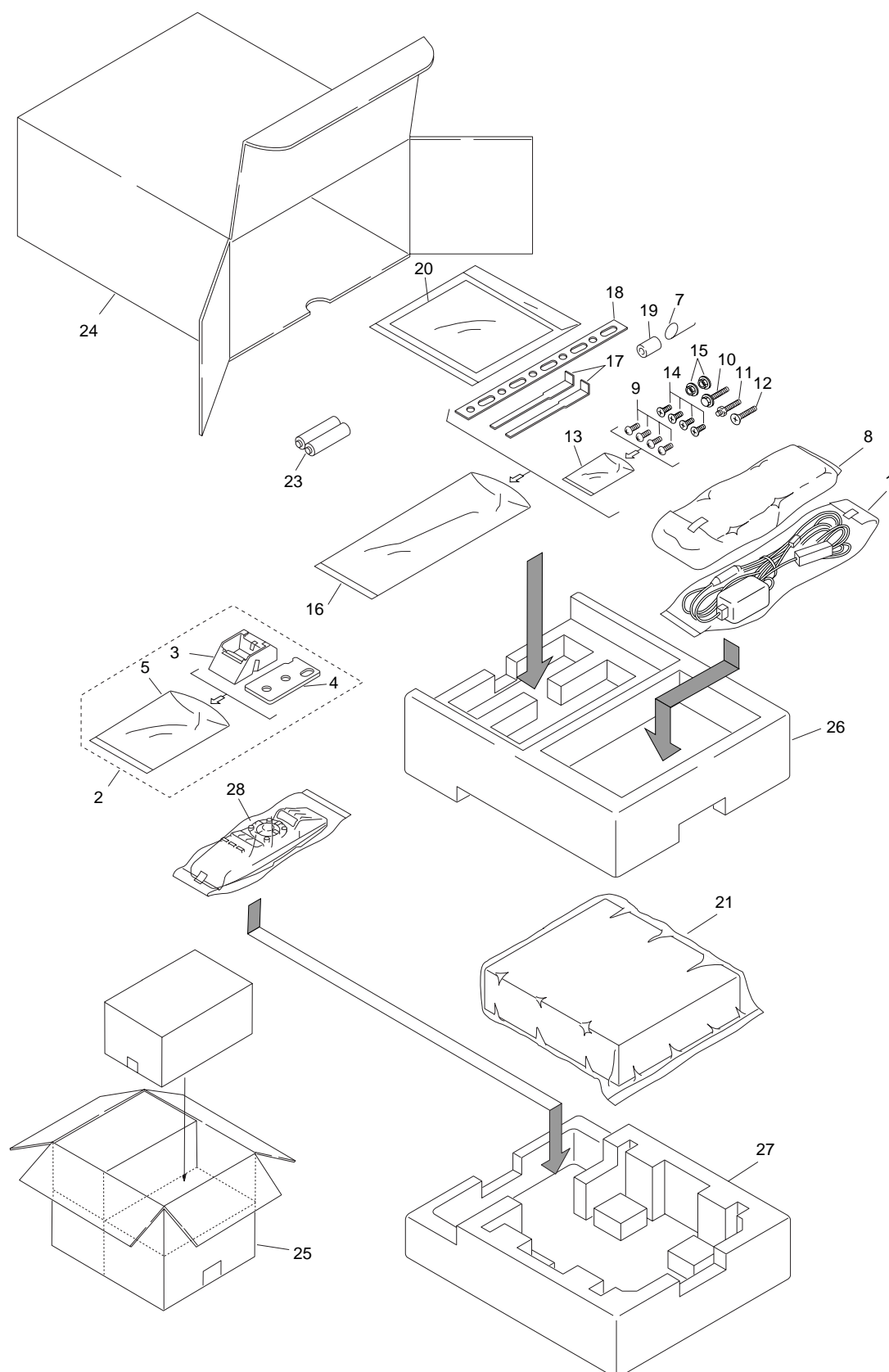
This product contains lead in solder and certain electrical parts contain chemicals which are known to the state of California to cause cancer, birth defects or other reproductive harm.

Health & Safety Code Section 25249.6 - Proposition 65

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2. EXPLODED VIEWS AND PARTS LIST

2.1 PACKING



NOTE:

- Parts marked by “*” are generally unavailable because they are not in our Master Spare Parts List.
- Screws adjacent to ∇ mark on the product are used for disassembly.

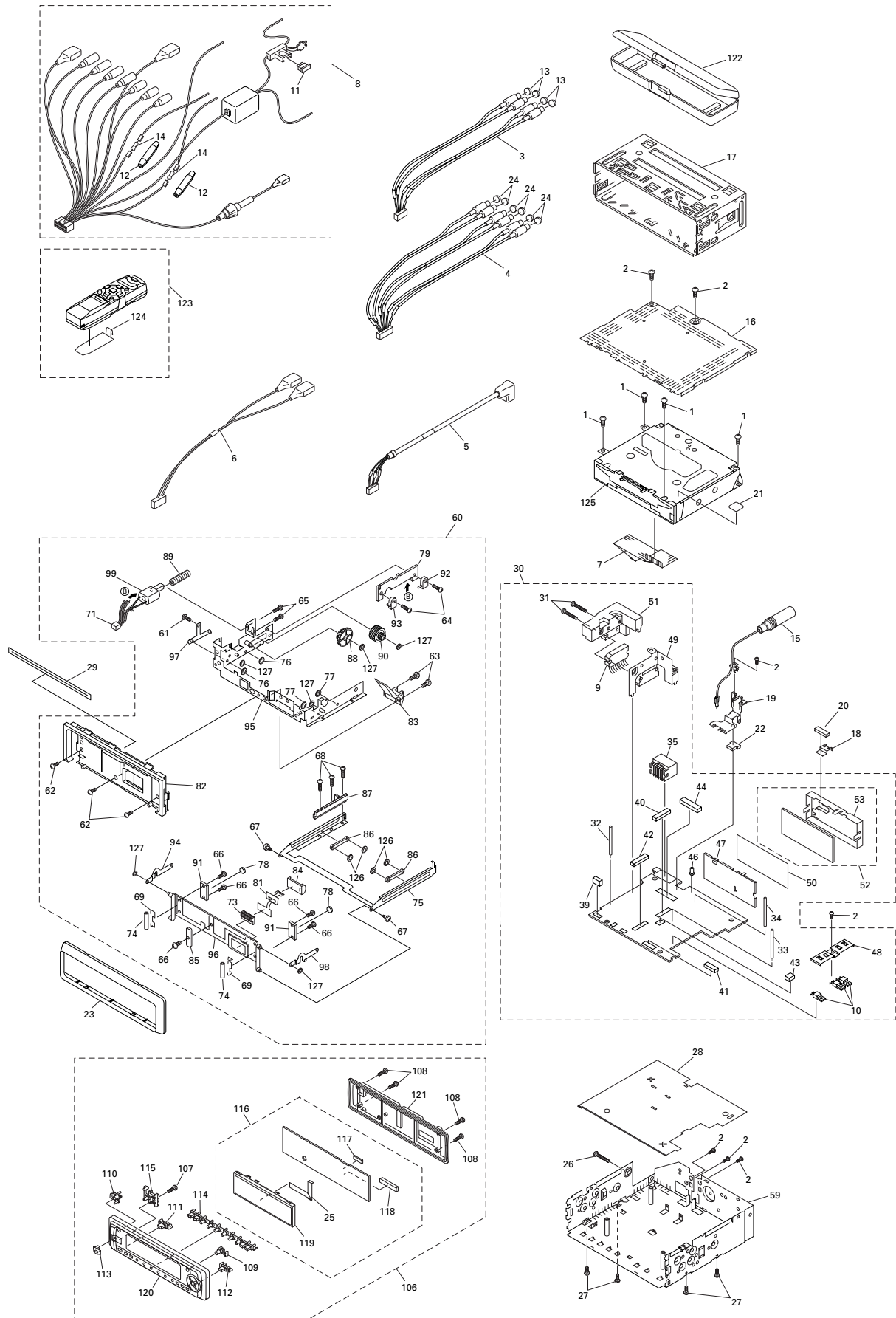
● PACKING SECTION PARTS LIST

Mark	No.	Description	Part No.	
			DEH-P8000R/UC	DEH-P8050/ES
	1	Cord Assy	CDE5854	CDE5854
	2	Base Assy	CEA2426	CEA2426
*	3	Base	CNS5031	CNS5031
*	4	Sheet	CZA3371	CZA3371
	5	Polyethylene Bag	CZE3188	CZE3188
	6		
	7	Spring	CBH-865	CBH-865
	8	Case Assy	CXB3520	CXB3520
	9	Screw	BMZ50P060FMC	BMZ50P060FMC
	10	Screw	CBA-102	Not used
	11	Screw	CBA1002	CBA1002
	12	Screw	CBA1120	CBA1120
*	13	Polyethylene Bag	CEG-127	CEG-127
	14	Screw	CMZ50P060FMC	CMZ50P060FMC
	15	Nut	NF50FMC	Not used
*	16	Polyethylene Bag	CEG-158	CEG-158
	17	Handle	CNC5395	CNC5395
	18	Strap	CNF-111	Not used
	19	Bush	CNV1917	CNV1917
	20-1	Polyethylene Bag	CEG1116	CEG1116
	20-2	Owner's Manual	CRD2974	CRD2980
	20-3	Owner's Manual	Not used	CRD2981
	20-4	Installation Manual	CRD2975	CRD2982
*	20-5	Caution Card	CRP1207	CRP1207
*	20-6	Card	ARY1048	Not used
*	20-7	Caution Card	CRP1209	CRP1210
	21	Polyethylene Bag	CEG1185	* CEG1088(Cover)
	22		
	23	Battery	CEX1006	CEX1006
	24	Carton	CHG3775	CHG3773
	25	Contain Box	CHL3775	CHL3773
	26	Protector	CHP2032	CHP2032
	27	Protector	CHP2033	CHP2033
	28	Remote Control Assy	CXB3875	CXB3875

● Owner's Manual, Installation Manual



Model	Part No.	Language
DEH-P8000R/UC	CRD2974	English, French
	CRD2975	English, French
DEH-P8050/ES	CRD2980	English, Spanish
	CRD2981	Portuguese, Arabic
	CRD2982	English, Spanish, Portuguese, Arabic

2.2 EXTERIOR





(1) EXTERIOR SECTION PARTS LIST

Mark No.	Description	Part No.	Mark No.	Description	Part No.
1	Screw	BSZ26P060FMC	51	Heat Sink	CNR1535
2	Screw	BSZ30P050FMC	52	FM/AM Tuner Unit	CWE1501
3	Cap	See Contrast table(2)	53	Holder	CNC7532
4	Cord Assy	See Contrast table(2)	54	
5	Cord Assy	CDE5842	55	
6	Cord Assy	See Contrast table(2)	56	
7	Connector	CDE5846	57	
8	Cord Assy	CDE5854	58	
9	IC(IC301)	PAL005A	59	Chassis Unit	CXB3556
10	Transistor(Q803,921,998)	2SD2396	60	Panel Assy	CXB3578
11	Fuse(10A)	CEK1136	61	Screw	BMZ20P030FMC
12	Cap	CNS1472	62	Screw	CBA1154
13	Cord Assy	See Contrast table(2)	63	Screw	BPZ20P060FMC
14	Resistor	RS1/2PMF102J	64	Screw	CBA1060
15	Antenna Cable	CDH1256	65	Screw	CBA1061
16	Case	CNB2426	66	Screw	CBA1082
17	Holder	CNC6798	67	Screw	CBA1430
18	Earth Terminal	See Contrast table(2)	68	Screw	CBA1454
19	Holder	CNC8170	69	Spring	CBH2130
20	Spacer	See Contrast table(2)	70	
21	Cushion	CNM6065	71	Cord	CDE5960
22	Cushion	CNM6387	72	
23	Panel	See Contrast table(2)	73	Connector	CKS3997
24	Cap	See Contrast table(2)	74	Roller	CLA3583
* 25	PCB	CNP5508	75	Frame	CNC8201
26	Screw	BSZ30P200FMC	76	Spacer	CNM6155
27	Screw	CBA1447	77	Spacer	CNM6156
28	Insulator	CNM6135	78	Spacer	CNM6419
29	Cover	CNM6489	79	PCB	CNP5321
30	Tuner Amp Unit	See Contrast table(2)	80	
31	Screw	BMZ26P160FMC	81	PCB	CNP5355
32	Clamper	CEF1004	82	Panel	CNS5247
33	Clamper	See Contrast table(2)	83	Lighting Conductor	CNV5605
34	Clamper	CEF1009	84	Cover	CNV5610
35	Plug(CN901)	CKM1278	85	Guide	CNV5672
36		86	Guide	CNV5696
37		87	Rack	CNV5697
38		88	Gear	CNV5698
39	Plug(CN851)	CKS-786	89	Gear	CNV5761
* 40	Plug(CN101)	CKS1058	90	Torque Limiter Unit	CNV5762
41	Connector(CN801)	CKS1532	91	Holder	CNV5763
42	Connector(CN991)	CKS1960	92	Switch(S951)	CSN1012
43	Connector(CN681)	See Contrast table(2)	93	Switch(S952)	CSN1022
44	Connector(CN351)	See Contrast table(2)	94	Arm Unit	CXB3574
45		95	Frame Unit	CXB3575
46	Mini Pin Jack(CN451)	CKX1046	96	Holder Unit	CXB3576
47	Holder	See Contrast table(2)	97	Bracket Unit	CXB3577
48	Holder	CNC8168	98	Arm Unit	CXB3866
49	Holder	CNC8169	99	Motor(M951)	CXM1085
50	Insulator	See Contrast table(2)	100	

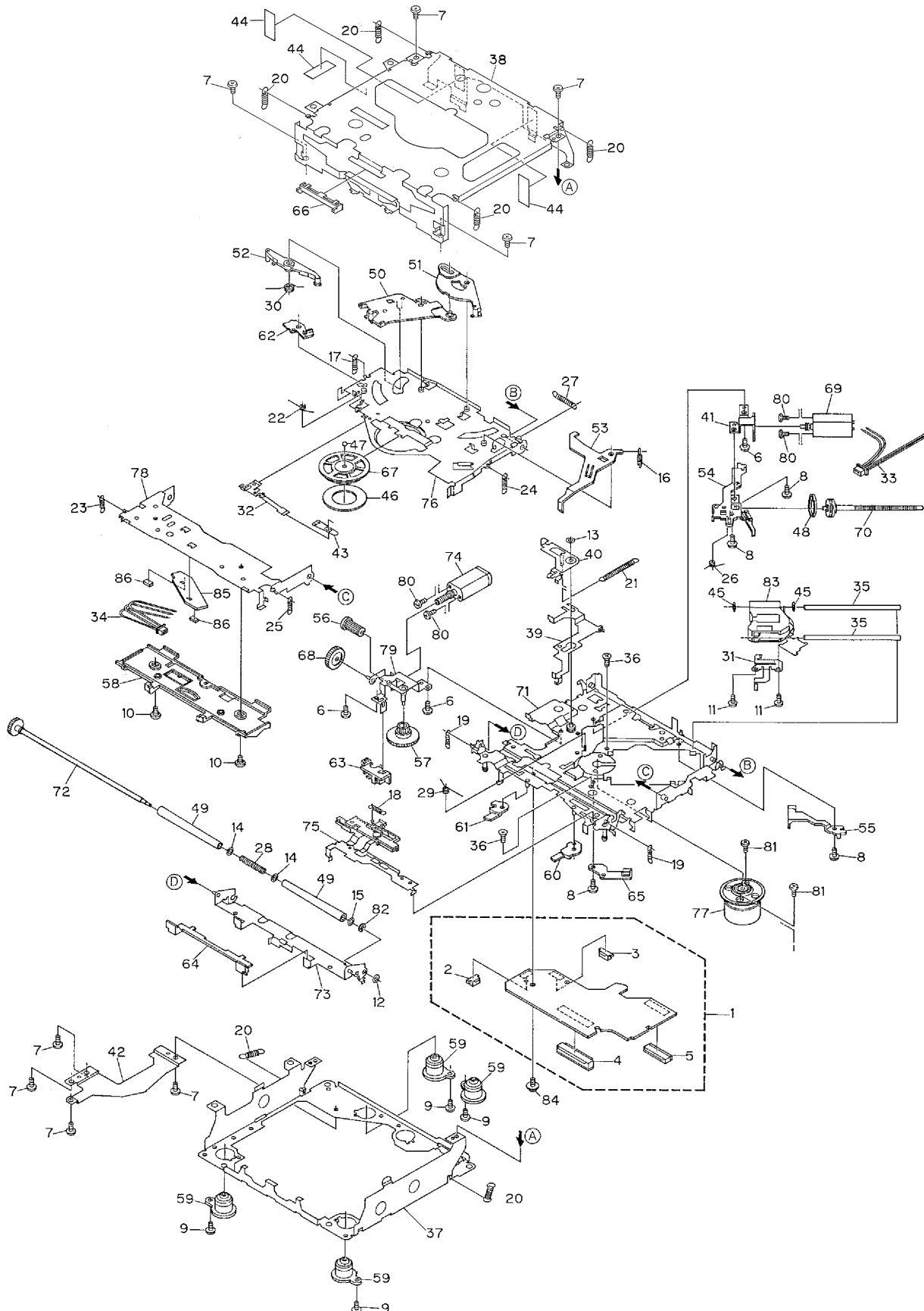
Mark No.	Description	Part No.	Mark No.	Description	Part No.
101		116	Keyboard Unit	CWM6226
102		117	Connector(CN1902)	CKS3995
103		118	Connector(CN1901)	CKS3996
104		119	OEL Module	MXK8002
105		120	Grille Unit	See Contrast table(2)
106	Detach Grille Assy	See Contrast table(2)	121	Cover Unit	See Contrast table(2)
107	Screw	BPZ20P060FMC	122	Case Assy	CXB3520
108	Screw	BPZ20P080FZK	123	Remote Control Assy	CXB3875
109	Button()	See Contrast table(2)	124	Battery Cover	CNS5032
110	Button(D)	CAC5891	125	CD Mechanism Module(S8)	CXK5251
111	Button(SOURCE)	See Contrast table(2)	126	Washer	2-1816-0035-D2-00
112	Button()	See Contrast table(2)	127	Washer	2-1821-0045-D2-00
113	Button(EQ)	See Contrast table(2)			
114	Button(1-6)	See Contrast table(2)			
115	Housing	CNV5606			

(2) CONTRAST TABLE

DEH-P8000R/UC and DEH-P8050/ES are constructed same except for the following:

Mark No.	Description	Part No.	
		DEH-P8000R/UC	DEH-P8050/ES
3	Cord Assy	Not used	CDE5841
4	Cord Assy	CDE5840	Not used
6	Cord Assy	Not used	CDE5844
13	Cap	Not used	CNV2680
18	Earth Terminal	CNC7358	CNC6469(Holder)
20	Spacer	CNM6482	CNM4870(Cushion)
23	Panel	CNS5256	CSN5548
24	Cap	CNV2680	Not used
30	Tuner Amp Unit	CWM6222	CWM6224
33	Clamper	Not used	CEF1088
43	Connector(CN681)	Not used	CKS3597
44	Connector(CN351)	CKS3606	CKS3602
47	Holder	CNC7533	Not used
50	Insulator	CNM5967	Not used
106	Detach Grille Assy	CXB3980	CXB3288
109	Button()	CAC5890	CAC6126
111	Button(SOURCE)	CAC5892	CAC5901
112	Button()	CAC5893	CAC6045
113	Button(EQ)	CAC5894	CAC5899
114	Button(1-6)	CAC5910	CAC5911
120	Grille Unit	CXB3984	CXB3286
121	Cover Unit	CXB4309	CXB4310

2.3 CD MECHANISM MODULE



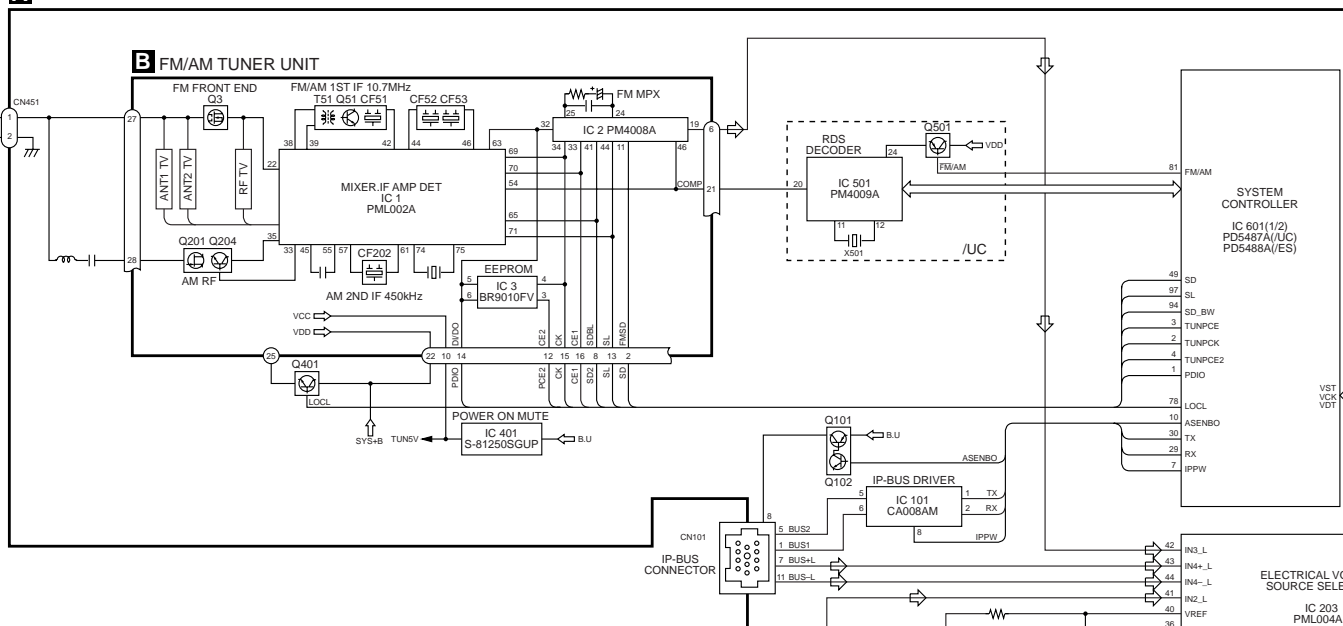
● CD MECHANISM MODULE SECTION PARTS LIST

Mark No.	Description	Part No.	Mark No.	Description	Part No.
1	Control Unit	CWX2358	46	Sheet	CNM6215
2	Connector(CN802)	CKS2192	47	Ball	CNR1189
3	Connector(CN801)	CKS2193	48	Belt	CNT1086
4	Connector(CN701)	CKS2771	49	Roller	CNV4509
5	Connector(CN101)	CKS3486	50	Arm	CNV5246
6	Screw	BMZ20P030FZK	51	Arm	CNV5247
7	Screw	BSZ20P040FZK	52	Arm	CNV5248
8	Screw(M2×3)	CBA1077	53	Arm	CNV5249
9	Screw(M2×6)	CBA1489	54	Guide	CNV5254
10	Screw	CBA1243	55	Guide	CNV5255
11	Screw(M2×4)	CBA1362	56	Gear	CNV5257
12	Washer	CBF1037	57	Gear	CNV5256
13	Washer	CBF1038	58	Guide	CNV5869
14	Washer	CBF1060	59	Damper	CNV5266
* 15	Washer	CBF1075	60	Arm	CNV5359
16	Spring	CBH2079	61	Arm	CNV5360
17	Spring	CBH2117	62	Arm	CNV5361
18	Spring	CBH2278	63	Guide	CNV5509
19	Spring	CBH2110	64	Guide	CNV5510
20	Spring	CBH2282	65	Holder	CNV5578
21	Spring	CBH2114	66	Guide	CNV5751
22	Spring	CBH2115	67	Clamper	CNV5758
23	Spring	CBH2080	68	Gear	CNV5813
24	Spring	CBH2118	69	Motor Unit(M1)	CXB2190
25	Spring	CBH2161	70	Screw Unit	CXB2191
26	Spring	CBH2163	71	Chassis Unit	CXB2192
27	Spring	CBH2189	72	Gear Unit	CXB2193
28	Spring	CBH2249	73	Arm Unit	CXB2194
29	Spring	CBH2260	74	Motor Unit(M2)	CXB2195
30	Spring	CBH2262	75	Lever Unit	CXB2553
31	Spring	CBL1367	76	Arm Unit	CXB2554
32	Spring	CBL1369	77	Motor Unit(M3)	CXB2562
33	Connector	CDE5531	78	Arm Unit	CXB2795
34	Connector	CDE5532	79	Bracket Unit	CXB4071
35	Shaft	CLA3304	80	Screw	JFZ20P025FMC
36	Screw(M2.6×6)	CBA1458	81	Screw	JGZ17P025FZK
37	Frame	CNC7544	82	Washer	YE15FUC
38	Frame	CNC7545	83	Pickup Unit(Service)(P8)	CXX1285
39	Lever	CNC7546	84	Screw	IMS26P030FMC
40	Arm	CNC7739	* 85	PCB	CNX2982
41	Bracket	CNC7798	86	Photo-transistor(Q1, 2)	CPT230SX-TU
42	Plate	CNC8090			
43	Spacer	CNM3315			
44	Sheet	CNM6170			
45	Cushion	CNM6204			

3. BLOCK DIAGRAM AND SCHEMATIC DIAGRAM

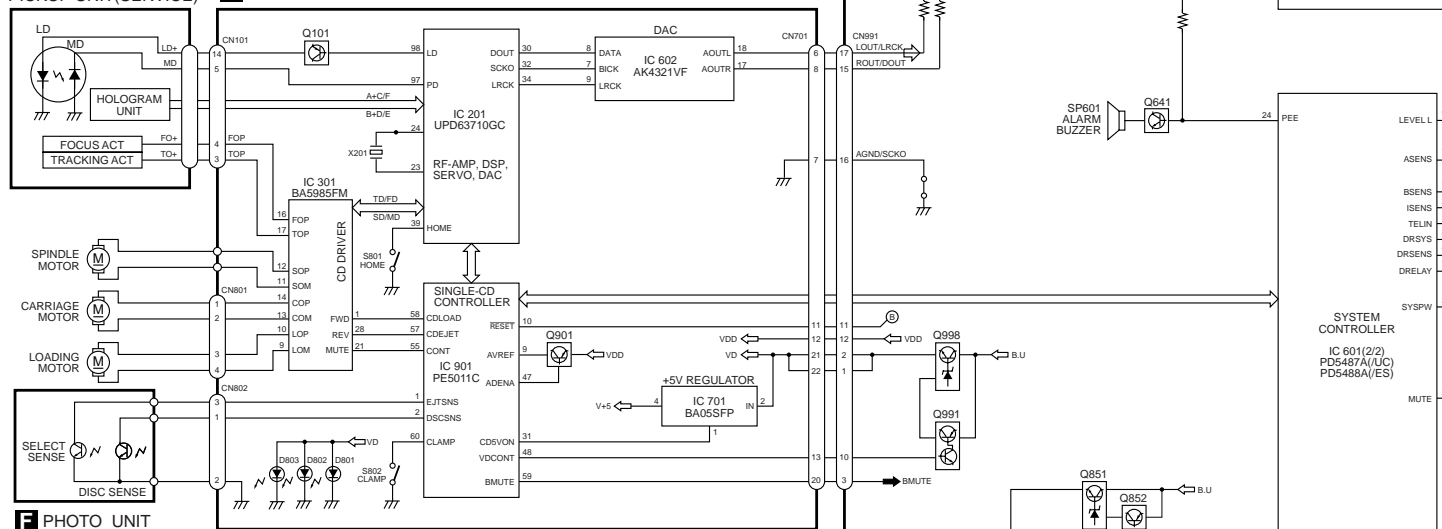
3.1 BLOCK DIAGRAM

A TUNER AMP UNIT



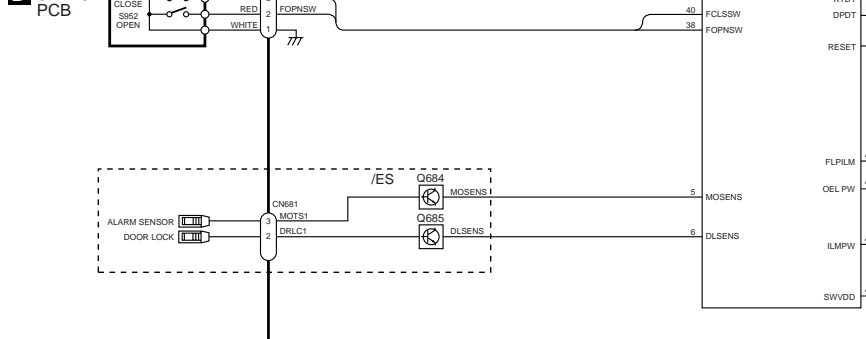
PICKUP UNIT(SERVICE)

E CONTROL UNIT

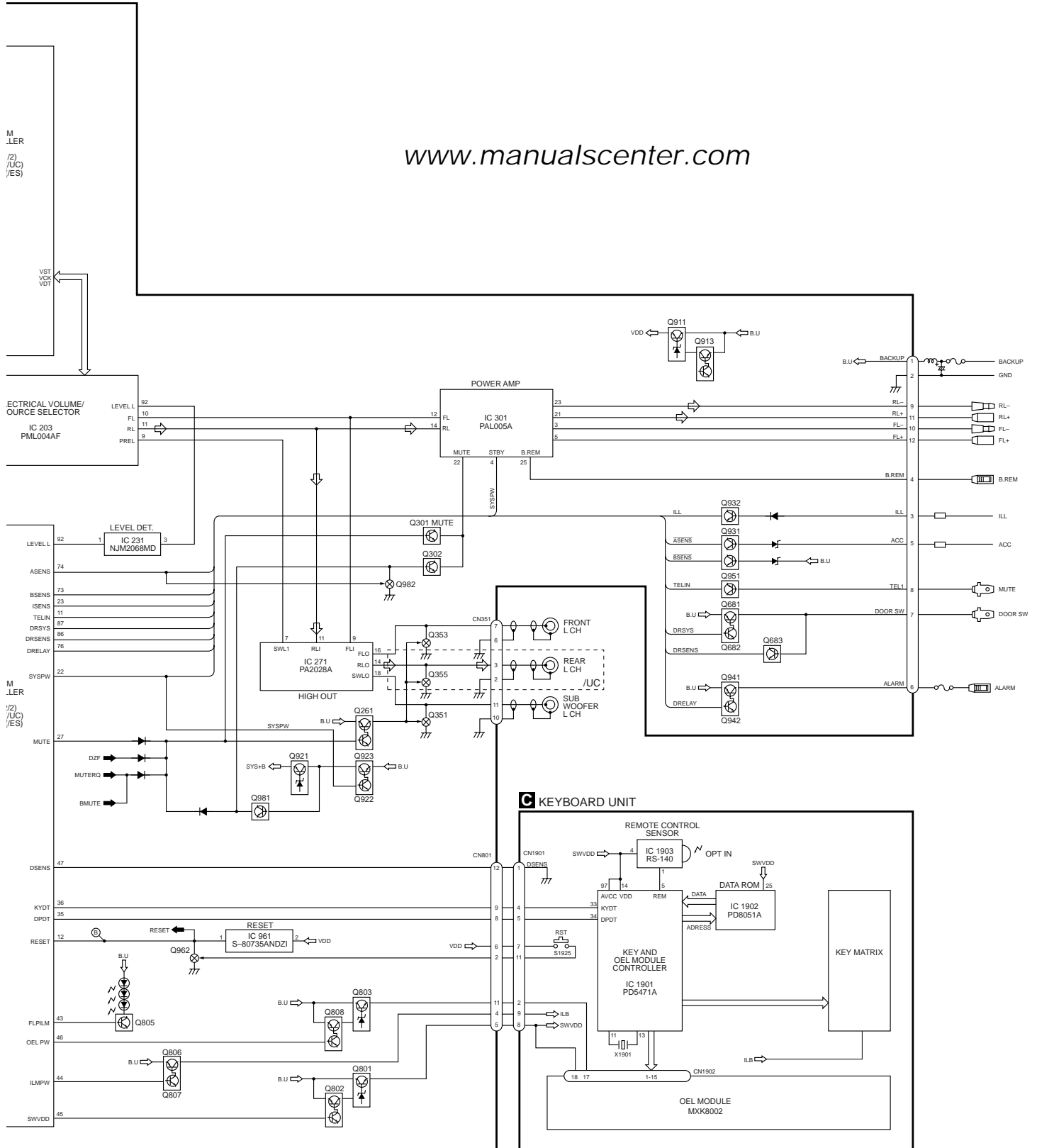


F PHOTO UNIT

D SWITCH PCB



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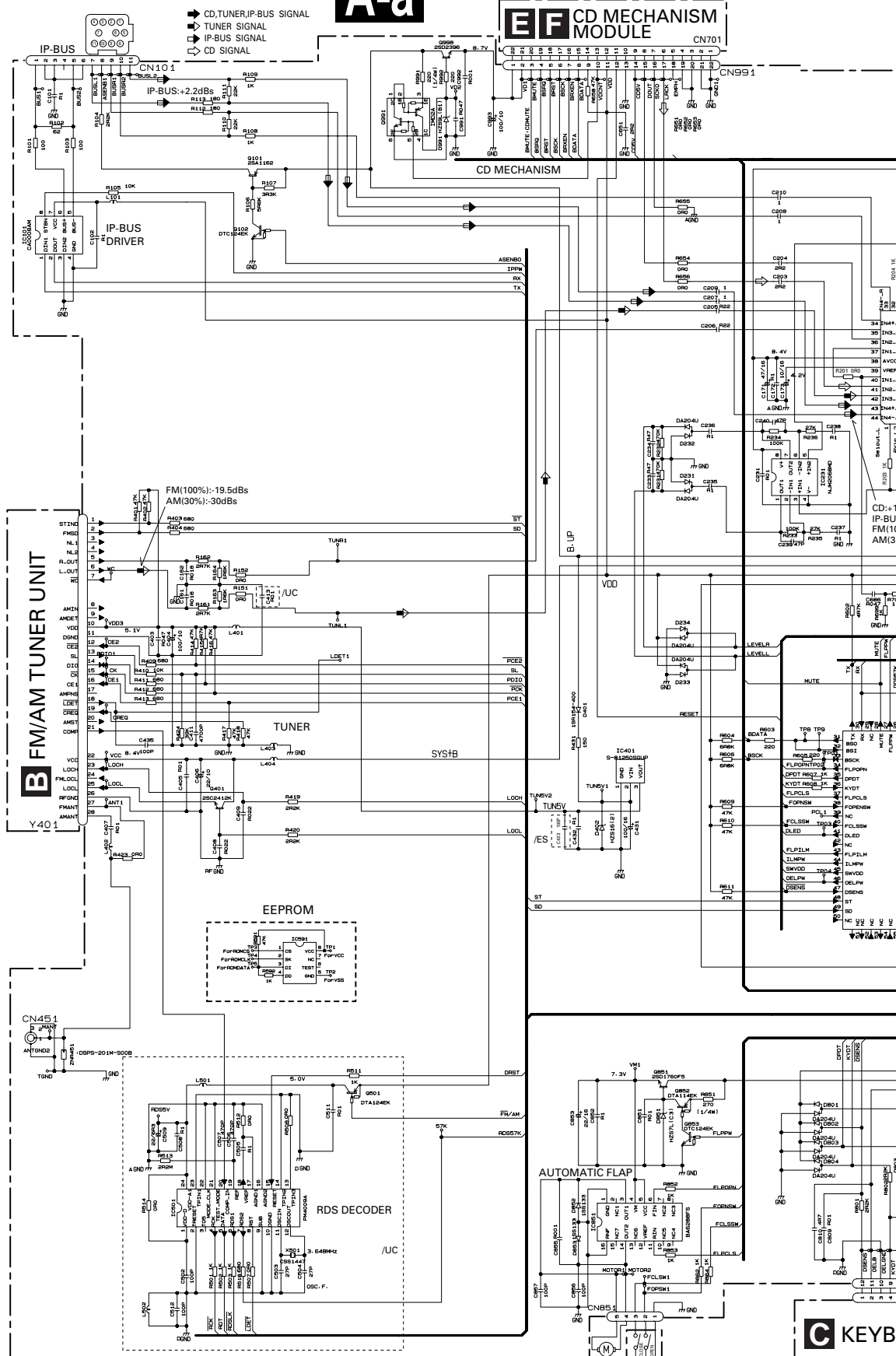


3.2 OVERALL CONNECTION DIAGRAM(GUIDE PAGE)

Note: When ordering service parts, be sure to refer to “EXPLODED VIEWS AND PARTS LIST” or “ELECTRICAL PARTS LIST”.

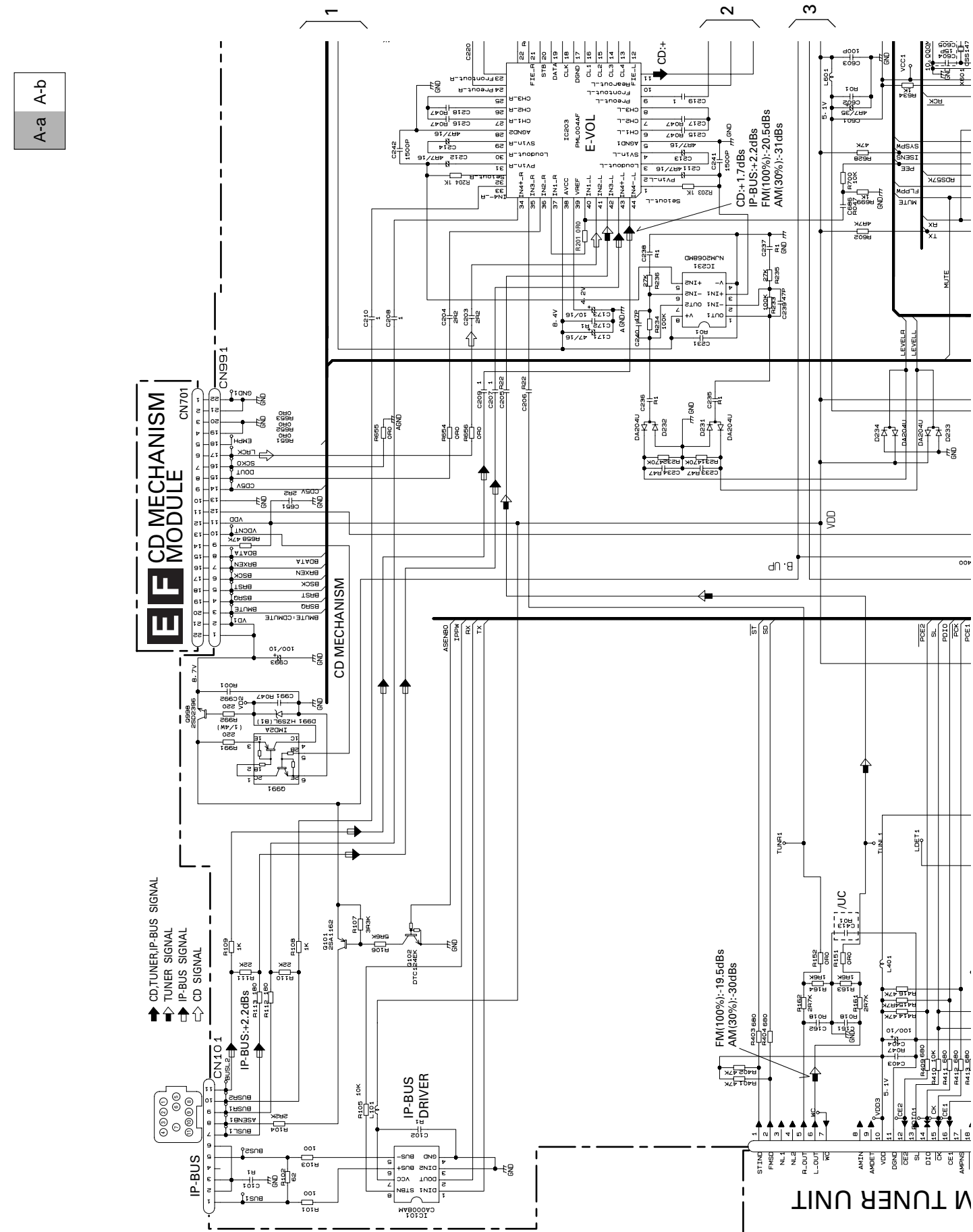
A-a

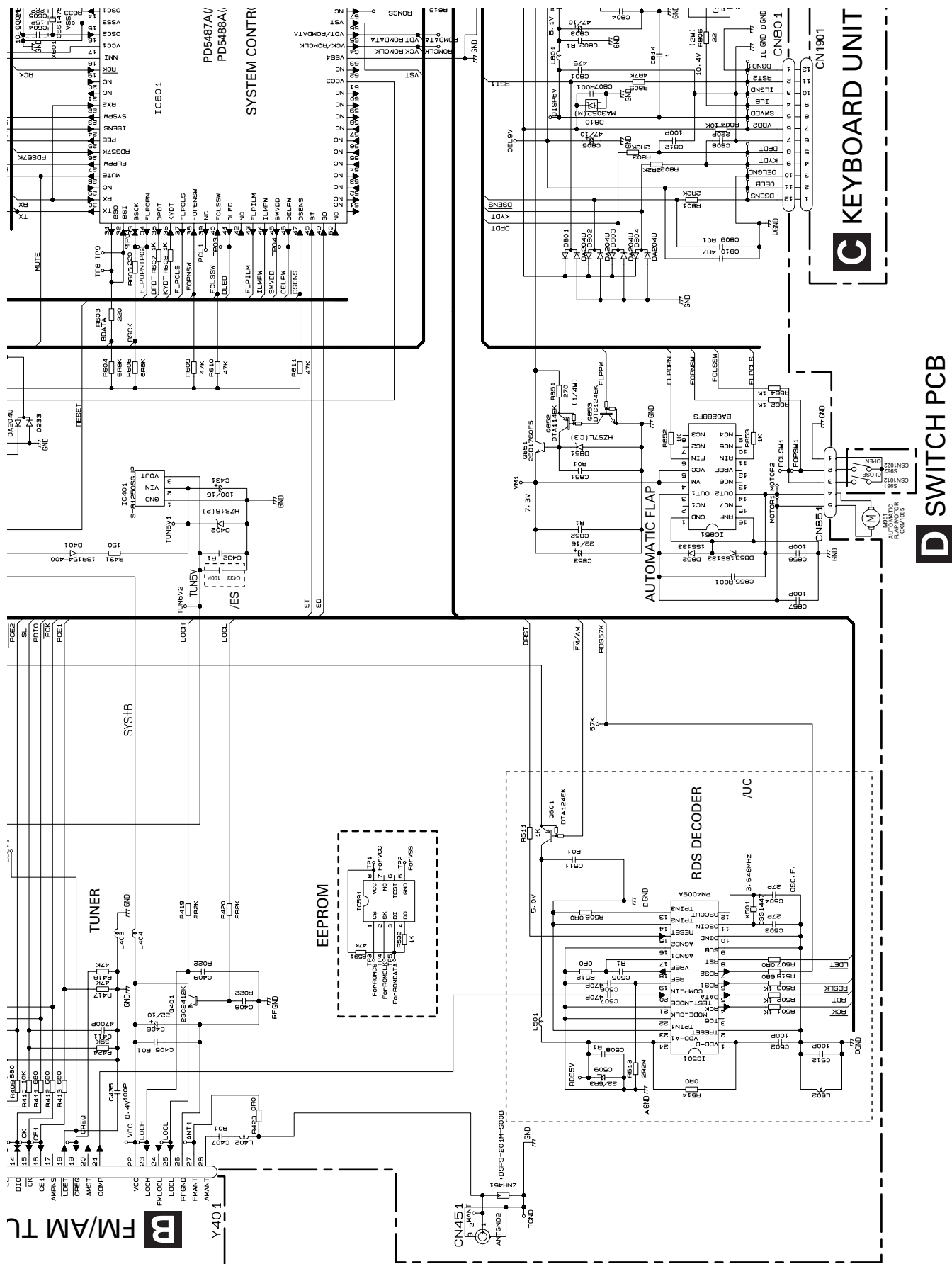
EF CD MECHANISM MODULE



C KEYB

D SWITCH PCB





A-a A-b

A


B


C

D



Decimal points for resistor and capacitor fixed values are expressed as:
2.2→2R2
0.022→R022

 Symbol indicates a resistor.
No differentiation is made between chip resistors and discrete resistors.

 Symbol indicates a capacitor.
No differentiation is made between chip capacitors and discrete capacitors.

The Δ mark found on some component parts indicates the importance of the safety factor of the part. Therefore, when replacing, be sure to use parts of identical designation.

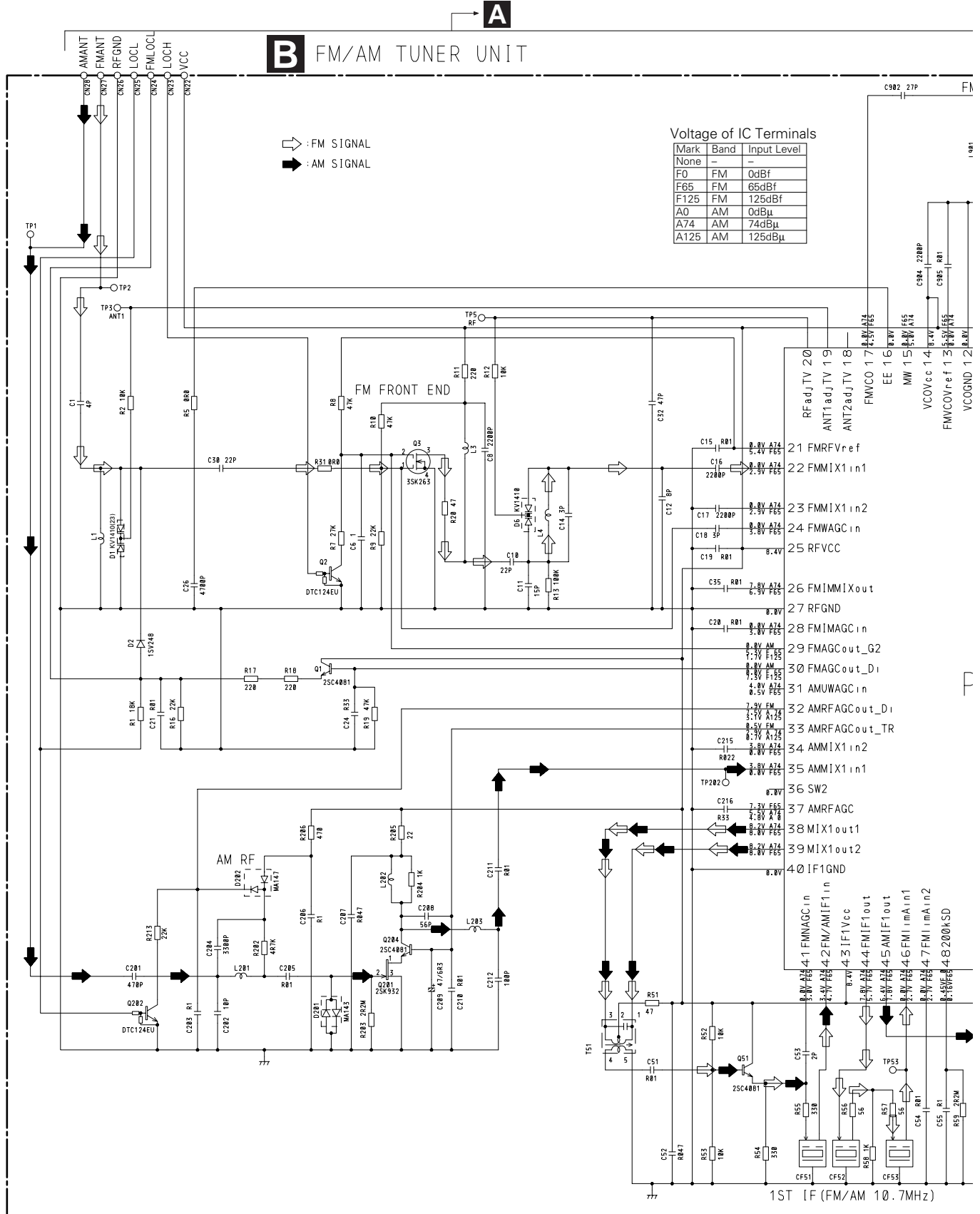
3.3 FM/AM TUNER UNIT

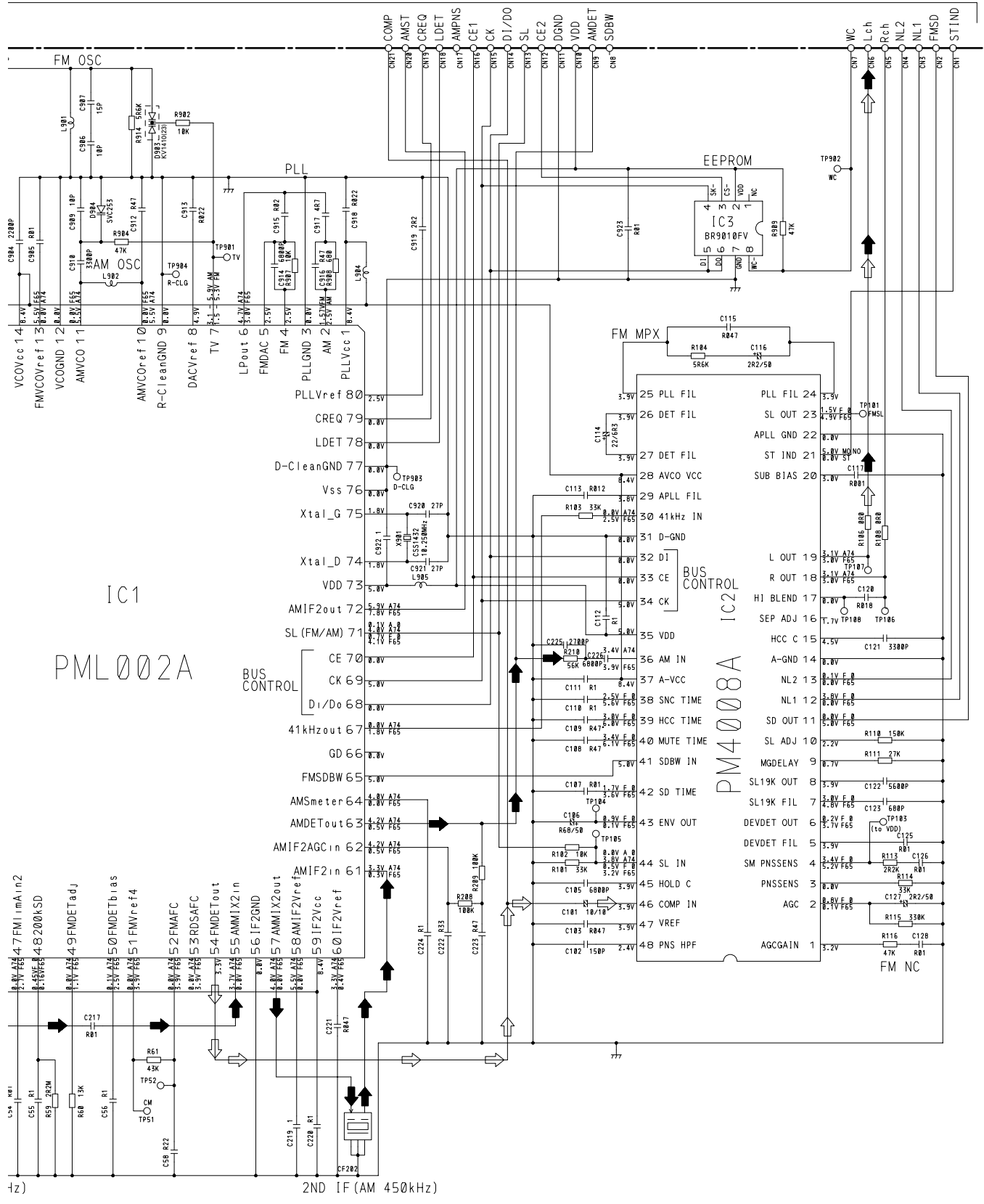
A

B

C

D





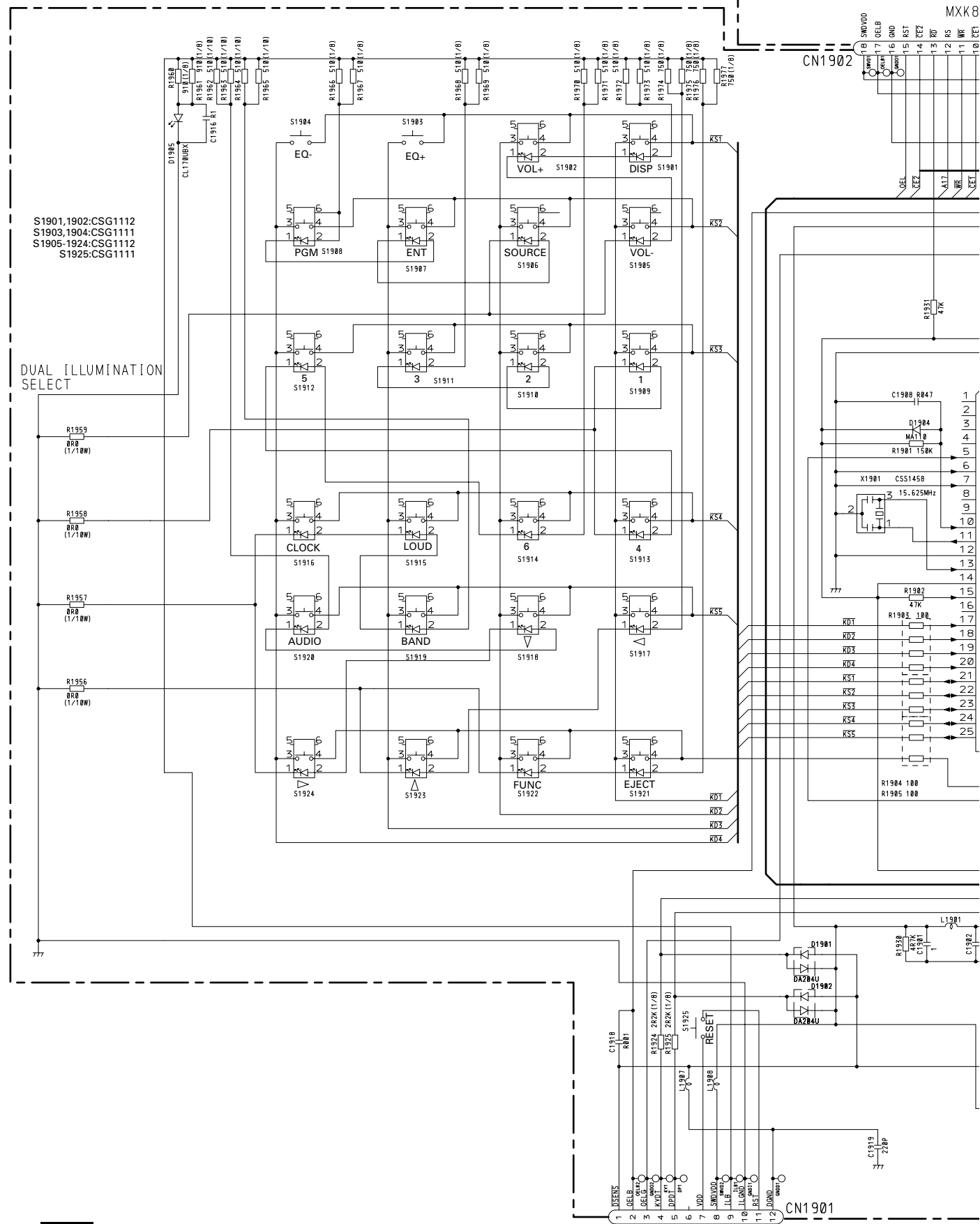
3.4 KEYBOARD UNIT

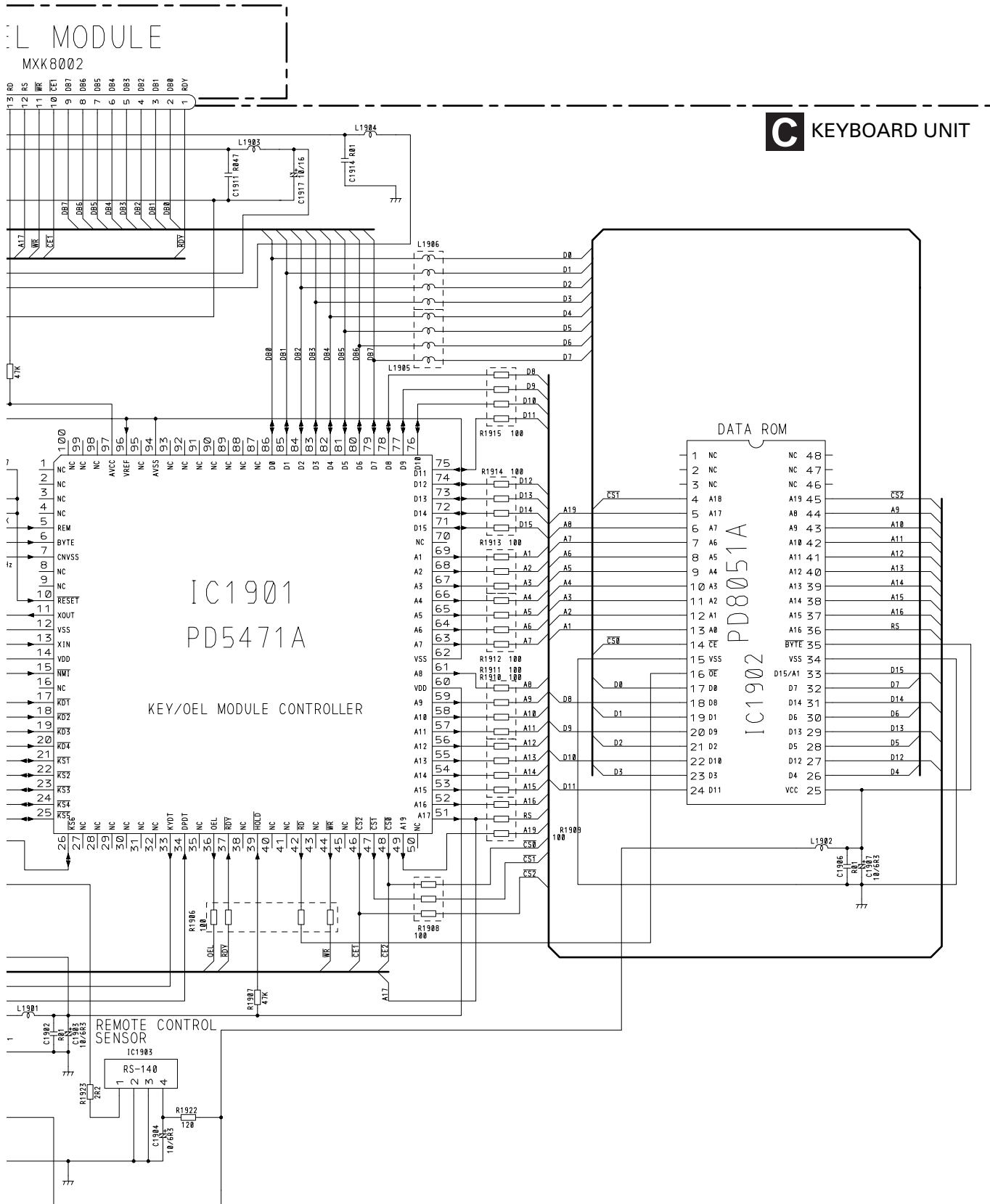
A

B

C

D





3.5 CD MECHANISM MODULE


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CONTROL UNIT

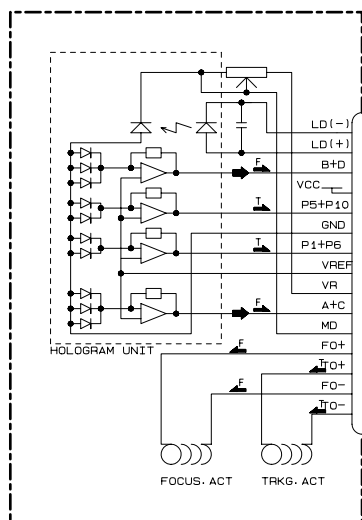
A

B

C

D

PICKUP UNIT(SERVICE)



SIGNAL LINE
 FOCUS SERVO LINE
 TRACKING SERVO LINE
 CARRIAGE SERVO LINE
 SPINDLE SERVO LINE

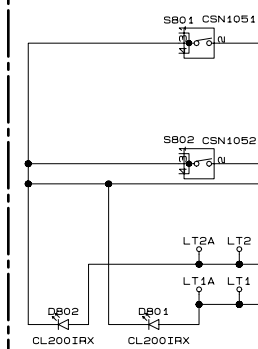
SWITCHES:

CONTROL UNIT

S801 : HOME SWITCH.....ON-OFF

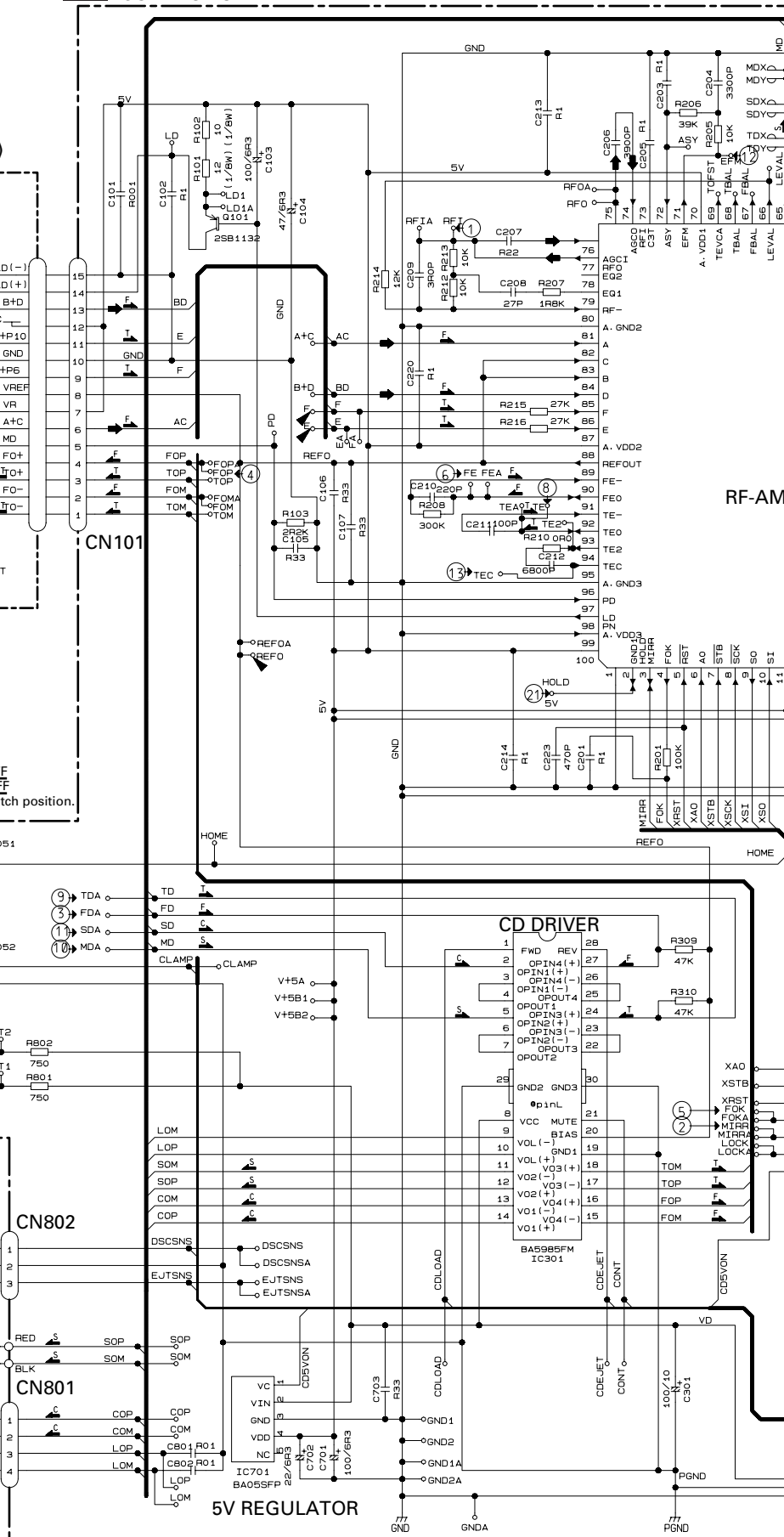
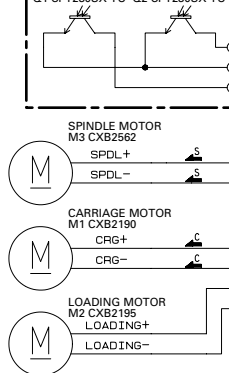
S802 : CLAMP SWITCH.....ON-OFF

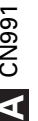
The underlined indicates the switch position.



F PHOTO UNIT

Q1 CPT230SX-TU Q2 CPT230SX-TU



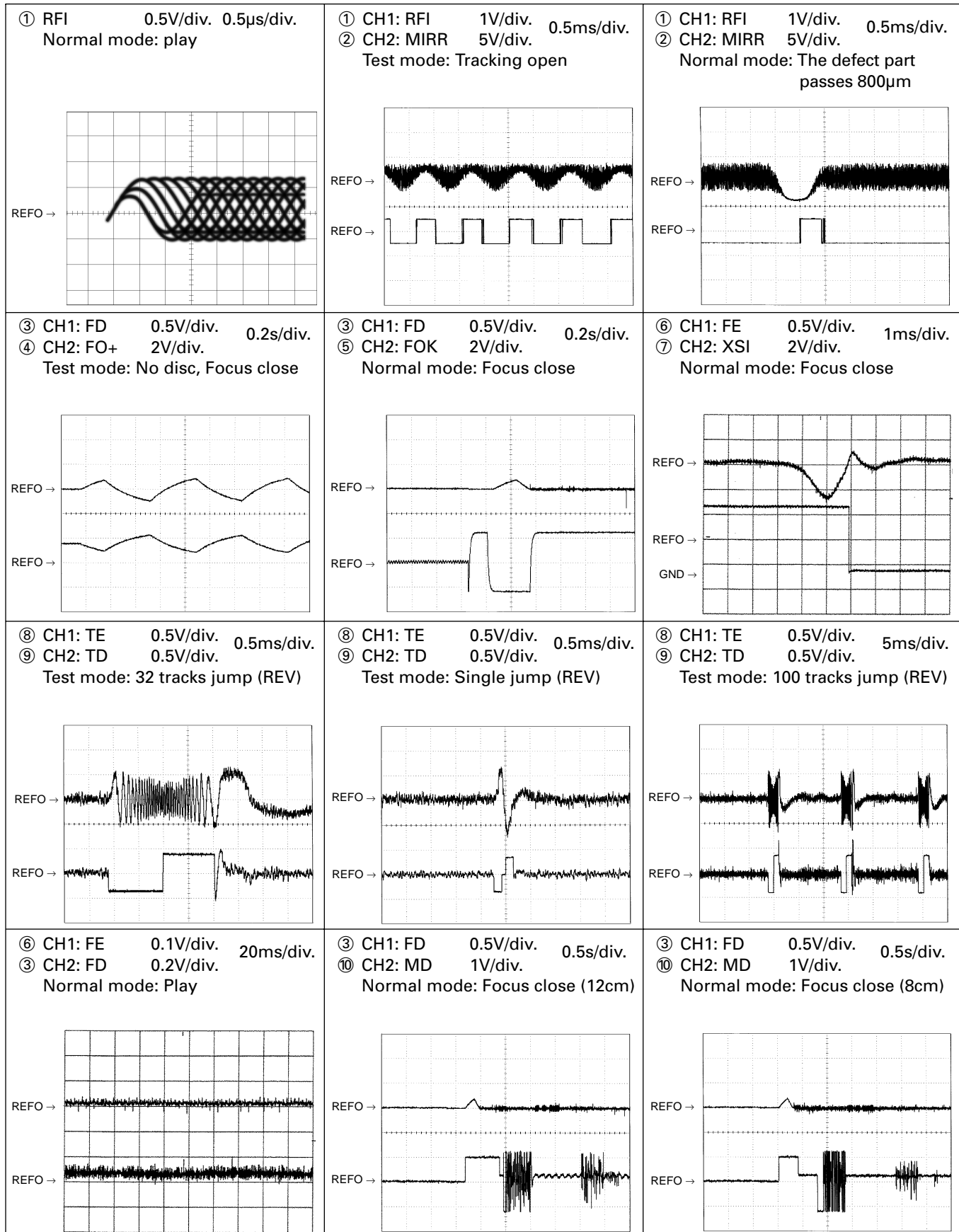


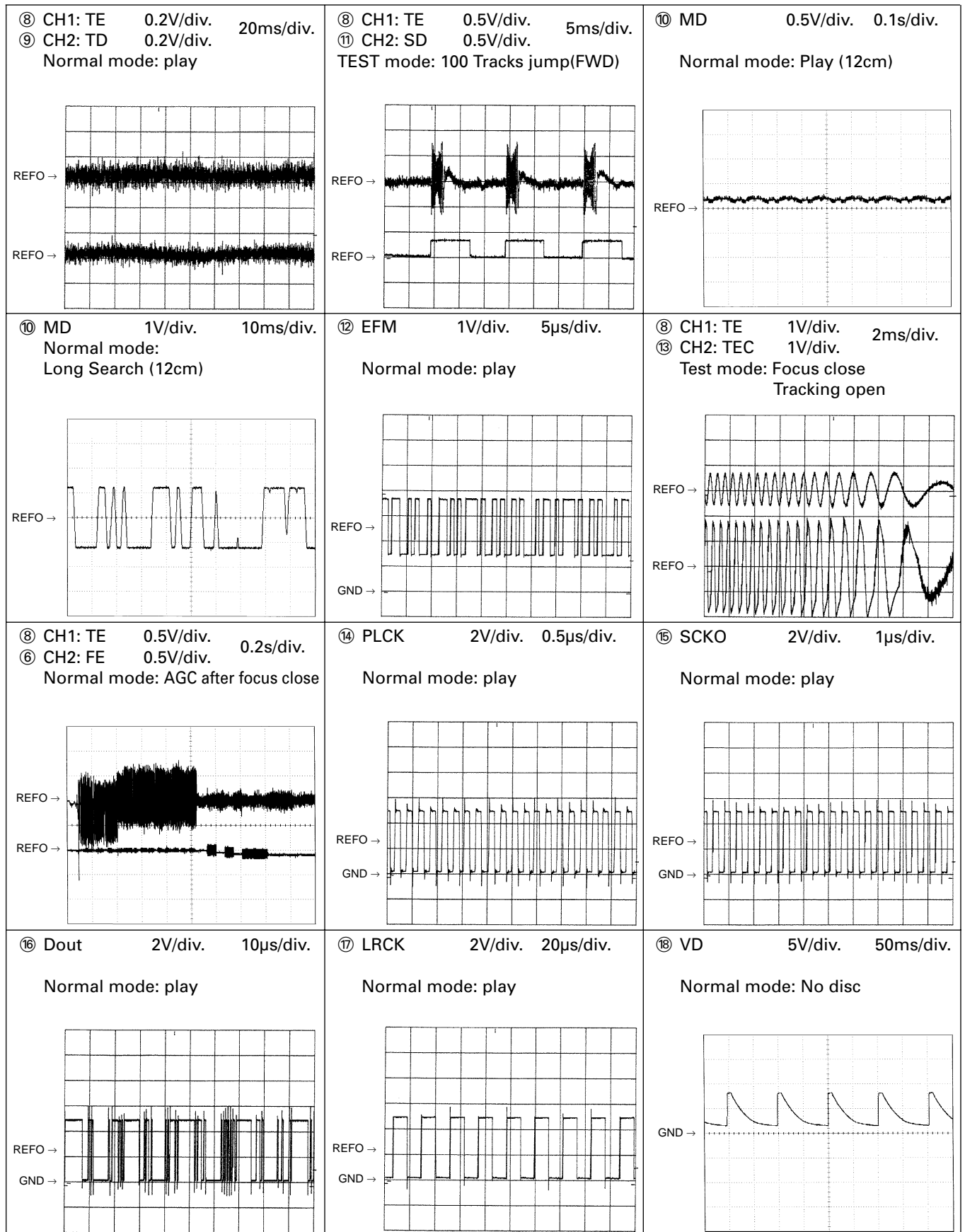
Note:1. The encircled numbers denote measuring points in the circuit diagram.

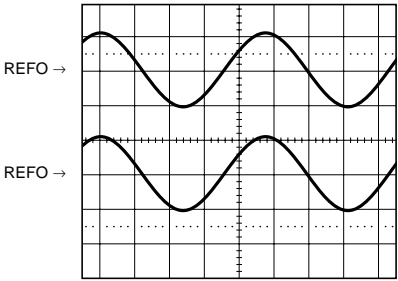
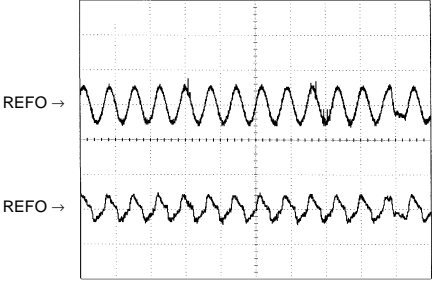
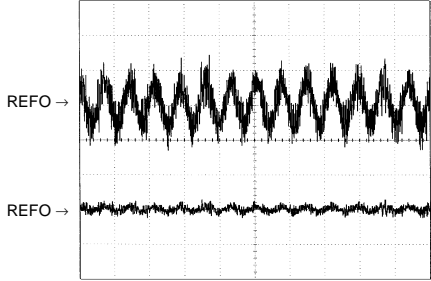
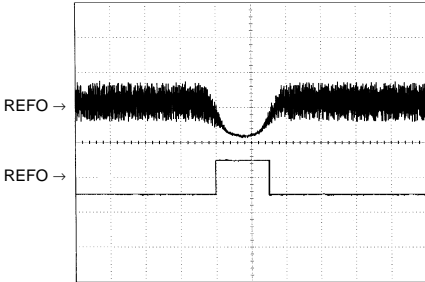
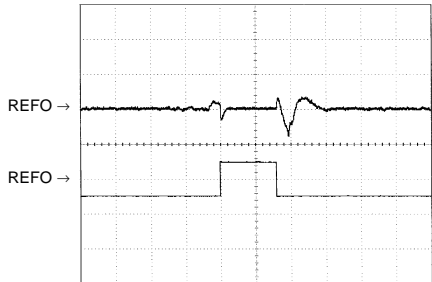
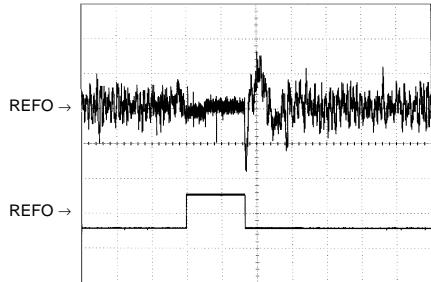
2. Reference voltage

REFO:2.5V

● Waveforms





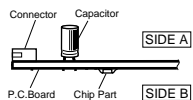
<div><div><div>⑰ CH1: R OUT 1V/div. 0.2ms/div.</div><div>⑳ CH2: L OUT 1V/div.</div><div>Normal mode: Play (1kHz 0dB)</div></div><div></div></div>	<div><div><div>⑥ CH1: FE 0.2V/div. 1ms/div.</div><div>③ CH2: FD 0.5V/div.</div><div>Normal mode: During AGC</div></div><div></div></div>	<div><div><div>⑧ CH1: TE 0.2V/div. 1ms/div.</div><div>⑨ CH2: TD 0.5V/div.</div><div>Normal mode: During AGC</div></div><div></div></div>
<div><div><div>① CH1: RFI 1V/div. 0.5ms/div.</div><div>② CH2: HOLD 5V/div.</div><div>Normal mode: The defect part passes 800μm(B.D)</div></div><div></div></div>	<div><div><div>③ CH1: FD 1V/div. 0.5ms/div.</div><div>② CH2: HOLD 5V/div.</div><div>Normal mode: The defect part passes 800μm(B.D)</div></div><div></div></div>	<div><div><div>⑨ CH1: TD 0.1V/div. 0.5ms/div.</div><div>② CH2: HOLD 5V/div.</div><div>Normal mode: The defect part passes 800μm(B.D)</div></div><div></div></div>

4. PCB CONNECTION DIAGRAM

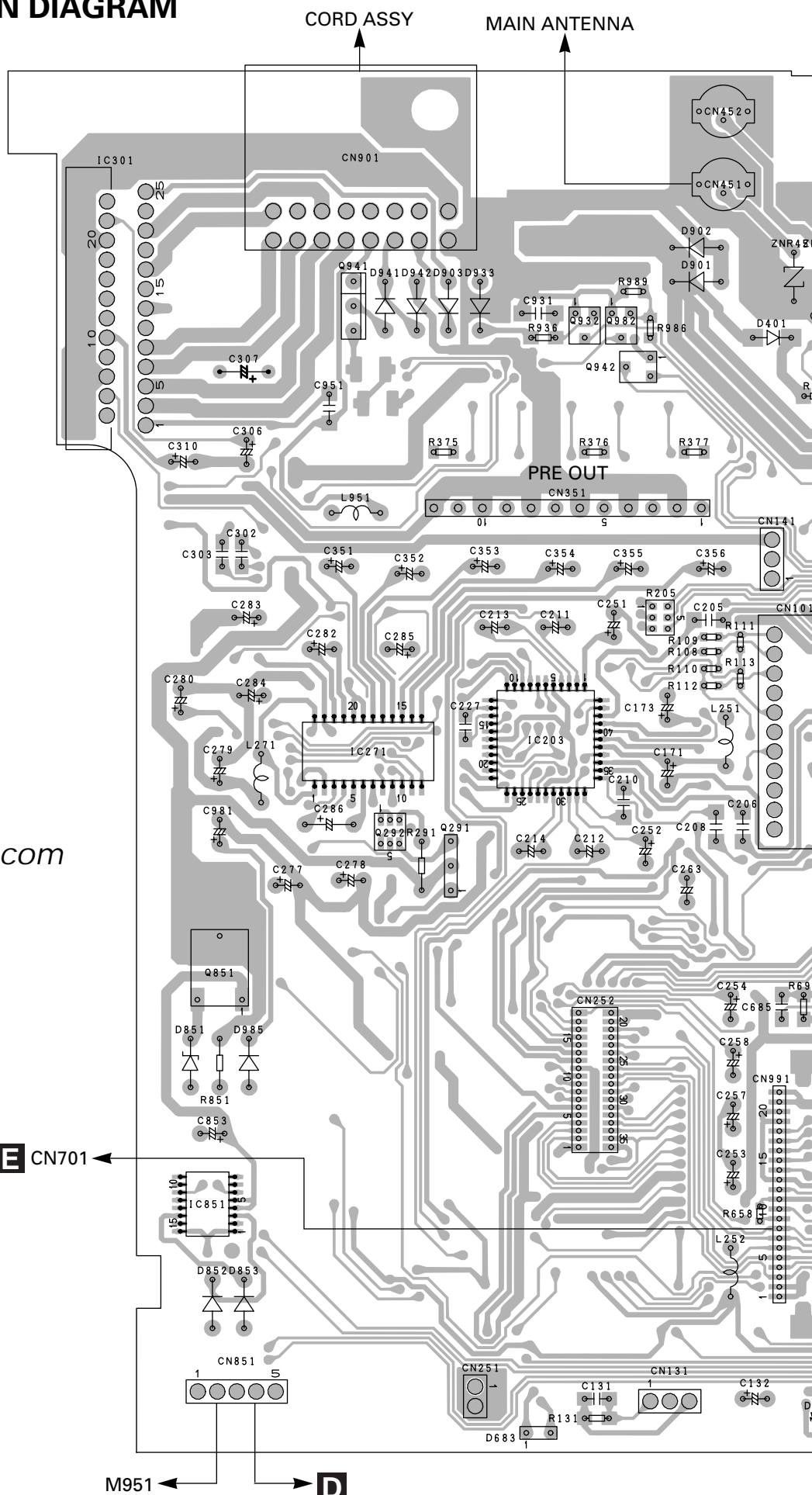
4.1 TUNER AMP UNIT

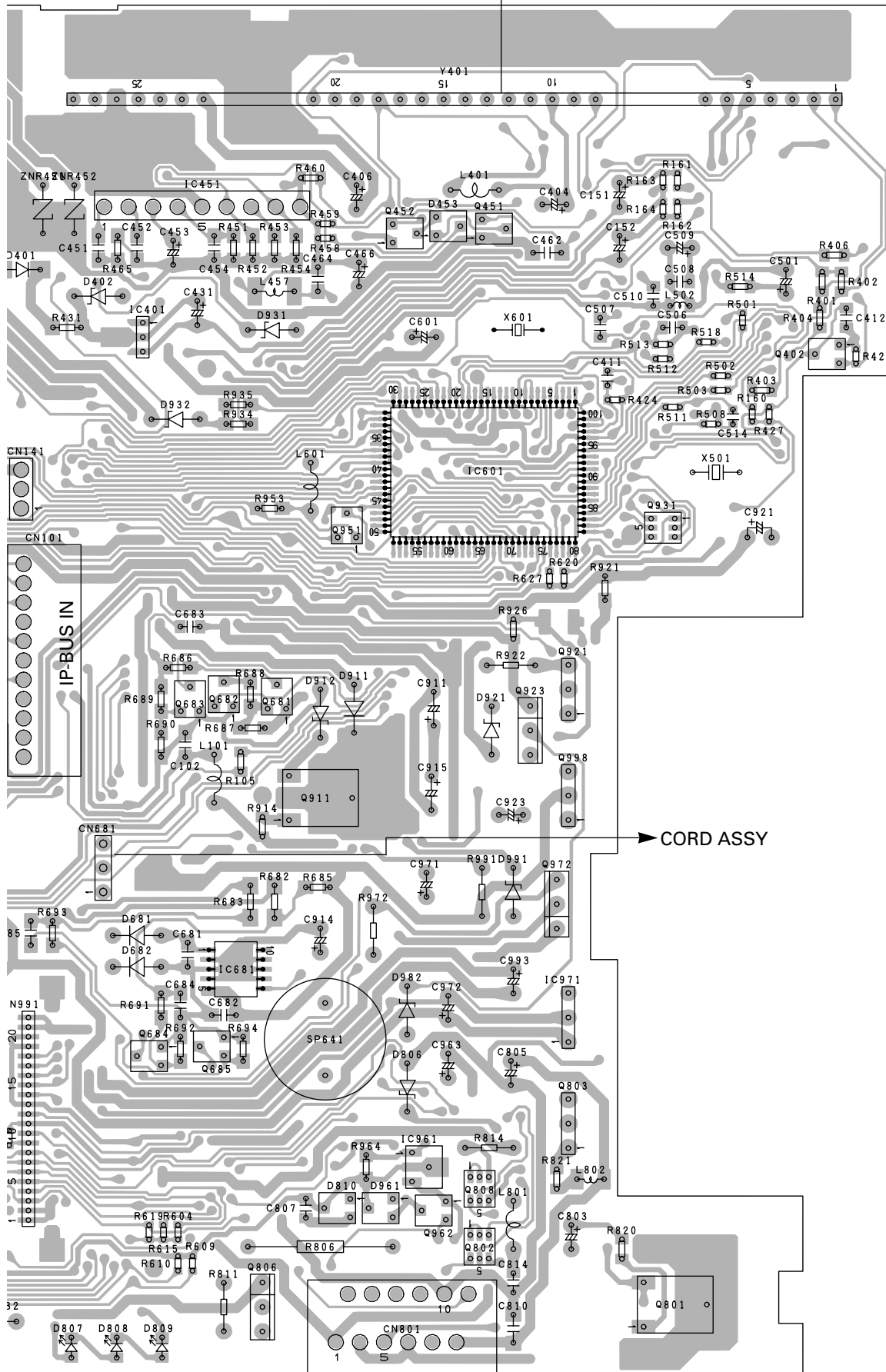
NOTE FOR PCB DIAGRAMS

1. The parts mounted on this PCB include all necessary parts for several destination.
For further information for respective destinations, be sure to check with the schematic diagram.
2. Viewpoint of PCB diagrams



A TUNER AMP UNIT



B**SIDE A**

IC301

IC451

Q941 Q451 Q452

Q932 Q982

Q942

IC401

Q402

IC601

Q931

Q951

Q921

IC203 IC271

Q923 Q682 Q681 Q683

Q291 Q998 Q292

Q911

Q972

Q851

IC681

IC971

Q684

Q685

Q803

IC851

IC961

Q808

Q962

Q802

Q806

Q801

C

CN1901

A

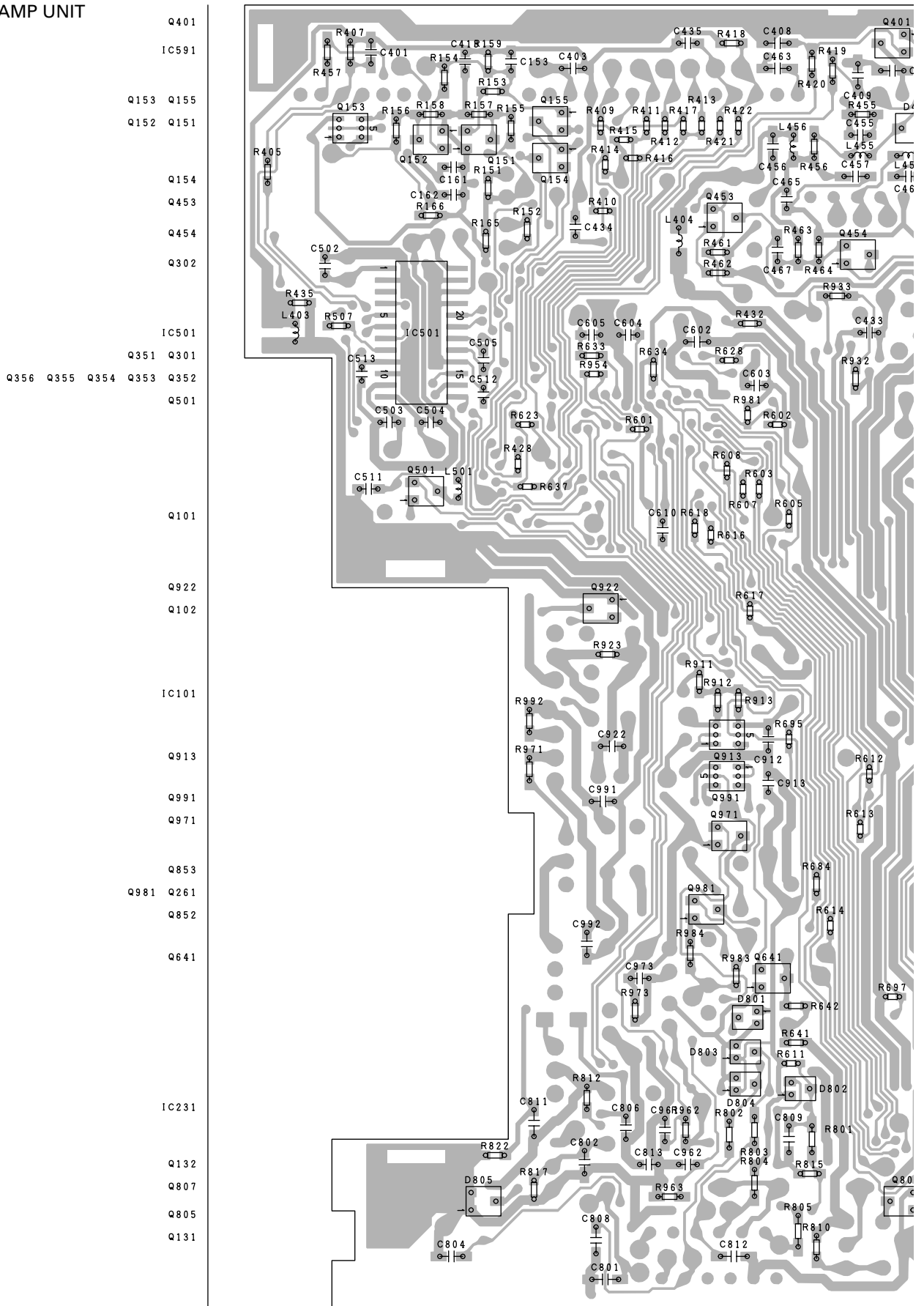
A TUNER AMP UNIT

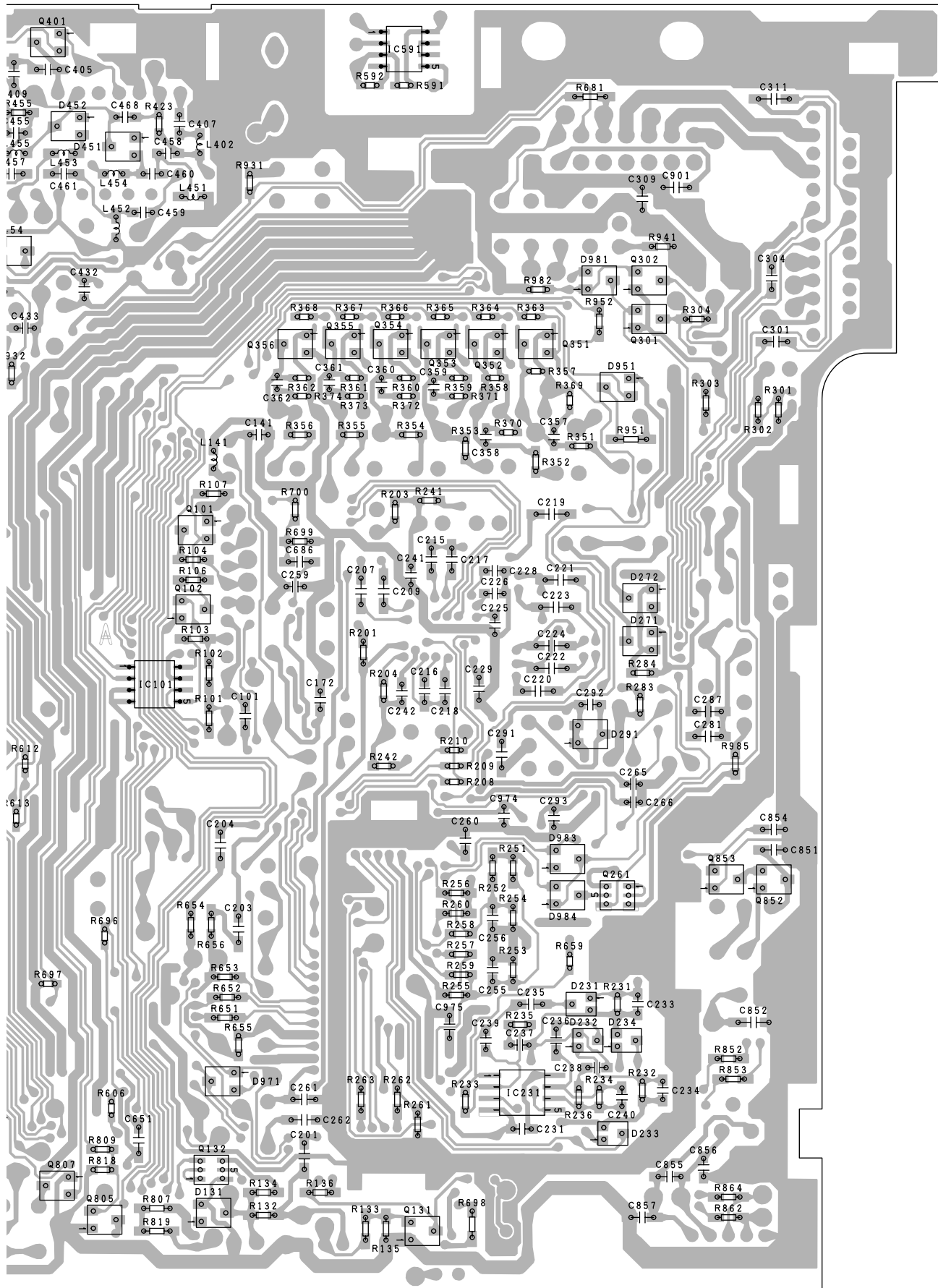
A

B

C

D



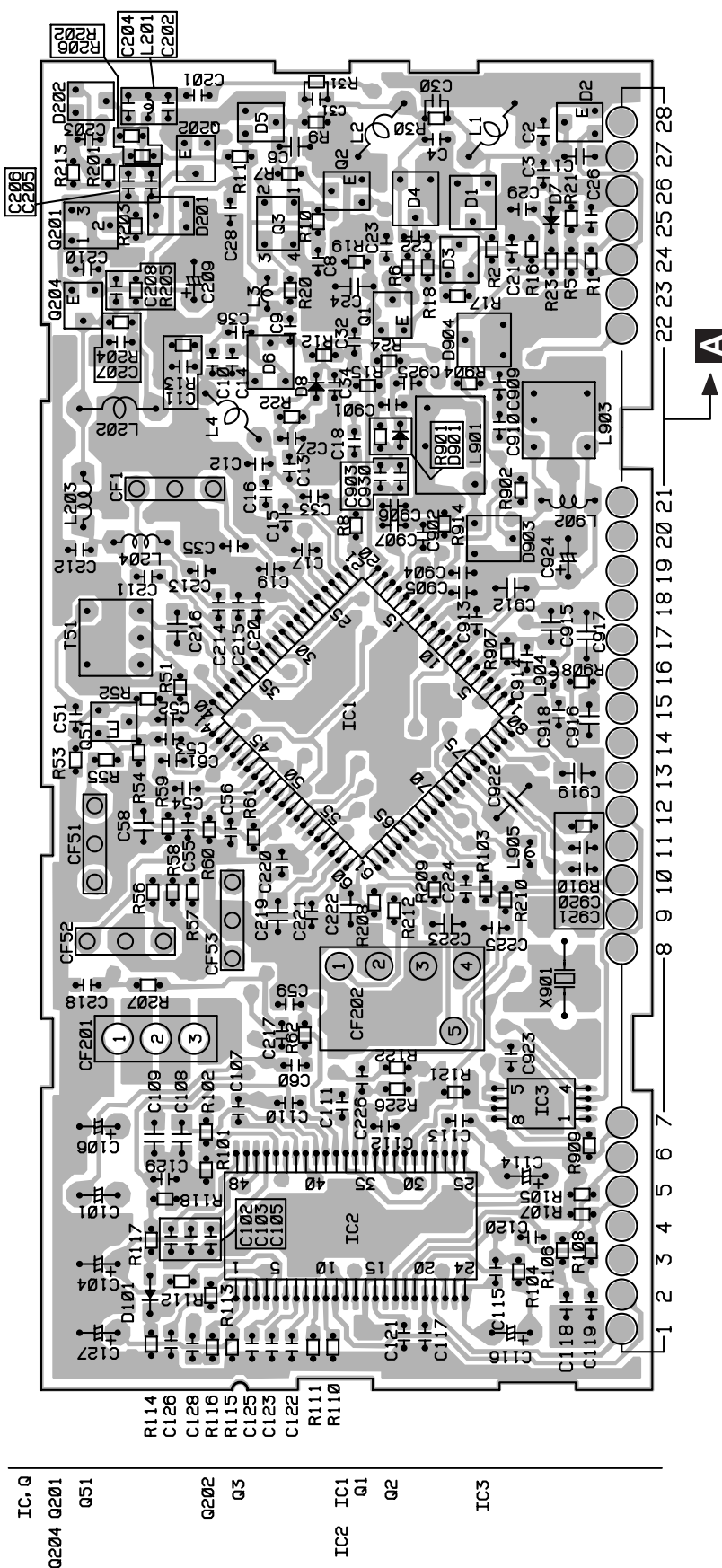


4.2 FM/AM TUNER UNIT

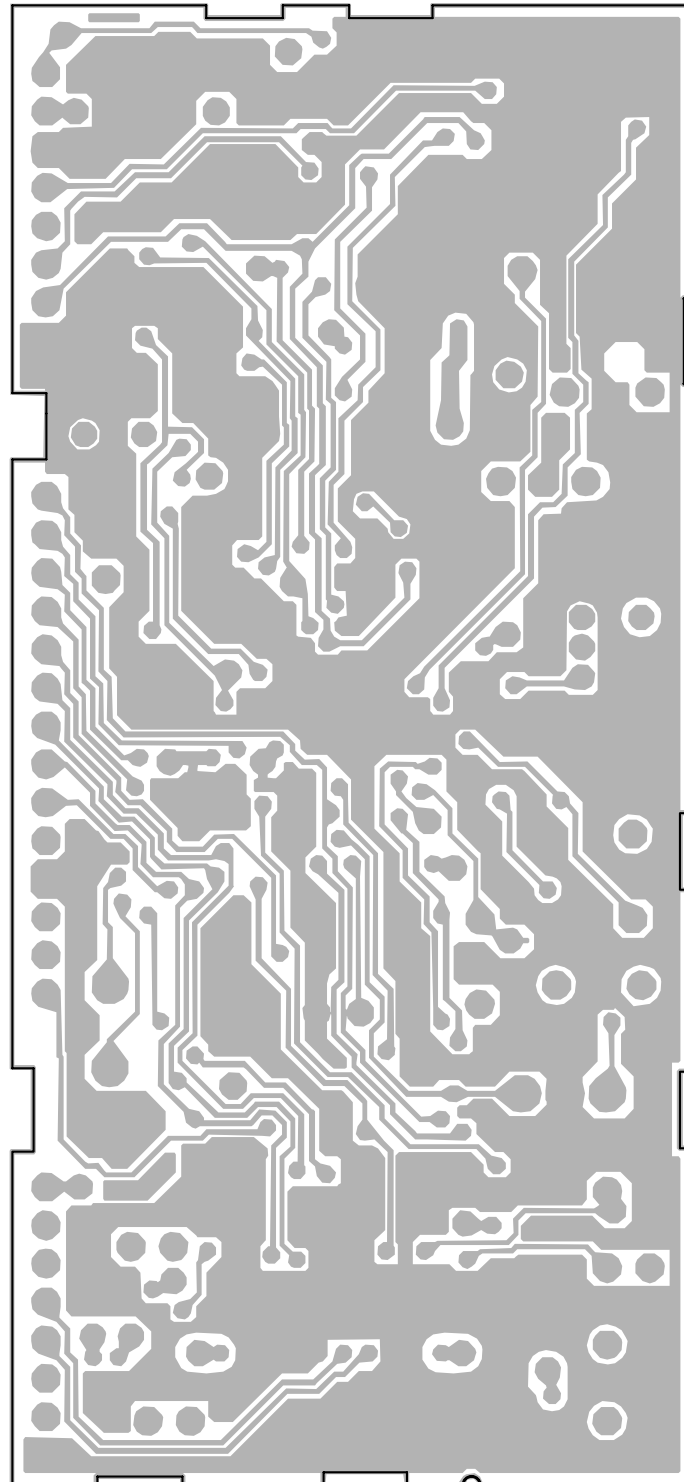
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SIDE A

FM/AM TUNER UNIT



SIDE B

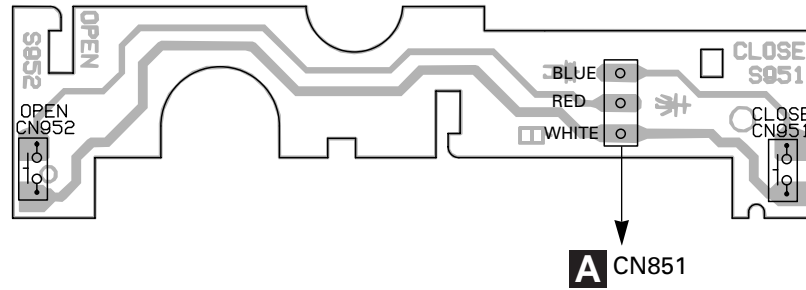


B FM/AM TUNER UNIT

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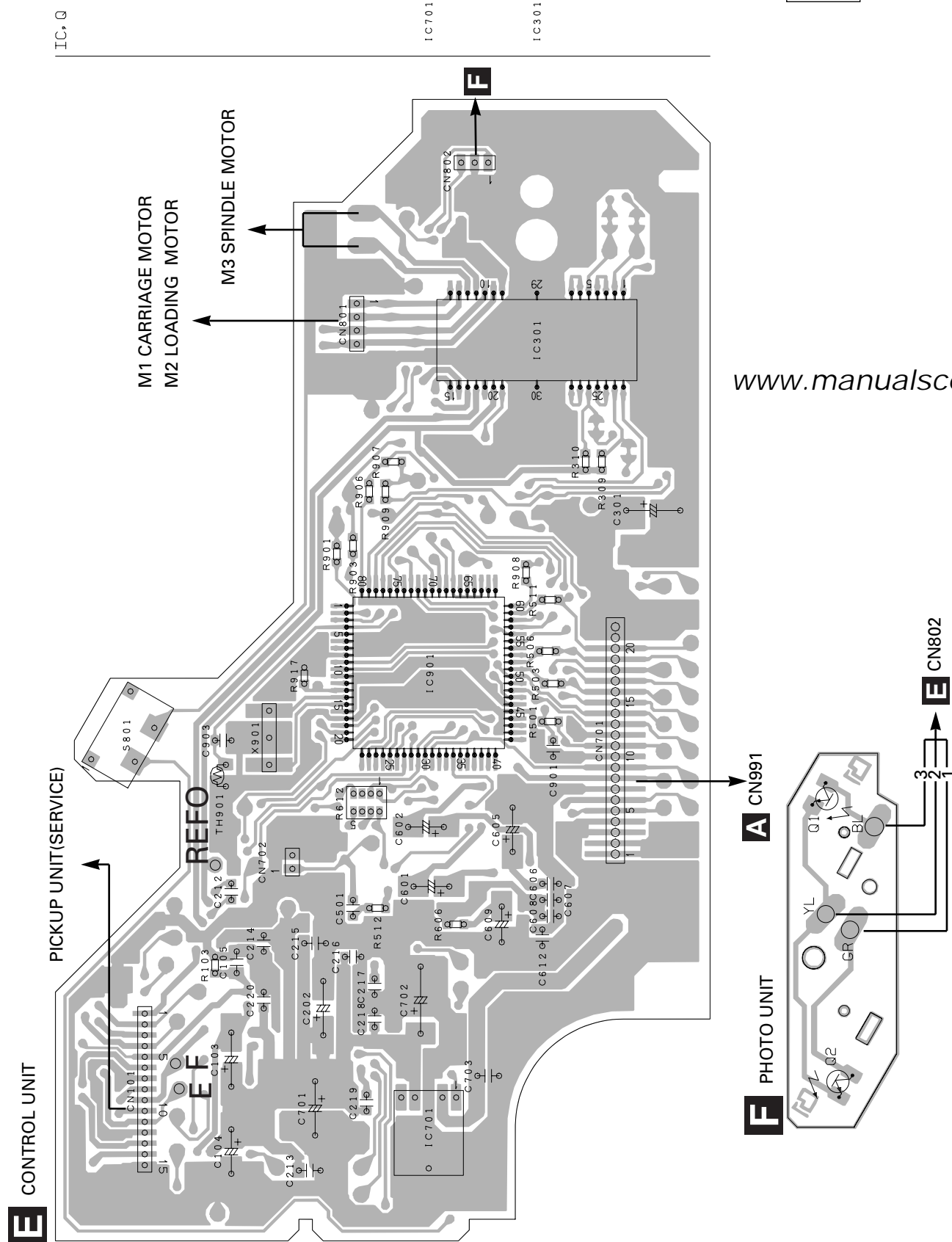
4.4 SWITCH PCB

F SWITCH PCB



E F

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SIDE B

IC₅₀

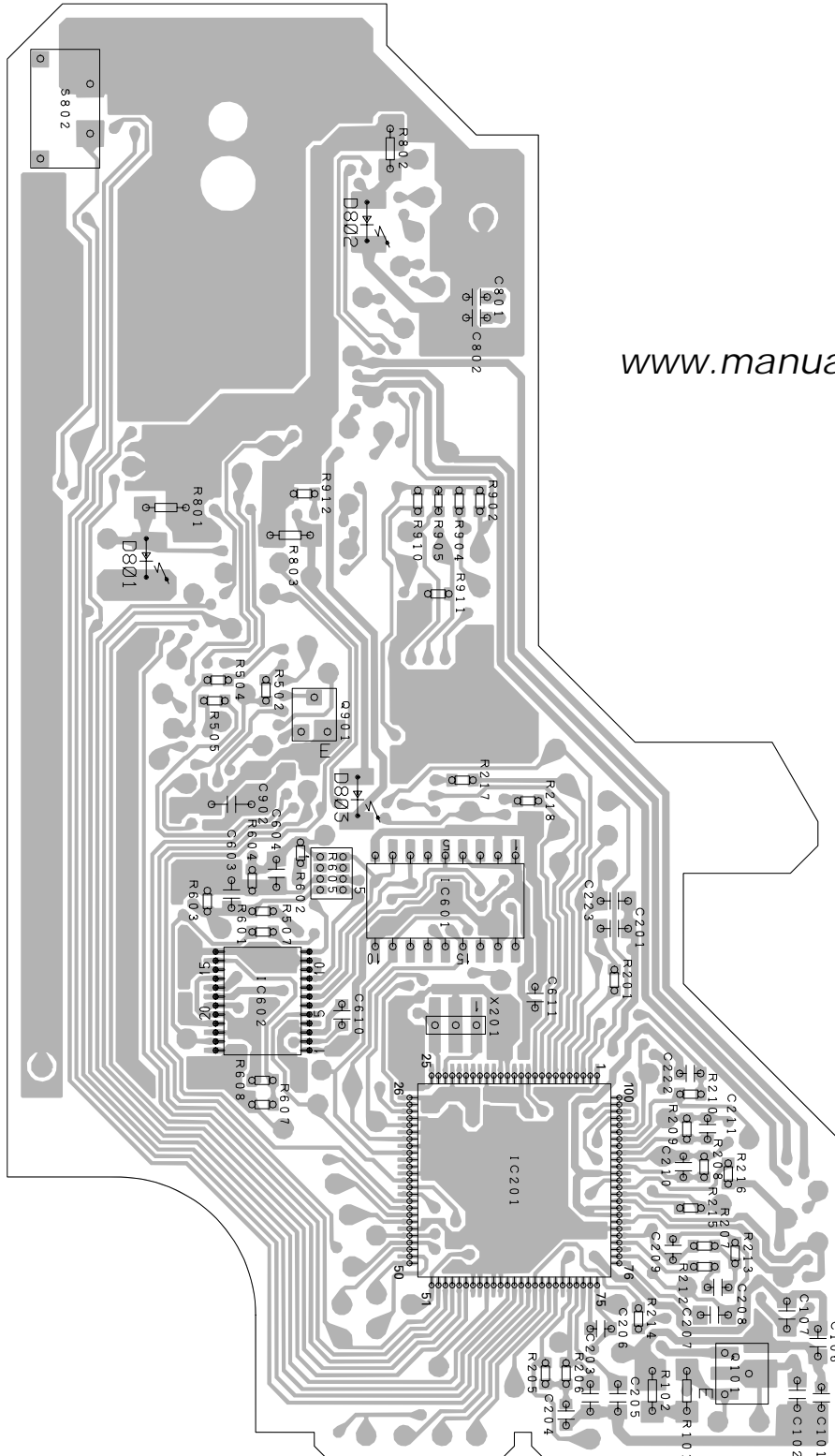
Q101

1C201

IC601

Q901

IC602



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CONTROL UNIT

5. ELECTRICAL PARTS LIST

NOTES:

- Parts whose parts numbers are omitted are subject to being not supplied.
- The part numbers shown below indicate chip components.

Chip Resistor

RS1/○S○○○○J,RS1/○○S○○○○J

Chip Capacitor (except for CQS.....)

CKS....., CCS....., CSZS.....

====Circuit Symbol and No.====Part Name	Part No.	====Circuit Symbol and No.====Part Name	Part No.
A Unit Number : CWM6222(DEH-P8000R/UC)		Q 981 Transistor	2SC2412K
Unit Number : CWM6224(DEH-P8050/ES)		Q 982 Transistor	2SC2412K
Unit Name : Tuner Amp Unit		Q 991 Transistor	IMD2A
		Q 998 Transistor	2SD2396
		D 231 Diode Network	DA204U
MISCELLANEOUS			
IC 101 IC	CA0008AM	D 232 Diode Network	DA204U
IC 203 IC	PML004AF	D 233 Diode Network	DA204U
IC 231 IC	NJM2068MD	D 234 Diode Network	DA204U
IC 271 IC	PA2028A	D 401 Diode	1SR154-400
IC 301 IC	PAL005A	D 402 Diode	HZS16(2)
IC 401 IC	S-81250SGUP	D 683 LED	BR4361F
IC 501 IC	See Contrast table	D 801 Diode Network	DA204U
IC 601 IC	See Contrast table	D 802 Diode Network	DA204U
IC 851 IC	BA6288FS	D 803 Diode Network	DA204U
IC 961 IC	S-80735ANDZI	D 804 Diode Network	DA204U
Q 101 Transistor	2SA1162	D 805 Diode	MA3056(M)
Q 102 Transistor	DTC124EK	D 806 Diode	HZS9L(C2)
Q 261 Transistor	IMD2A	D 807 LED	CL170PGCD
Q 301 Transistor	DTC124EK	D 808 LED	CL170PGCD
Q 302 Transistor	DTC124EK	D 809 LED	CL170PGCD
Q 351 Transistor	2SC3326	D 810 Diode	MA3062(M)
Q 352 Transistor	2SC3326	D 851 Diode	HZS7L(C3)
Q 353 Transistor	2SC3326	D 852 Diode	1SS133
Q 354 Transistor	2SC3326	D 853 Diode	1SS133
Q 355 Transistor	See Contrast table	D 901 Diode	ERA15-02VH
Q 356 Transistor	See Contrast table	D 902 Diode	ERA15-02VH
Q 401 Transistor	2SC2412K	D 903 Diode	ERA15-02VH
Q 501 Transistor	See Contrast table	D 911 Diode	ERA15-02VH
Q 641 Transistor	DTC114EK	D 912 Diode	HZS6L(B1)
Q 681 Transistor	2SA1162	D 921 Diode	HZS9L(C1)
Q 682 Transistor	DTC124EK	D 931 Diode	HZS7L(A1)
Q 683 Transistor	2SC2412K	D 932 Diode	HZS7L(C3)
Q 684 Transistor	See Contrast table	D 933 Diode	ERA15-02VH
Q 685 Transistor	See Contrast table	D 941 Diode	ERA15-02VH
Q 801 Transistor	2SD1760F5	D 942 Diode	ERA15-02VH
Q 802 Transistor	IMD2A	D 951 Diode	MA152WK
Q 803 Transistor	2SD2396	D 961 Diode	MA152K
Q 805 Transistor	2SC2412K	D 981 Diode	MA152WK
Q 806 Transistor	2SB1238	D 982 Diode	HZS9L(A2)
Q 807 Transistor	DTC143EK	D 983 Diode	MA152K
Q 808 Transistor	IMD2A	D 984 Diode	MA152WK
Q 851 Transistor	2SD1760F5	D 985 Diode	1SS133
Q 852 Transistor	DTA114EK	D 991 Diode	HZS9L(B1)
Q 853 Transistor	DTC124EK	ZNR 451	DSPS-201M-S00B
Q 911 Transistor	2SD1760F5	L 101 Inductor	LAU3R3K
Q 913 Transistor	IMD2A	L 251 Ferri-Inductor	LAU2R2K
Q 921 Transistor	2SD2396	L 271 Ferri-Inductor	LAU101K
Q 922 Transistor	DTC114EK	L 401 Ferri-Inductor	LAU2R2K
Q 923 Transistor	2SB1238	L 402 Inductor	LCTB4R7K2125
Q 931 Transistor	IMX1	L 403 Inductor	CTF1420
Q 932 Transistor	DTC114EK	L 404 Inductor	LCTA1R0J3225
Q 941 Transistor	2SB1243	L 501 Inductor	See Contrast table
Q 942 Transistor	DTC124EK	L 502 Inductor	See Contrast table
Q 951 Transistor	2SA1162	L 601 Inductor	LAU100K
Q 962 Transistor	2SC2412K	L 801 Inductor	LAU100K

====Circuit Symbol and No.==Part Name	Part No.	====Circuit Symbol and No.==Part Name	Part No.
L 802 Inductor	CTF1484	R 371	RS1/16S471J
L 951 Ferri-Inductor	LAU2R2K	R 372	RS1/16S471J
X 501 Crystal Resonator 3.648MHz	See Contrast table	R 373	See Contrast table
X 601 Radiator 10.00MHz	CSS1475	R 374	See Contrast table
SP 641 Buzzer	CPV1012	R 375	RS1/10S0R0J
FM/AM Tuner Unit	CWE1501	R 376	RS1/10S0R0J
		R 377	See Contrast table
		R 401	RS1/10S473J
		R 402	RS1/10S473J
		R 403	RS1/10S681J
		R 404	RS1/10S681J
		R 409	RS1/16S681J
		R 410	RS1/16S103J
		R 411	RS1/16S681J
		R 412	RS1/16S681J
		R 413	RS1/16S681J
		R 414	RS1/16S473J
		R 415	RS1/16S472J
		R 416	RS1/16S473J
		R 417	RS1/16S473J
		R 418	RS1/10S473J
		R 419	RS1/10S222J
		R 420	RS1/10S222J
		R 423	RS1/10S0R0J
		R 424	RS1/16S393J
		R 431	RS1/8S151J
		R 501	See Contrast table
		R 502	See Contrast table
		R 503	See Contrast table
		R 507	See Contrast table
		R 508	See Contrast table
		R 511	See Contrast table
		R 512	See Contrast table
		R 513	See Contrast table
		R 514	See Contrast table
		R 518	See Contrast table
		R 591	RS1/16S473J
		R 592	RS1/16S102J
		R 601	RS1/16S473J
		R 602	RS1/16S472J
		R 603	RS1/16S221J
		R 604	RS1/16S682J
		R 605	RS1/16S221J
		R 606	RS1/16S682J
		R 607	RS1/16S102J
		R 608	RS1/16S102J
		R 609	RS1/16S473J
		R 610	RS1/16S473J
		R 611	RS1/16S473J
		R 614	RS1/16S221J
		R 615	RS1/16S682J
		R 616	RS1/16S221J
		R 617	RS1/16S473J
		R 618	RS1/16S221J
		R 619	RS1/16S682J
		R 620	RS1/16S473J
		R 623	RS1/16S473J
		R 627	RS1/16S473J
		R 628	RS1/16S473J
		R 633	RS1/10S0R0J
		R 634	RS1/10S102J
		R 637	RS1/16S473J
		R 641	RS1/10S202J
		R 642	RS1/10S102J
		R 654	RS1/10S0R0J

RESISTORS

R 101
R 102
R 103
R 104
R 105

RS1/10S101J
RS1/10S620J
RS1/10S101J
RS1/10S222J
RS1/10S103J

R 106
R 107
R 108
R 109
R 110

RS1/10S562J
RS1/10S332J
RS1/16S102J
RS1/16S102J
RS1/16S223J

R 111
R 112
R 113
R 151
R 152

RS1/16S223J
RS1/16S181J
RS1/16S181J
RS1/10S0R0J
RS1/10S0R0J

R 161
R 162
R 163
R 164
R 201

RS1/16S272J
RS1/16S272J
RS1/16S162J
RS1/16S162J
RS1/10S0R0J

R 203
R 204
R 205
R 231
R 232

RS1/10S102J
RS1/10S102J
RA3C102J
RS1/10S474J
RS1/10S474J

R 233
R 234
R 235
R 236
R 283

RS1/10S104J
RS1/10S104J
RS1/10S273J
RS1/10S273J
RS1/10S203J

R 284
R 301
R 302
R 303
R 304

RS1/10S0R0J
RS1/10S103J
RS1/10S103J
RS1/10S103J
RS1/10S331J

R 351
R 352
R 353
R 354
R 355

RS1/10S820J
RS1/10S820J
RS1/10S820J
RS1/10S820J
See Contrast table

R 356
R 357
R 358
R 359
R 360

See Contrast table
RS1/16S223J
RS1/16S223J
RS1/16S223J
RS1/16S223J

R 361
R 362
R 363
R 364
R 365

See Contrast table
See Contrast table
RS1/16S103J
RS1/16S103J
RS1/16S103J

R 366
R 367
R 368
R 369
R 370

RS1/16S103J
See Contrast table
See Contrast table
RS1/16S471J
RS1/16S471J

====Circuit Symbol and No.==Part Name	Part No.	====Circuit Symbol and No.==Part Name	Part No.
R 655	RS1/10S0R0J	R 953	RS1/10S472J
R 656	RS1/10S0R0J	R 954	RS1/16S102J
R 658	RS1/16S473J	R 962	RS1/10S102J
R 659	RS1/16S0R0J	R 963	RS1/10S473J
R 681	RS1/8S102J	R 964	RS1/10S822J
R 682	See Contrast table	R 981	RS1/16S223J
R 683	See Contrast table	R 982	RS1/10S473J
R 685	See Contrast table	R 983	RS1/10S103J
R 686	RS1/10S103J	R 984	RS1/10S473J
R 687	RS1/10S223J	R 985	RS1/10S102J
R 688	RS1/10S223J	R 986	RS1/10S224J
R 689	RS1/10S223J	R 989	RS1/10S473J
R 690	RS1/10S272J	R 991	RD1/4PU221J
R 691	See Contrast table	R 992	RS1/10S221J
R 692	See Contrast table		
R 693	See Contrast table	CAPACITORS	
R 694	See Contrast table	C 101	CKSQYB104K16
R 695	RS1/16S473J	C 102	CKSQYB104K16
R 696	See Contrast table	C 161	CKSQYB183K25
R 697	See Contrast table	C 162	CKSQYB183K25
R 698	RS1/8S471J	C 171	CEJA470M16
R 699	RS1/10S102J		
R 700	RS1/10S103J	C 172	CKSQYB104K16
R 801	RS1/8S222J	C 173	CEJA100M16
R 802	RS1/8S222J	C 203	CKSYB225K16
		C 204	CKSYB225K16
R 803	RS1/8S222J	C 205	CKSYB224K16
R 804	RS1/8S103J		
R 805	RS1/8S472J	C 206	CKSYB224K16
R 806	RS2PMF220J	C 207	CKSYB105K16
R 807	RS1/8S221J	C 208	CKSYB105K16
		C 209	CKSYB105K16
R 809	RS1/10S103J	C 210	CKSYB105K16
R 810	RS1/10S222J		
R 811	RD1/4PU102J	C 211	CEJANP4R7M16
R 812	RS1/10S152J	C 212	CEJANP4R7M16
R 813	RS1/4S221J	C 213	CEJANP4R7M16
		C 214	CEJANP4R7M16
R 814	RD1/4PU391J	C 215	CKSQYB473K50
R 818	RS1/10S103J		
R 819	RS1/8S221J	C 216	CKSQYB473K50
R 820	RS1/10S1R0J	C 217	CKSQYB473K50
R 821	RS1/10S1R0J	C 218	CKSQYB473K50
		C 219	CKSYB105K16
R 851	RD1/4PU271J	C 220	CKSYB105K16
R 852	RS1/10S102J		
R 853	RS1/10S102J	C 221	CKSYB105K16
R 862	RS1/10S102J	C 222	CKSYB105K16
R 864	RS1/10S102J	C 223	CKSYB105K16
		C 224	CKSYB105K16
R 911	RS1/10S0R0J	C 225	CKSQYB333K50
R 912	RS1/10S152J		
R 913	RS1/10S512J	C 226	CKSQYB123K50
R 914	RS1/10S1R0J	C 227	CKSQYB473K50
R 921	RS1/10S1R0J	C 228	CKSQYB153K50
		C 229	CKSQYB153K50
R 922	RD1/4PU221J	C 231	CKSQYB103K50
R 923	RS1/10S102J		
R 924	RS1/4S152J	C 233	CKSQYB474K16
R 926	RS1/10S223J	C 234	CKSQYB474K16
R 931	RS1/10S472J	C 235	CKSQYB104K16
		C 236	CKSQYB104K16
R 932	RS1/10S473J	C 237	CKSQYB104K25
R 933	RS1/10S103J		
R 934	RS1/10S473J	C 238	CKSQYB104K25
R 935	RS1/10S103J	C 239	CCSQCH470J50
R 936	RS1/10S103J	C 240	CCSQCH470J50
		C 241	CKSQYB152K50
R 941	RS1/10S472J	C 242	CKSQYB152K50
R 942	RS1/4S221J		
R 943	RS1/4S221J	C 262	CKSYB475K10
R 951	RS1/8S153J	C 277	CEJA4R7M35
R 952	RS1/10S472J	C 278	CEJA101M16
		C 279	CEJA100M16
		C 280	CEJA100M16

====Circuit Symbol and No.====Part Name	Part No.	====Circuit Symbol and No.====Part Name	Part No.
C 281	CKSYB225K16	C 807	CKSQYB102K50
C 282	CEJA330M25	C 808	CKSYB221K50
C 283	CEJA330M25	C 809	CKSYB103K50
C 286	CASQA3R3M16	C 810	CKSYB475K10
C 287	CKSYB684K25	C 811	CKSYB225K16
C 301	CKSQYB224K16	C 812	CCSCH101J50
C 302	CKSQYB224K16	C 813	CKSQYB103K50
C 303	CKSQYB224K16	C 814	CKSQYB105K10
C 304	CKSQYB224K16	C 851	CKSQYB103K50
C 306	CEJA330M10	C 852	CKSYB104K16
C 307	CCH1339	C 853	CEJA220M16
C 309	CKSQYB104K16	C 855	CKSQYB102K50
C 310	CEJA100M16	C 856	CCSQCH101J50
C 311	CKSYB105K16	C 857	CCSQCH101J50
C 351	CEJA100M35	C 901	CKSYB103K50
C 352	CEJA100M35	C 911	CCH1183
C 353	CEJA100M35	C 912	CKSQYB472K50
C 354	CEJA100M35	C 913	CKSQYB103K50
C 355	See Contrast table	C 914	CEJA470M10
C 356	See Contrast table	C 915	CCH1183
C 357	CKSRYB222K50	C 921	CCH1181
C 358	CKSRYB222K50	C 922	CKSQYB103K50
C 359	CKSRYB222K50	C 923	CEJA101M16
C 360	CKSRYB222K50	C 931	CKSYB105K16
C 361	See Contrast table	C 951	CKSYB103K50
C 362	See Contrast table	C 961	CKSQYB102K50
C 403	CKSQYB473K16	C 962	CKSQYB104K16
C 404	CEJA101M10	C 963	CEJA2R2M50
C 405	CKSQYB103K50	C 981	CEJA220M16
C 406	CEJA220M10	C 991	CKSQYB473K50
C 407	CKSQYB103K50	C 992	CKSQYB102K50
C 408	CKSQYB223K50	C 993	CEJA101M10
C 409	CKSQYB223K50		
C 411	CKSRYB472K50		
C 413	See Contrast table		
C 431	CEJA101M16		
C 432	CKSQYB104K16		
C 433	See Contrast table		
C 435	CCSQCH101J50		
C 502	See Contrast table		
C 503	See Contrast table		
C 504	See Contrast table		
C 505	See Contrast table		
C 506	See Contrast table		
C 507	See Contrast table		
C 508	See Contrast table		
C 509	See Contrast table		
C 511	See Contrast table		
C 512	See Contrast table		
C 601	CEJA4R7M35		
C 602	CKSQYB103K50		
C 603	CCSQCH101J50		
C 604	CCSQCH150J50		
C 605	CCSQCH220J50		
C 651	CKSYB225K16		
C 683	CKSQYB103K50		
C 684	See Contrast table		
C 685	See Contrast table		
C 686	CKSQYB473K16		
C 801	CKSYB475K10		
C 802	CKSQYB104K16		
C 803	CEJA470M10		
C 804	CKSQYB103K50		
C 805	CEJA470M10		
C 806	CKSQYB103K50		

CONTRAST TABLE of TUNER AMP UNIT

DEH-P8000R/UC and DEH-P8050/ES are constructed same except for the following:

Symbol and Description		Part No.	
		DEH-P8000R/UC	DEH-P8050/ES
IC501	IC	PM4009A	Not used
IC601	IC	PD5487A	PD5488A
Q355,356	Transistor	2SC3326	Not used
Q501	Transistor	DTA124EK	Not used
Q684,685	Transistor	Not used	2SC2412K
L501	Inductor	CTF1295	Not used
L502	Inductor	CTF1420	Not used
X501	Crystal Resonator 3.648MHz	CSS1447	Not used
R355,356		RS1/10S820J	Not used
R361,362		RS1/16S223J	Not used
R367,368		RS1/16S103J	Not used
R373,374		RS1/16S471J	Not used
R377,514		RS1/10S0R0J	Not used
R501,502,503,511		RS1/16S102J	Not used
R507		RS1/10S0R0J	Not used
R508,512		RS1/16S0R0J	Not used
R513		RS1/16S225J	Not used
R518		RS1/16S681J	Not used
R682,683		Not used	RS1/8S102J
R685		Not used	RS1/10S103J
R691,693		Not used	RS1/10S223J
R692,694		Not used	RS1/10S272J
R696,697		Not used	RS1/16S473J
C355,356		CEJA100M35	Not used
C361,362		CKSRYB222K50	Not used
C413,511		CKSQYB103K50	Not used
C433		Not used	CCSQCH101J50
C502		CCSQCH101J50	Not used
C503,504		CCSQCH270J50	Not used
C505		CKSQYB104K16	Not used
C506,507		CKSQYB471K50	Not used
C508		CKSQYB104K16	Not used
C509		CEJA220M6R3	Not used
C512		CCSRCH101J50	Not used
C684,685		Not used	CKSQYB103K50

====Circuit Symbol and No.==Part Name	Part No.	====Circuit Symbol and No.==Part Name	Part No.
B Unit Number : CWE1501			
Unit Name : FM/AM Tuner Unit			
MISCELLANEOUS			
IC 1 IC	PML002A	R 104	RS1/16S562J
IC 2 IC	PM4008A	R 106	RS1/16S0R0J
IC 3 IC	BR9010FV	R 108	RS1/16S0R0J
Q 1 Transistor	2SC4081	R 110	RS1/16S154J
Q 2 Transistor	DTC124EU	R 111	RS1/16S273J
Q 3 FET	3SK263	R 113	RS1/16S222J
Q 51 Transistor	2SC4081	R 114	RS1/16S333J
Q 201 FET	2SK932	R 115	RS1/16S334J
Q 202 Transistor	DTC124EU	R 116	RS1/16S473J
Q 204 Transistor	2SC4081	R 202	RS1/16S472J
D 1 Diode	KV1410(23)	R 203	RS1/16S225J
D 2 Diode	1SV248	R 204	RS1/16S102J
D 6 Diode	KV1410(23)	R 205	RS1/16S220J
D 201 Diode	MA143	R 206	RS1/16S471J
D 202 Diode	MA147	R 208	RS1/16S104J
D 903 Diode	KV1410(23)	R 209	RS1/16S104J
D 904 Diode	SVC253	R 210	RS1/16S563J
L 1 Coil	CTC1155	R 213	RS1/16S223J
L 3 Inductor	LCTB1R5K2125	R 902	RS1/16S103J
L 4 Coil	CTC1155	R 904	RS1/16S473J
L 201 Inductor	LCTB330K1608	R 907	RS1/16S103J
L 202 Inductor	CTF1287	R 908	RS1/16S681J
L 203 Inductor	LCTA121J3225	R 909	RS1/16S473J
L 901 Coil	CTC1154	R 914	RS1/16S562J
L 902 Inductor	LCTA3R3J3225		
L 904 Inductor	LCTBR47K1608	CAPACITORS	
L 905 Inductor	LCTBR47K1608	C 1	CCSQCH4R0C50
T 51 Coil	CTE1132	C 6	CKSQYB105K10
CF 51 Ceramic Filter	CTF1442	C 8	CKSRYB222K50
CF 52 Ceramic Filter	CTF1442	C 10	CCSRCH220J50
CF 53 Ceramic Filter	CTF1442	C 11	CCSRCH150J50
CF 202 Ceramic Filter	CTF1476	C 12	CCSRCH8R0D50
X 901 Crystal Resonator 10.250MHz	CSS1432	C 14	CCSRCJ3R0C50
		C 15	CKSRYB103K50
		C 16	CKSRYB222K50
		C 17	CKSRYB222K50
		C 18	CCSRCJ3R0C50
		C 19	CKSRYB103K50
		C 20	CKSRYB103K50
		C 21	CKSRYB103K50
		C 24	CKSQYB334K16
R 1	RS1/16S183J	C 26	CKSRYB472K50
R 2	RS1/16S103J	C 30	CCSRCH220J50
R 5	RS1/16S0R0J	C 32	CCSRCH470J50
R 7	RS1/16S273J	C 35	CKSRYB103K50
R 8	RS1/16S473J	C 51	CKSRYB103K50
R 9	RS1/16S223J	C 52	CKSRYB473K16
R 10	RS1/16S473J	C 53	CCSRCK2R0C50
R 11	RS1/16S221J	C 54	CKSRYB103K50
R 12	RS1/16S103J	C 55	CKSRYB104K16
R 13	RS1/16S104J	C 56	CKSRYB104K16
R 16	RS1/16S223J	C 58	CKSQYB224K16
R 17	RS1/16S221J	C 101	CEALNP100M10
R 18	RS1/16S221J	C 102	CCSRCH151J50
R 19	RS1/16S473J	C 103	CKSRYB473K16
R 20	RS1/16S470J	C 105	CKSRYB682K25
R 31	RS1/16S0R0J	C 106	CEALR68M50
R 51	RS1/16S470J	C 107	CKSRYB103K50
R 52	RS1/16S103J	C 108	CKSQYB474K16
R 53	RS1/16S103J	C 109	CKSQYB474K16
R 54	RS1/16S331J	C 110	CKSRYB104K16
R 55	RS1/16S331J	C 111	CKSRYB104K16
R 56	RS1/16S560J	C 112	CKSRYB104K16
R 57	RS1/16S560J	C 113	CKSRYB123K25
R 58	RS1/16S102J	C 114	CEAL220M6R3
R 59	RS1/16S225J	C 115	CKSRYB473K16
R 60	RS1/16S133J		
R 61	RS1/16S433J		
R 101	RS1/16S333J		
R 102	RS1/16S103J		
R 103	RS1/16S333J		

====Circuit Symbol and No.==Part Name	Part No.	====Circuit Symbol and No.==Part Name	Part No.
C 116	CEAL2R2M50	L 1904	Inductor
C 117	CKSRYPB102K50	L 1905	Inductor Array
C 120	CKSRYPB183K25	L 1906	Inductor Array
C 121	CKSRYPB332K50	L 1907	Inductor
C 122	CKSRYPB562K25	L 1908	Inductor
C 123	CKSRYPB681K50	X 1901	Ceramic Resonator 15.62MHz
C 125	CKSRYPB103K50	S 1901	Push Switch
C 126	CKSRYPB103K50	S 1902	Push Switch
C 127	CEAL2R2M50	S 1903	Push Switch
C 128	CKSRYPB103K50	S 1904	Push Switch
C 201	CCSRCH471J50	S 1905	Push Switch
C 202	CCSRCH100D50	S 1906	Push Switch
C 203	CKSRYPB104K16	S 1907	Push Switch
C 204	CKSRYPB332K50	S 1908	Push Switch
C 205	CKSRYPB103K50	S 1909	Push Switch
C 206	CKSRYPB104K16	S 1910	Push Switch
C 207	CKSRYPB473K16	S 1911	Push Switch
C 208	CCSRCH560J50	S 1912	Push Switch
C 209	CEAL470M6R3	S 1913	Push Switch
C 210	CKSRYPB103K50	S 1914	Push Switch
C 211	CKSRYPB103K50	S 1915	Push Switch
C 212	CCSRCH101J50	S 1916	Push Switch
C 215	CKSRYPB223K25	S 1917	Push Switch
C 216	CKSOYB334K16	S 1918	Push Switch
C 217	CKSRYPB103K50	S 1919	Push Switch
C 219	CKSOYB105K10	S 1920	Push Switch
C 220	CKSRYPB104K16	S 1921	Push Switch
C 221	CKSRYPB473K16	S 1922	Push Switch
C 222	CKSOYB334K16	S 1923	Push Switch
C 223	CKSOYB474K16	S 1924	Push Switch
C 224	CKSRYPB104K16	S 1925	Push Switch
C 225	CKSRYPB272K50	RESISTORS	
C 226	CKSRYPB682K25	R 1901	RS1/16S154J
C 902	CCSRCH270J50	R 1902	RS1/16S473J
C 904	CKSRYPB223K25	R 1903	RA4C101J
C 905	CKSRYPB103K50	R 1904	RA3C101J
C 906	CCSRTH100D50	R 1905	RA3C101J
C 907	CCSRTH150J50	R 1906	RA4C101J
C 909	CCSRTH100D50	R 1907	RS1/16S473J
C 910	CKSRYPB332K50	R 1908	RA3C101J
C 912	CKSOYB474K16	R 1909	RA3C101J
C 913	CKSRYPB223K25	R 1910	RA4C101J
C 914	CKSRYPB682K25	R 1911	RA4C101J
C 915	CKSOYB223K25	R 1912	RA4C101J
C 916	CKSOYB474K16	R 1913	RA3C101J
C 917	CKSYB475K10	R 1914	RA4C101J
C 918	CKSRYPB223K25	R 1915	RA4C101J
C 919	CKSOYB225K10	R 1922	RS1/10S121J
C 920	CCSRCH270J50	R 1923	RS1/10S2R2J
C 921	CCSRCH270J50	R 1924	RS1/8S222J
C 922	CKSYB105K16	R 1925	RS1/8S222J
C 923	CKSRYPB103K50	R 1930	RS1/16S472J
		R 1931	RS1/16S473J
		R 1956	RS1/10S0R0J
		R 1957	RS1/10S0R0J
		R 1958	RS1/10S0R0J
		R 1959	RS1/10S0R0J
		R 1960	RS1/8S911J
		R 1961	RS1/8S911J
		R 1962	RS1/10S511J
		R 1963	RS1/10S511J
		R 1964	RS1/10S511J
		R 1965	RS1/10S511J
		R 1966	RS1/8S511J
		R 1967	RS1/8S511J
		R 1968	RS1/8S511J
		R 1969	RS1/8S511J
IC 1901	IC		
IC 1902	IC		
IC 1903	HIC Module		
D 1901	Diode Network		
D 1902	Diode Network		
D 1904	Diode		
D 1905	LED		
L 1901	Chip Inductor		
L 1902	Chip Inductor		
L 1903	Inductor		
	PD5471A		
	PD8051A		
	RS-140		
	DA204U		
	DA204U		
	MA110		
	CL170UBX		
	LCTA2R2J3225		
	LCTA2R2J3225		
	CTF1484		

C Unit Number : CWM6226
Unit Name : Keyboard Unit

MISCELLANEOUS

====Circuit Symbol and No.====Part Name

Part No.

R	1970	RS1/8S511J
R	1971	RS1/8S511J
R	1972	RS1/8S511J
R	1973	RS1/8S511J
R	1974	RS1/8S751J
R	1975	RS1/8S751J
R	1976	RS1/8S751J
R	1977	RS1/8S751J

CAPACITORS

C	1901	CKSQYB105K10
C	1902	CKSRYB103K25
C	1903	CSZS100M6R3
C	1904	CSZS100M6R3
C	1906	CKSQYB103K25
C	1907	CSZS100M6R3
C	1908	CKSRYB473K16
C	1911	CKSRYB473K16
C	1914	CKSRYB103K25
C	1916	CKSQYB104K25
C	1917	CSZSR100M16
C	1918	CKSRYB102K50
C	1919	CCSQCH221J50

D Unit Number :
Unit Name : Switch PCB

S	951	Switch(CLOSE)	CSN1012
S	952	Switch(OPEN)	CSN1022

E Unit Number : CWX2358
Unit Name : Control Unit

MISCELLANEOUS

IC	201	IC	UPD63710GC
IC	301	IC	BA5985FM
IC	602	IC	AK4321VF
IC	701	IC	BA05SFP
IC	901	IC	PE5011C
Q	101	Transistor	2SB1132
Q	901	Transistor	UN2111
D	801	LED	CL200IRX
D	802	LED	CL200IRX
TH	901	Thermistor	CCX1037
X	201	Ceramic Oscillator 16.934MHz	CSS1456
X	901	Radiator 8.380MHz	CSS1453
S	801	Spring Switch(HOME)	CSN1051
S	802	Spring Switch(CLAMP)	CSN1052

RESISTORS

R	101	RS1/8S120J
R	102	RS1/8S100J
R	103	RS1/16S222J
R	201	RS1/16S104J
R	205	RS1/16S103J
R	206	RS1/16S393J
R	207	RS1/16S182J
R	208	RS1/16S304J
R	210	RS1/16S0R0J
R	212	RS1/16S103J
R	213	RS1/16S103J
R	214	RS1/16S123J
R	215	RS1/16S273J
R	216	RS1/16S273J
R	217	RS1/16S681J
R	218	RS1/16S681J
R	309	RS1/16S473J
R	310	RS1/16S473J
R	501	RS1/16S102J
R	502	RS1/16S681J

====Circuit Symbol and No.====Part Name

Part No.

R	503	RS1/16S681J
R	504	RS1/16S681J
R	505	RS1/16S681J
R	506	RS1/16S681J
R	511	RS1/16S0R0J
R	601	RS1/16S102J
R	602	RS1/16S102J
R	603	RS1/16S223J
R	604	RS1/16S223J
R	606	RS1/16S0R0J
R	607	RS1/16S0R0J
R	612	RA4C0R0J
R	801	RS1/8S751J
R	802	RS1/8S751J
R	901	RS1/16S222J
R	902	RS1/16S473J
R	903	RS1/16S222J
R	904	RS1/16S473J
R	905	RN1/16SE1502D
R	906	RS1/16S473J
R	908	RS1/16S222J
R	909	RS1/16S104J
R	910	RS1/16S103J
R	911	RS1/16S223J
R	912	RS1/16S473J
R	917	RS1/16S0R0J

CAPACITORS

C	101	CCSRCH102J25
C	102	CKSQYB104K16
C	103	CEV101M6R3
C	104	CEV470M6R3
C	105	CKSQYB334K16
C	106	CKSQYB334K16
C	107	CKSQYB334K16
C	201	CKSQYB104K16
C	202	CEV101M6R3
C	203	CKSQYB104K16
C	204	CKSRYB332K50
C	205	CKSQYB104K16
C	206	CKSRYB392K50
C	207	CKSQYB224K16
C	208	CCSRCH270J50
C	209	CCSRCH3R0C50
C	210	CCSRCH221J50
C	211	CCSRCH101J50
C	212	CKSRYB682K25
C	213	CKSQYB104K16
C	214	CKSRYB104K16
C	215	CKSQYB104K16
C	216	CKSRYB104K16
C	217	CKSRYB104K16
C	218	CKSRYB104K16
C	219	CKSRYB104K16
C	220	CKSRYB104K16
C	223	CKSQYB471K50
C	301	CEV101M10
C	601	CEV4R7M35
C	602	CEV4R7M35
C	603	CCSQSL152J50
C	604	CCSQSL152J50
C	605	CEV470M6R3
C	606	CKSRYB104K16
C	607	CKSRYB104K16
C	608	CKSRYB104K16
C	609	CEV100M16
C	610	CKSRYB104K16
C	612	CKSRYB104K16

====Circuit Symbol and No.==Part Name		Part No.
C	701	CEV101M6R3
C	702	CCH1300
C	703	CKSQYB334K16
C	801	CKSRYB103K25
C	802	CKSRYB103K25
C	901	CKSRYB472K50
C	902	CKSYB475K10
C	903	CKSRYB103K25

F Unit Number :
Unit Name : Photo Unit

Q	1	Photo-transistor	CPT230SX-TU
Q	2	Photo-transistor	CPT230SX-TU

Miscellaneous Parts List

M	1	Pickup Unit(Service)(P8)	CXX1285
M	1	Motor Unit(CARRIAGE)	CXB2190
M	2	Motor Unit(LOADING)	CXB2195
M	3	Motor Unit(SPINDLE)	CXB2562
M	951	Motor (AUTO FLAP)	CXM1085

6. ADJUSTMENT

6.1 CD ADJUSTMENT

1) Precautions

- This unit uses a single power supply (+5V) for the regulator. The signal reference potential, therefore, is connected to REFO(approx. 2.5V) instead of GND.

If REFO and GND are connected to each other by mistake during adjustments, not only will it be impossible to measure the potential correctly, but the servo will malfunction and a severe shock will be applied to the pick-up. To avoid this, take special note of the following.

Do not connect the negative probe of the measuring equipment to REFO and GND together. It is especially important not to connect the channel 1 negative probe of the oscilloscope to REFO with the channel 2 negative probe connected to GND.

Since the frame of the measuring instrument is usually at the same potential as the negative probe, change the frame of the measuring instrument to floating status.

If by accident REFO comes in contact with GND, immediately switch the regulator or power OFF.

- Always make sure the regulator is OFF when connecting and disconnecting the various filters and wiring required for measurements.
- Before proceeding to further adjustments and measurements after switching regulator ON, let the player run for about one minute to allow the circuits to stabilize.
- Since the protective systems in the unit's software are rendered inoperative in test mode, be very careful to avoid mechanical and /or electrical shocks to the system when making adjustment.
- Disc detection during loading and eject operations is performed by means of a photo transistor in this unit. Consequently, if the inside of the unit is exposed to a strong light source when the outer casing is removed for repairs or adjustment, the following malfunctions may occur.

*During PLAY, even if the eject button is pressed, the disc will not be ejected and the unit will remain in the PLAY mode.

*The unit will not load a disc.

When the unit malfunctions this way, either re-position the light source, move the unit or cover the photo transistor.

2) Test Mode

This mode is used for adjusting the CD mechanism module of the device.

- Test mode starting procedure
Reset while pressing the **4** and **6** keys together.
- Test mode cancellation
Switch ACC, back-up OFF.
- After pressing the EJECT key, do not press any other key until the disk is completely ejected.
- If the ► or ◀ key is pressed while focus search is in progress, immediately turn the power off (otherwise the actuator may be damaged due to adhesion of the lenses).
- Jump operation of TRs other than 100TR continues after releasing the key. CRG move and 100TR jump operations are brought into the "Tracking close" status when the key is released.
- Powering Off/On resets the jump mode to "Single TR (91)", the RF AMP gain setting to 0 dB, and the automatic adjustment value to the initial value.

6.2 CHECKING THE GRATING AFTER CHANGING THE PICKUP UNIT

• Note :

The grating angle of the PU unit cannot be adjusted after the PU unit is changed. The PU unit in the CD mechanism module is adjusted on the production line to match the CD mechanism module and is thus the best adjusted PU unit for the CD mechanism module. Changing the PU unit is thus best considered as a last resort. However, if the PU unit must be changed, the grating should be checked using the procedure below.

• Purpose :

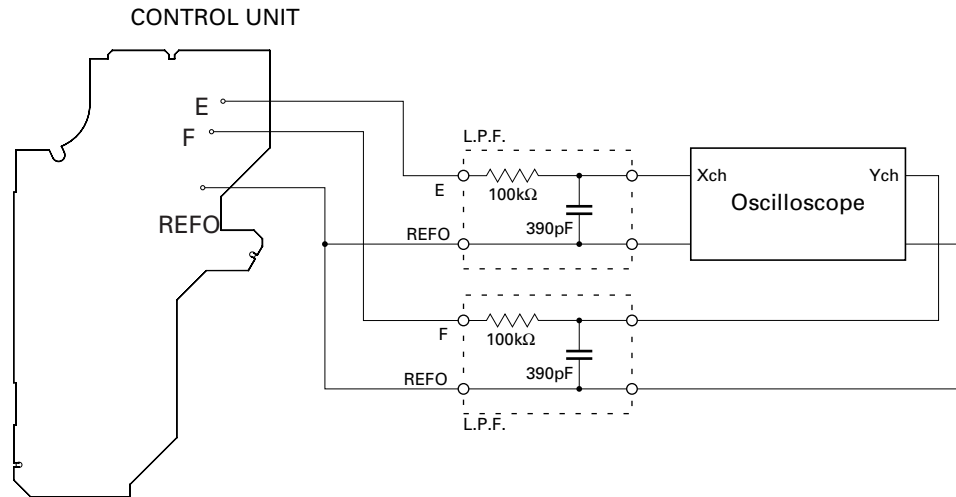
To check that the grating is within an acceptable range when the PU unit is changed.

• Symptoms of Mal-adjustment :

If the grating is off by a large amount symptoms such as being unable to close tracking, being unable to perform track search operations, or taking a long time for track searching.

• Method :

- | | |
|-----------------------|----------------------------|
| • Measuring Equipment | • Oscilloscope, Two L.P.F. |
| • Measuring Points | • E, F, REFO |
| • Disc | • ABEX TCD-784 |
| • Mode | • TEST MODE |



• Checking Procedure

1. In test mode, load the disc and switch the 5V regulator on.
2. Using the ► and ◄ buttons, move the PU unit to the innermost track.
3. Press key 3 to close focus, the display should read "91". Press key 2 to implement the tracking balance adjustment the display should now read "81". Press key 3 2 times. The display will change, returning to "81" on the fourth press.
4. As shown in the diagram above, monitor the LPF outputs using the oscilloscope and check that the phase difference is within 75°. Refer to the photographs supplied to determine the phase angle.
5. If the phase difference is determined to be greater than 75° try changing the PU unit to see if there is any improvement. If, after trying this a number of times, the grating angle does not become less than 75° then the mechanism should be judged to be at fault.

• Note

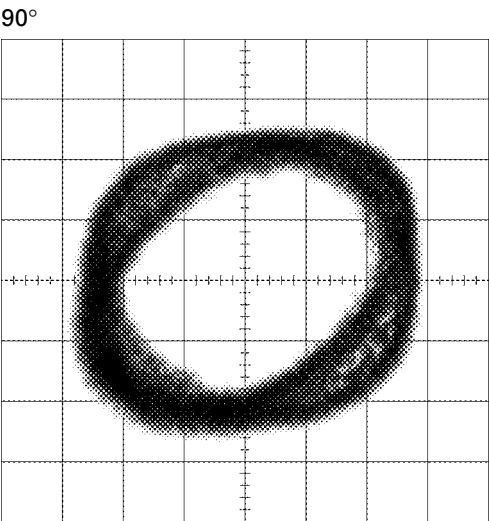
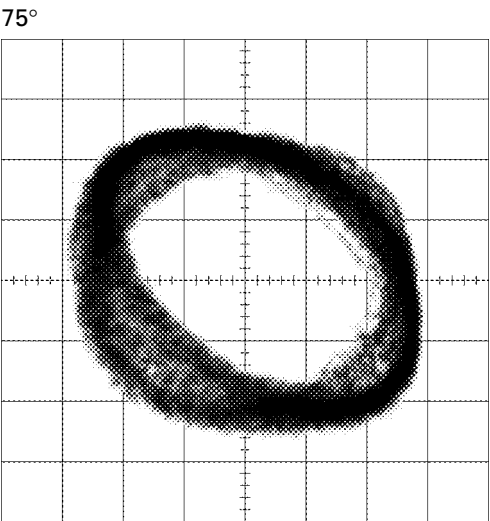
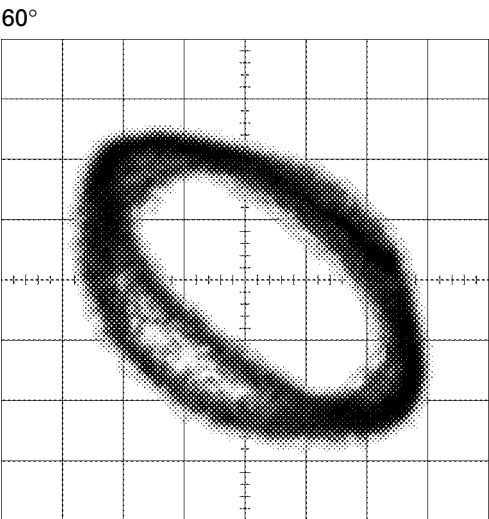
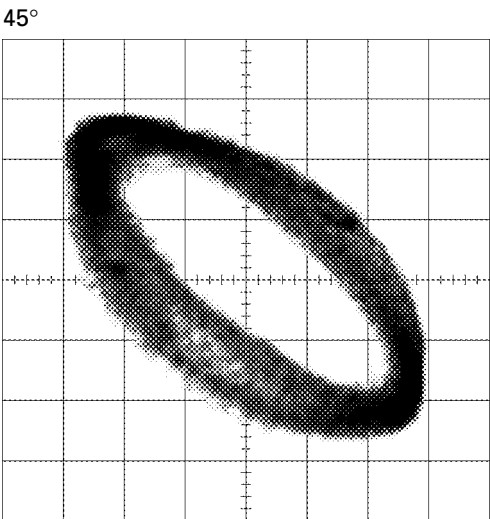
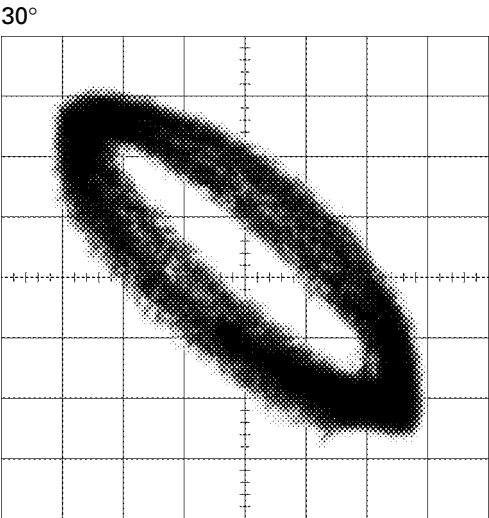
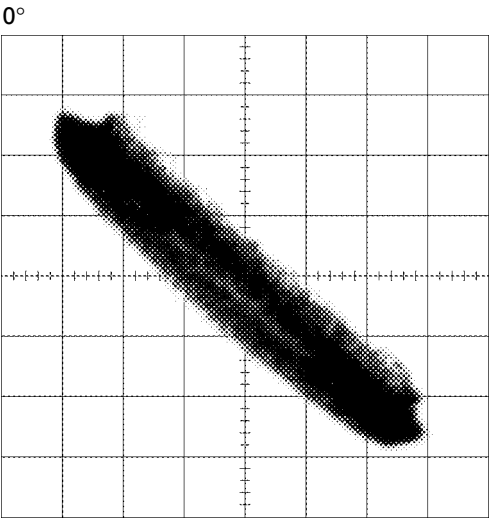
Because of eccentricity in the disc and a slight misalignment of the clamping center the grating waveform may be seen to "wobble" (the phase difference changes as the disc rotates). The angle specified above indicates the average angle.

• Hint

Reloading the disc changes the clamp position and may decrease the "wobble".

Grating waveform

Ech → Xch 20mV/div, AC
Fch → Ych 20mV/div, AC



7. GENERAL INFORMATION

7.1 DIAGNOSIS

7.1.1 TEST MODE

● Error Messages

If a CD is not operative or stopped during operation due to an error, the error mode is turned on and cause(s) of the error is indicated with a corresponding number. This arrangement is intended at reducing nonsense calls from the users and also for facilitating trouble analysis and repair work in servicing.

(1) Basic Indication Method

1) When SERRORM is selected for the CSMOD (CD mode area for the system), error codes are written to DMIN (minutes display area) and DSEC (seconds display area). The same data is written to DMIN and DSEC. DTNO remains in blank as before.

2) Main unit display examples

Depending on display capability of LCD used, display will vary as shown below. xx contains the error number.

8-digit display	6-digit display	4-digit display
ERROR-xx	ERR-xx	E-xx
	OR	
	Err-xx	

(2) Error Code List

Code	Class	Displayed error code	Description of the code and potential cause(s)
10	Electricity	Carriage Home NG	CRG can't be moved to inner diameter. CRG can't be moved from inner diameter. → Failure on home switch or CRG move mechanism.
11	Electricity	Focus Servo NG	Focusing not available. → Stains on rear side of disc or excessive vibrations on REWRITABLE.
12	Electricity	Spindle Lock NG	Spindle not locked. Sub-code is strange (not readable). → Failure on spindle, stains or damages on disc, or excessive vibrations.
		Subcode NG	A disc not containing CD-R data is found. Turned over disc are found, though rarely. → Failure on home switch or CRG move mechanism.
		RF AMP NG	An appropriate RF AMP gain can't be determined. → CD signal error.
17	Electricity	Setup NG	APC protection doesn't work. Focus can be easily lost. → Damages or stains on disc, or excessive vibrations.
30	Electricity	Search Time Out	Failed to reach target address. → CRG tracking error or damages on disc.
A0	System	Power Supply NG	Power (VD) is ground faulted. → Failure on SW transistor or power supply (failure on connector).

Remarks: Mechanical errors are not displayed (because a CD is turned off in these errors).

Unreadable TOC does not constitute an error. An intended operation continues in this case.

A newly designed main unit must conform to the example given above.

Upper digits of an error code are subdivided as shown below:

1x: Setup relevant errors, 3x: Search relevant errors, 3x: Search relevant errors, Ax: Other errors.

● New Test Mode

S-CD plays the same way as before.

If an error such as off focus, spindle unlocking, unreadable sub-code, or sound skipping occurs after setup, its cause and time occurred (in absolute time) are displayed.

During setup, operational status of the control software (internal RAM: CPOINT) is displayed.

These displays and functions are prepared for enhancing aging in the servicing and efficiency of trouble analysis.

(1) Shifting to the New Test Mode

- ① Turn on the current test mode by starting the reset from the key (it varies between the products).
 - ② Select S-CD for the source through the specified procedure including use of the [SOURCE] key, and inserting the disc. Then, press the [6] key while maintaining the regulator turned off.
 - ③ After the above operations, the new test mode remains on irrespective of whether the S-CD is turned on or off.
- You can reset the new test mode by turning on the reset start.

* With some products, the new test mode can be reset through the same operations as that employed for shifting to the STBY mode (while maintaining the Acc turned off).

(2) Key Correspondence

Key	Test mode		New test mode	
	Power Off	Power On	In-play	Error Production
BAND	To power on (offset adjustment performed)	To power off	–	Time/Err.No. switching
▶	–	FWD-Kick	FF/TR+	–
◀	–	REV-Kick	REV/TR-	–
1	–	T.Close (AGC performed) /parameter display switching	Scan	–
2	RF AMP gain switching	Parameter display switching /T.BAL adjustment/T.Open	Mode	–
3	To power on (offset adjustment not performed)	F.Close/RF AGC/F.T.AGC	–	–
6	–	F.Mode switching /T.Close (no AGC)/Jump switching	Auto/Manu	T.No./Time switching

Note: Eject and CD on/off is performed in the same procedure as that for the normal mode.

(3) Cause of Error and Error Code

Code	Class	Contents	Description and cause
40	Electricity	Off focus detected.	FOK goes low. → Damages/stains on disc, vibrations or failure on servo.
41	Electricity	Spindle unlocked.	FOK = Low continued for 50 msec. → Damages/stains on disc, vibrations or failure on servo.
42	Electricity	Sub-code unreadable.	Sub-code was unreadable for 50 msec. → Damages/stains on disc, vibrations or failure on servo.
43	Electricity	Sound skipping detected.	Last address memory function was activated. → Damages/stains on disc, vibrations or failure on servo.

Note: Mechanical errors during aging are not displayed.

The error codes should be indicated in the same way as in the normal mode.

(4) Display of Operational Status (CPOINT) during Setup

Status No.	Contents	Protective action
00	CD+5V ON process in progress.	None
01	Servo LSI initialization (1/3) in progress.	None
02	Servo LSI CRAM initialization in progress.	None
03	Servo LSI initialization (2/3) in progress.	None
04	Offset adjustment (1/3) in progress.	None
05	Offset adjustment (2/3) in progress.	None
06	Offset adjustment (3/3) in progress.	None
07	FZD adjustment in progress.	None
08	Servo LSI initialization (3/3) in progress.	None
10	Carriage move to home position started.	None
11	Carriage move to home position started.	None
12	Carriage is moving toward inner diameter.	Specified 10 seconds has been passed or failure on home switch.
13	Carriage is moving toward outer diameter.	Specified 10 seconds has been passed or failure on home switch.
14	Carriage outer kick in progress.	None
15	Carriage outer diameter feed (1 second) in progress.	None
20	Servo close started.	None
21	Pre-processing for focus search started.	None
22	Spindle rotation and focus search started.	None
23	Waiting for focus close (XSI=Low).	Specified focus search time has been passed.
24	Standing by after focus close is over.	Specified focus search time has been passed.
25	Focus search preprocessing is in progress while setup protection is turned on.	None
26	Focus search preprocessing is in progress while focus recovery is turned on.	None
27	Wait time after focus close is set up.	Off focus.
28	Standing by after focus close is over.	Off focus.
29	Setup (1/2) before T balance adjustment is started.	Off focus.
30	Setup (2/2) before T balance adjustment is started.	Off focus.
31	T balance adjustment started.	Off focus.
32	T balance adjustment (1/2).	Off focus.
33	T balance adjustment (2/2).	Off focus.
34	Waiting for spindle rotation to end. Spindle rough servo.	Off focus.
35	Standing by after spindle rough servo is over.	Off focus.
36	RF AGC started.	Off focus.
37	RF AGC started.	Off focus.
38	RF AGC ending process in progress.	Off focus.
39	Tracking close in progress.	Off focus.
40	Standing by after tracking is closed. Carriage closing in progress.	Off focus.
41	Focus/tracking AGC started.	Off focus.
42	Focus AGC started.	Off focus.
43	Focus AGC in progress.	Off focus.
44	Tracking AGC in progress.	Off focus.
45	Standing by after focus/tracking AGC are over.	Off focus.
46	Spindle processes applicable servo.	Off focus.
47	Check for servo close is started.	Off focus.
48	Check of LOCK pin started.	Off focus or spindle not locked.
49	RF AGC started.	Off focus.
50	RF AGC in progress.	Off focus.
51	Standing by after RF AGC is over.	Off focus.

(5) Display Examples

1) During Setup (When status no. = 11)

TRK No.	MIN.	SEC.
11	11'	11"

2) During Operation (TOC read, TRK search, Play, FF and REV)

The same as in the normal mode.

3) When a Protection Error Occurred

Switch to the following displays (A) and (B) using the [BAND] switch:

(A) Error occurrence timing display in absolute time.

An example: Error occurred in 12th tune at 34'56" in absolute time.

TRK No.	MIN.	SEC.
12	34'	56"

(B) Error No. display

An example: Error #40 (Off focus is detected)

ERROR-40

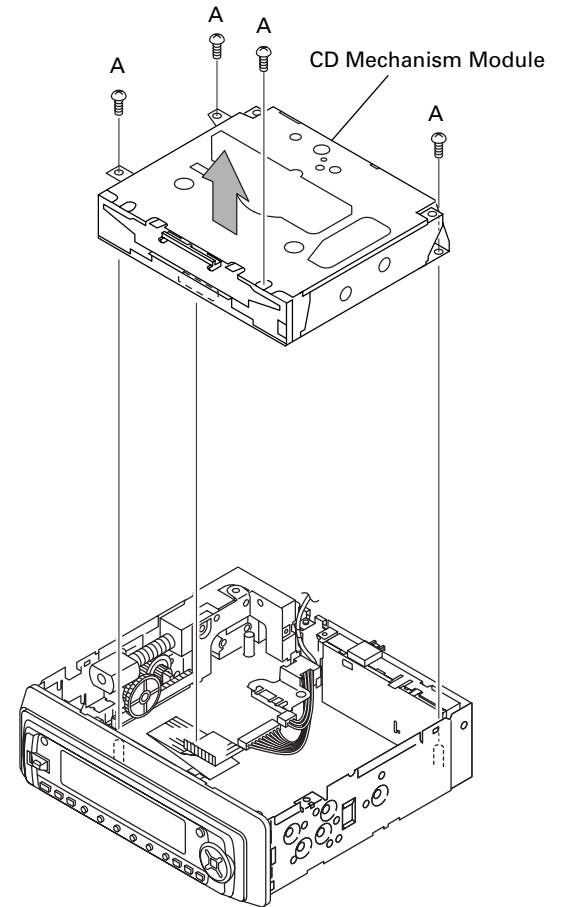
7.1.2 DISASSEMBLY

● Removing the Case (Not shown)

1. Remove the two screws, and then remove the Case.

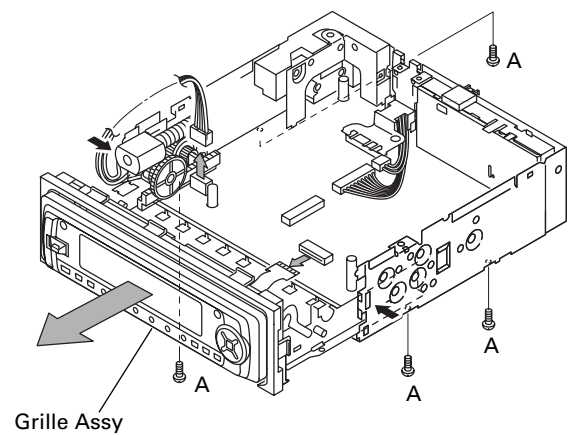
● Removing the CD Mechanism Module

1. Remove the four screws A.
2. Disconnect the connector, and then remove the CD Mechanism Module.



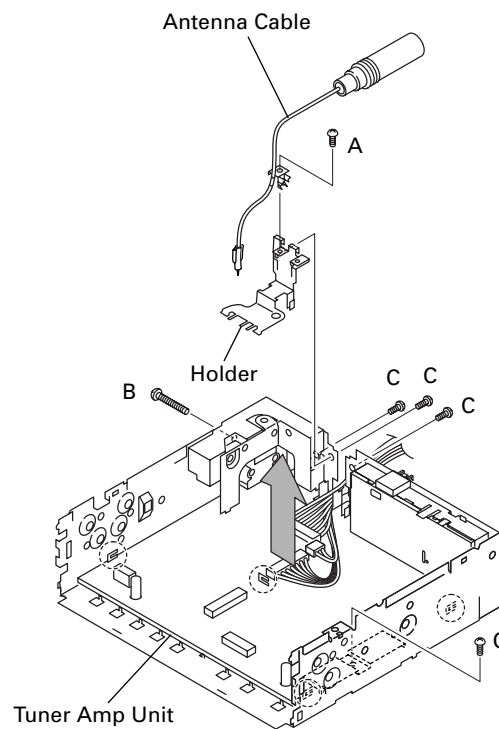
● Removing the Tuner Amp Unit (1/2)

1. Disconnect the two connectors.
2. Remove the four screws A.
3. Disconnect the two stoppers indicated by arrows, and then remove the Grille Assy.



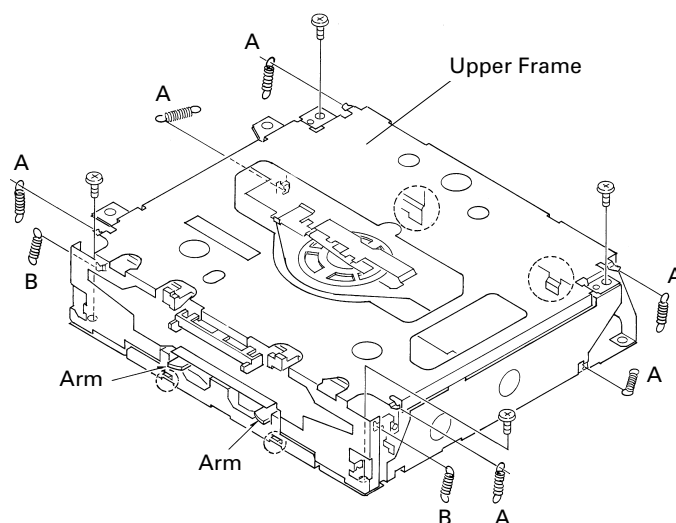
● **Removing the Tuner Amp Unit (2/2)**

1. Remove the screw A, four screws C, and then remove the Antenna Cable and Holder.
2. Remove the screw B.
3. Stretch the four tabs, and then remove the Tuner Amp Unit.



● Removing the Upper Frame

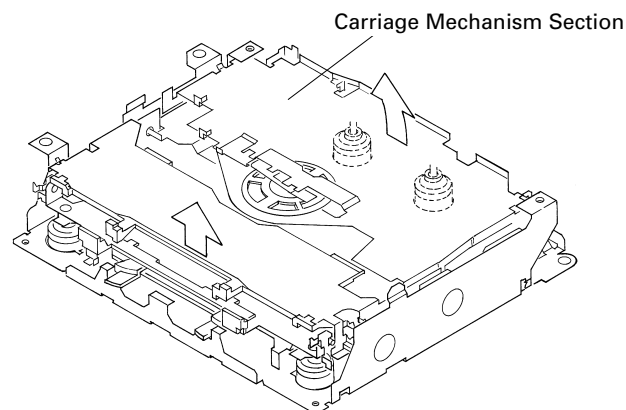
1. Remove six Springs A, two Springs B and four Screws.
2. Remove two Tabs situated on rear side of the Upper Frame, remove two Arms on the front side, then remove two Tabs on the front side.



● Removing the Carriage Mechanism

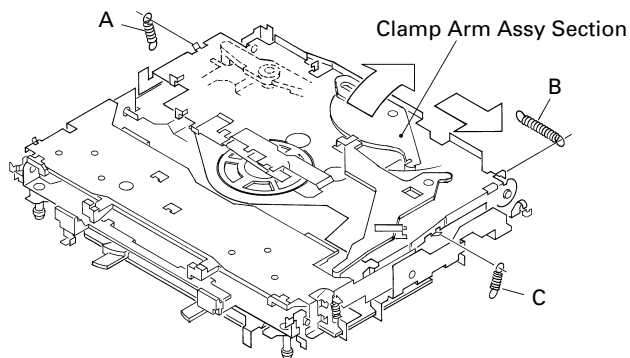
1. Disengage the Carriage Mechanism from the two dampers situated in the front side by driving it up, then disengage and remove the mechanism from the two dampers by driving it up aslant into front side direction.

Note : When assembling the Carriage Mechanism, coat the dampers with alcohol prior to the assembly.



● Removing the Clamp Arm Assy

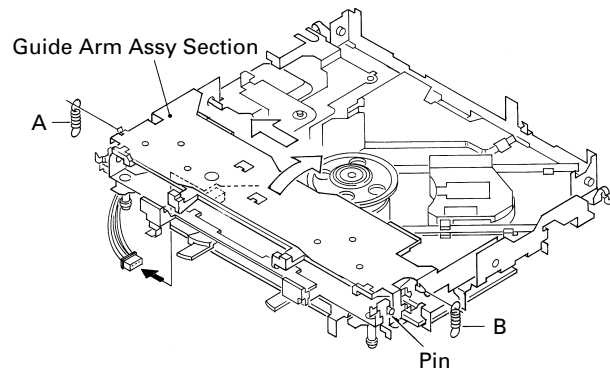
1. Remove a Spring A, a B and a Spring C.
2. Drive the Clamp Arm Assy up into rear side direction, then disengage the arm from its current position. Finally, drive the assembly approximately 45 degrees upward, then slide the assembly toward right side to remove it.



● Removing the Guide Arm Assy

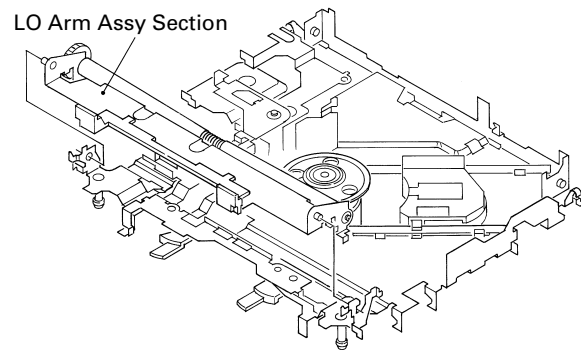
1. Remove a connector, a spring A and B
2. Drive the Guide Arm Assy up aslant into rear side direction, then remove it from a Pin. Finally, drive the assembly approximately 45 degrees upward, then slide the assembly toward left side to remove it.

Note : When assembling the guide arm assembly, route the cord inside the assembly. In this operation, care must be exercised so that cord may be caught by the gear.



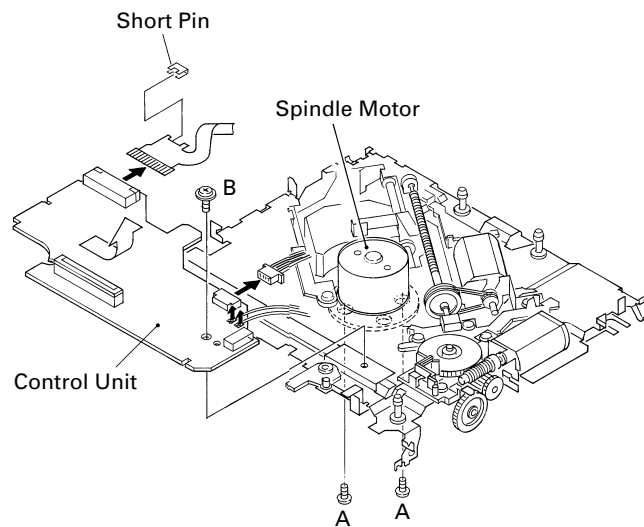
● Removing the LO Arm Assy

1. Remove two Pins to dismount the LO Arm Assy.



● Removing the Control Unit and the Spindle Motor

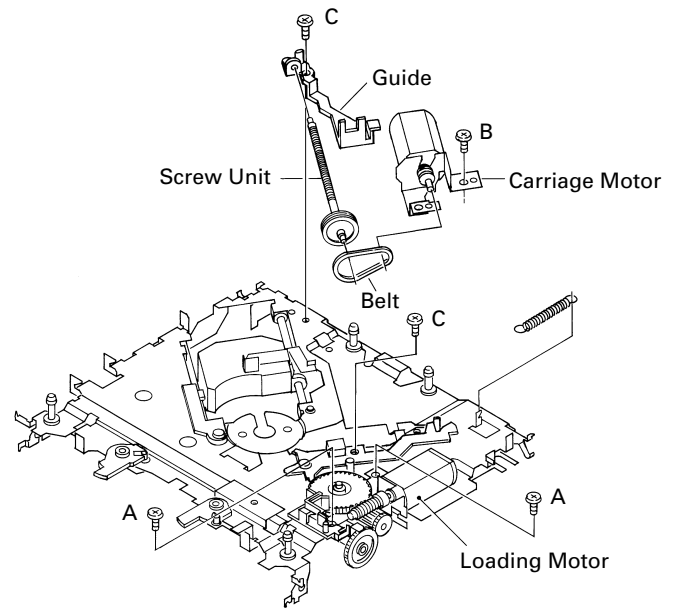
1. Remove from the connector after mounting the short pin on the flexible PCB of the pickup unit.
2. Remove two Soldered joints, then remove two Screws A.
3. Remove two connectors and a Screw B.
4. Disengage the Control Unit from two Tabs, then dismount the unit by sliding it toward left.
5. Dismount the Spindle Motor.



● Removing the Loading Motor and Carriage Motor

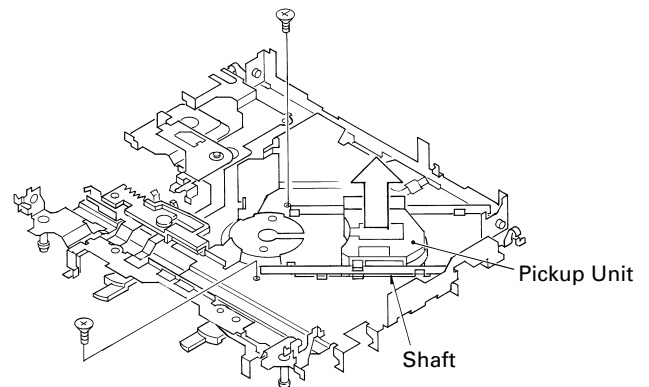
1. Remove the Spring and two Screws A.
2. Dismount the Loading Motor.
3. Remove the Belt, a Screw B, two Screws C, a Guide and a Screw Unit.
4. Dismount the Carriage Motor.

Note : When assembling the Belt, use care so that it may not be contaminated by grease.



● Removing the Pickup Unit

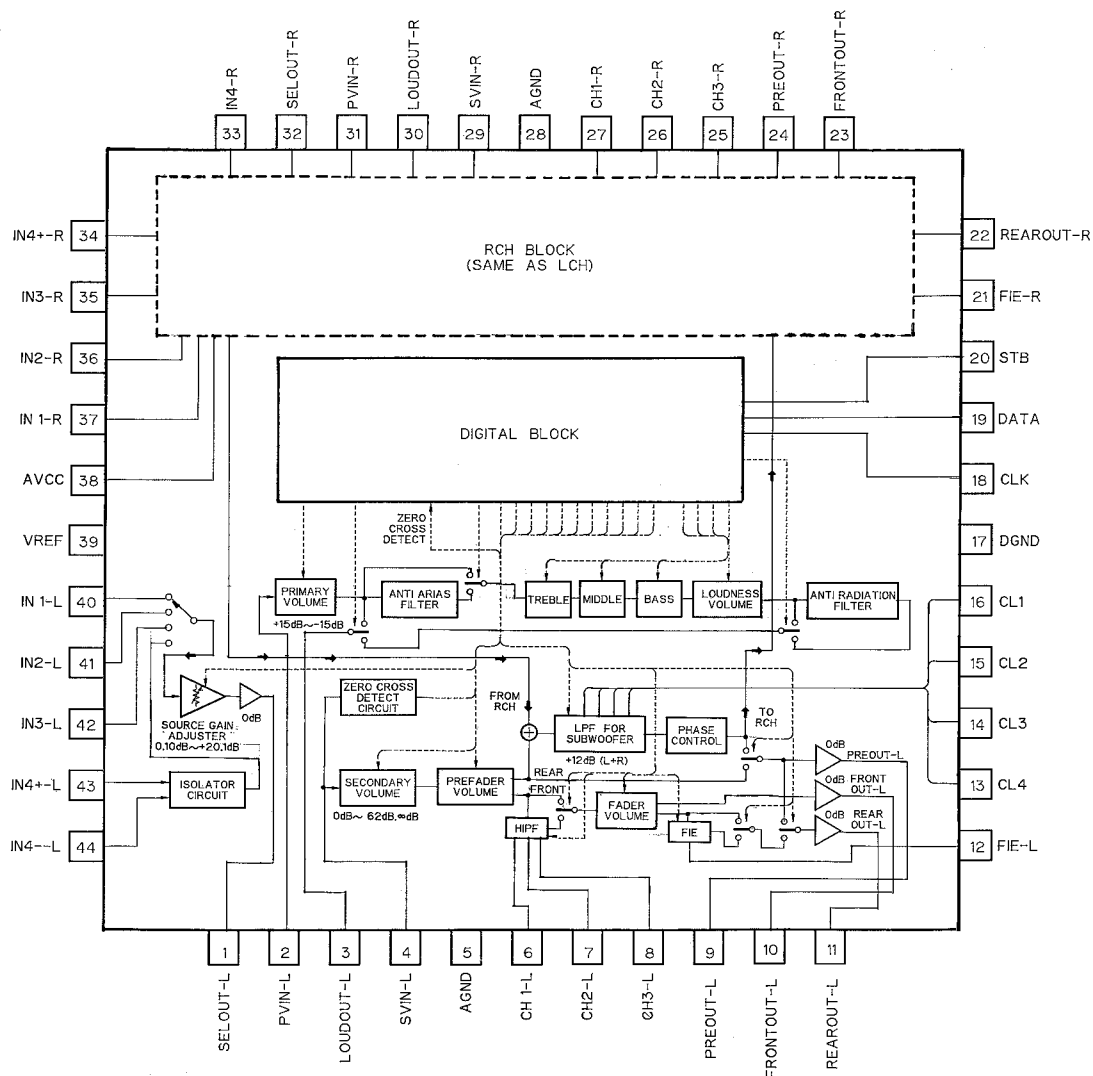
1. Remove two Screws and a Shaft.
2. Dismount the Pickup Unit.



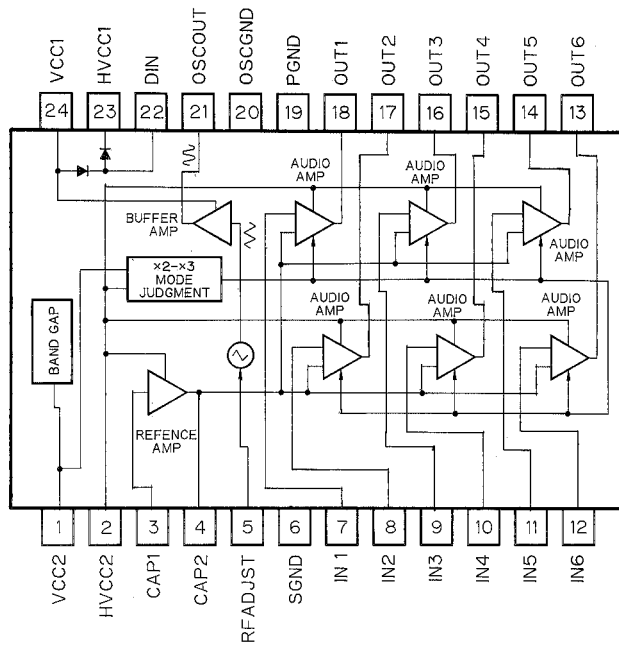
7.2 IC

PML004AF	PD5487A, PD5488A	BA5985FM
PA2028A	BA6288FS	PE5011C
PAL005A	BR9010FV	
S-81250SGUP	PD5471A	
PM4009A	UPD63710GC	

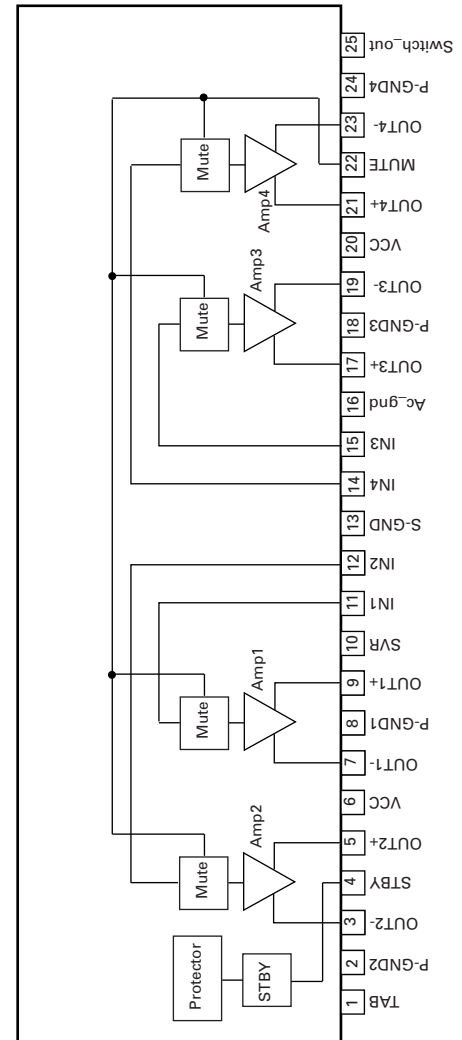
PML004AF



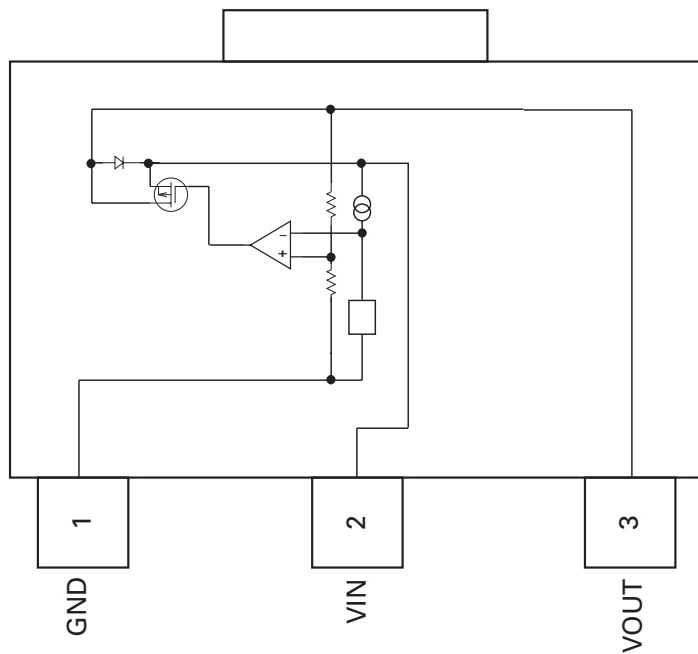
PA2028A



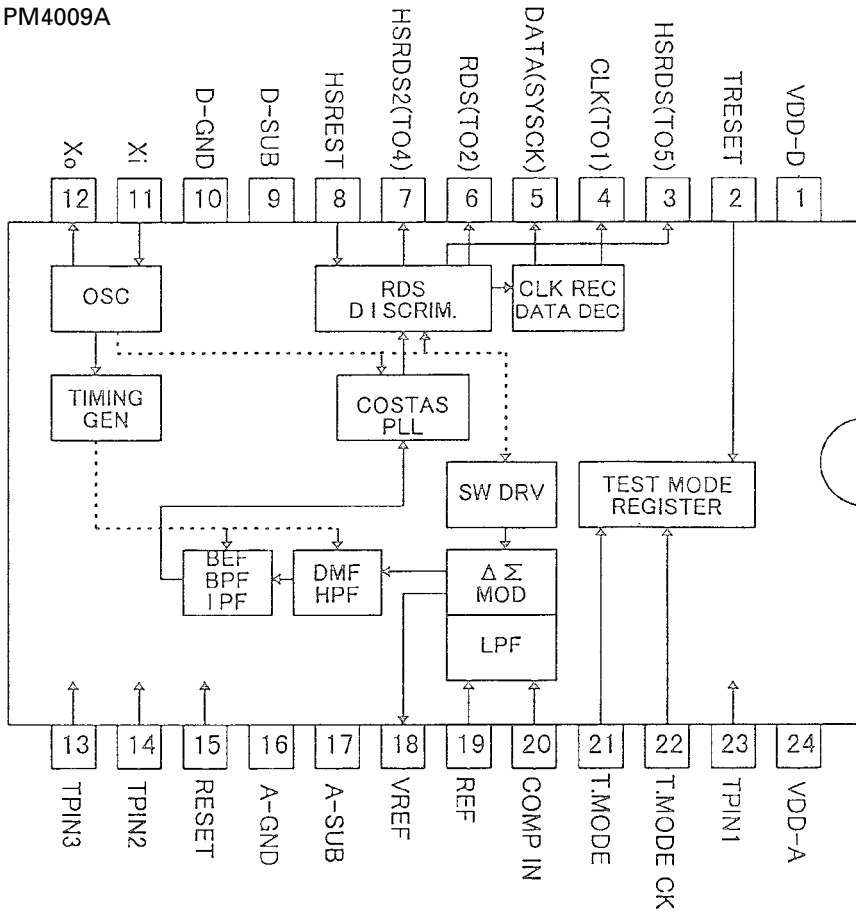
PAL005A



S-81250SGUP



PM4009A

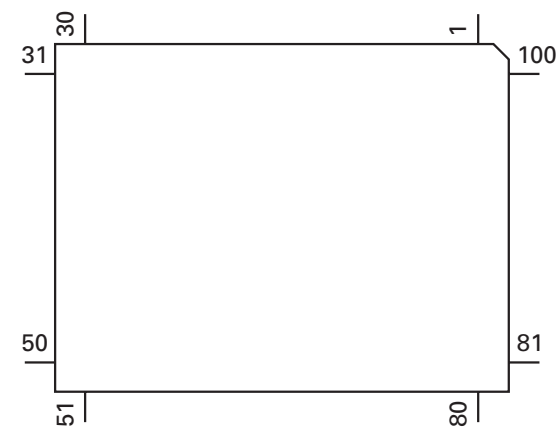


● Pin Functions (PD5487A, PD5488A)

Pin No.	Pin Name	I/O	Function and Operation
1	TUNPDO	O	PLL data output
2	TUNPCK	O	PLL clock output
3	TUNPCE	O	PLL chip enable output
4	TUNPCE2	O	PLL chip enable output 2
5	MOSENS	I	Motion/window damage sensor input
6	DLSSENS	I	Door lock sense input
7	IPPW	O	IP-BUS power supply control output
8,9	VSS1,2		GND
10	ASENBO	O	IP-BUS slave power supply control output
11	TELIN	I	Cellular mute input
12	RESET	I	Reset input
13	OSC1	O	Oscillator connection pin 1
14	VSS3		GND
15	OSC2	O	Oscillator connection pin 2
16	VCC1		5V
17	NMI		Pull up
18	RCK	I	RDS clock input
19	NC		Not used
20	DALMON	O	DFS alarm output
21	RX2	I	IP-BUS data input 2
22	SYSPW	O	System power supply control output
23	ISENS	I	Illumination sense input
24	PEE	O	Beep tone output
25	RDS57K	I	57kHzBP-OUT sense input
26	FLPPW	O	Flap motor driver power ON/OFF output
27	MUTE	O	Mute output
28	NC		Not used
29	RX	I	IP-BUS data input
30	TX	O	IP-BUS data output

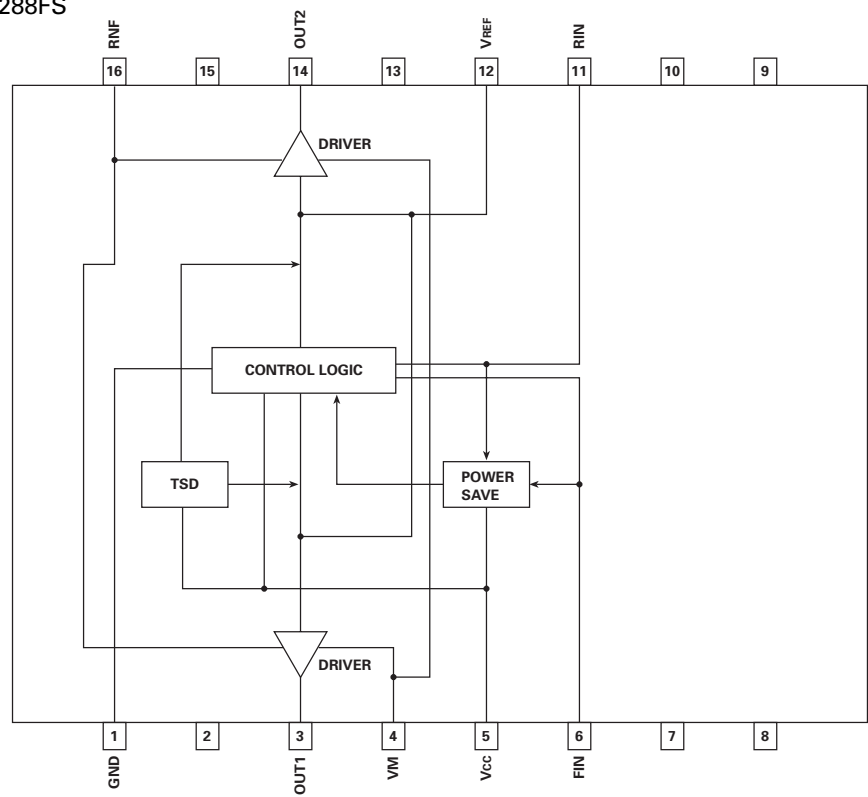
Pin No.	Pin Name	I/O	Function and Operation
31	BSO	O	P-BUS communication data output
32	BSI	I	P-BUS communication data input
33	BSCK	I/O	P-BUS serial clock input/output
34	FLPOPEN	O	Flap motor open output
35	DPDT	O	Display serial data output
36	KYDT	I	Display enable data input
37	FLPCLS	O	Flap motor close output
38	FOPENSW	I	Flap open switch input
39	NC		Not used
40	FCLSSW	I	Flap close switch input
41	DLED	O	Alarm LED output
42	NC		Not used
43	FLPILM	O	Inside of flap illumination output
44	ILMPW	O	Illumination power supply control output
45	SWVDD	O	Display chip select output
46	OELPW	O	OEL module power supply control output
47	DSSENS	I	Grille detach sense input
48	ST	I	FM stereo input
49	SD	I	SD input
50-61	NC		Not used
62	VCC3		5V
63	NC		Not used
64	VSS4		GND
65	VCK/ROMCLK	O	E-VOL clock output / ROM correction clock output
66	VDT/ROMDATA	O/I	E-VOL data output / ROM correction data input
67	VST/BSRQ2	O/I	E-VOL strobe pulse output / P-BUS communication input/output
68	NC		Not used
69	BRXEN	I/O	P-BUS communication input/output
70	BRST	O	P-BUS reset output
71	BSRQ	I/O	P-BUS communication request input/output
72	NC		Not used
73	BSSENS	I	Back up power sense input
74	ASENS	I	ACC power sense input
75	NC		Not used
76	DRELAY	O	External relay output
77	LOCH	O	Local "H" output
78	LOCL	O	Local "L" output
79	NC		Not used
80	NC		Open
81	FM/AM	O	FM/AM power select output
82	TMUTE	O	Tuner mute output
83	DRST	O	RDS decoder reset output
84	RDSLK	I	RDS lock signal input
85	RDT	I	RDS data input
86	DRSENS	I	Door open/close sense input
87	DRSYS	O	Door system select output
88	TESTIN	I	Test mode IN/test enable
89,90	NC		Not used
91	LEVELR	I	Level meter "R" AD input
92	LEVELL	I	Level meter "L" AD input
93	NC		Not used
94	SD_BW	I	SD input
95	NC		Not used
96	VSS5		GND
97	SL	I	Signal level input
98	VREF		A/D converter reference voltage
99	VCC4		5V
100	TUNPDI	I	PLL data input

*PD5487A, PD5488A

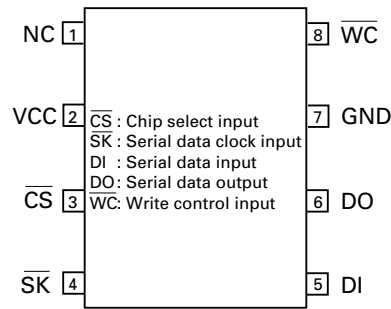


IC's marked by* are MOS type.
Be careful in handling them because they are very liable to be damaged by electrostatic induction.

BA6288FS



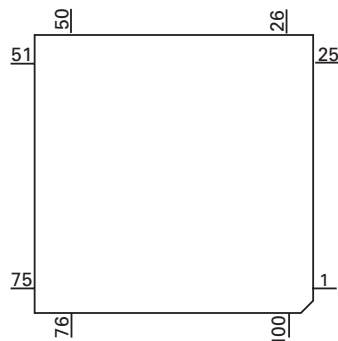
BR9010FV



● Pin Functions (PD5471A)

Pin No.	Pin Name	I/O	Format	Function and Operation
1-4	NC			Not used
5	REM	I		Remote control reception
6	BYTE	I		External data BUS width select input
7	CNVSS	I		Processor mode select input
8,9	NC			Not used
10	RESET	I		Reset input
11	XOUT	O		Crystal oscillating element connection pin
12	VSS			GND
13	XIN	I		Crystal oscillating element connection pin
14	VDD			VDD
15	NMI	I		NMI input
16	NC			Not used
17-20	KD1-4	I		Key data 1-4
21-26	KS1-6	I/O		Key strobe input/output 1-6
27-31	NC			Not used
32	ILMD	O	C	Dual illumination
33	KYDT	O	C	Key data output
34	DPDT	I		Display data input
35	NC			Not used
36	OEL	O	C	OEL controller ON
37	RDY	I		OEL controller ready input
38	NC			Not used
39	HOLD	I		Hold input
40,41	NC			Not used
42	RD	O	C	Read strobe
43	NC			Not used
44	WR	O	C	Write strobe
45	NC			Not used
46	CS2	O	C	Bank address (High)
47	CS1	O	C	Bank address (Low)
48	CS0	O	C	External ROM chip select
49	A19	O	C	Address bus Output
50	NC			Not used
51-59	A17-9	O	C	Address bus Output
60	VDD			VDD
61	A8	O	C	Address bus Output
62	VSS			GND
63-69	A7-1	O	C	Address bus Output
70	NC			Not used
71-86	D15-0	I/O		Data bus input/output
87-93	NC			Not used
94	AVSS			Connect to VSS
95	NC			Not used
96	VREF			Connect to VSS
97	AVCC			Connect to VCC
98-100	NC			Not used

*PD5471A



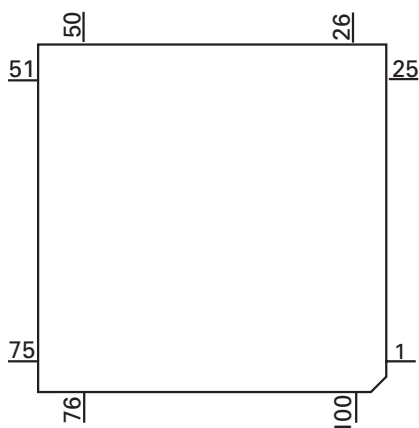
Format	Meaning
C	C MOS

● Pin Functions (UPD63710GC)

Pin No.	Pin Name	I/O	Function and Operation
1	GND		Logic circuit GND
2	HOLD	I/O	Defect detection output
3	MIRR	I/O	MIRR output
4	FOK	O	RFOK signal output
5	RST	I	Reset signal input
6	A0	I	Command/parameter identification signal input
7	STB	I	Data strobe signal input
8	SCK	I	Clock signal input for serial data input/output
9	SO	O	Serial data and status signal output
10	SI	I	Serial data input
11	VDD		Positive power supply terminal to logic circuit
12	DA.VDD		Positive power supply terminal to D/A converter
13	NC		Not used
14, 15	DA.GND		D/A converter GND
16	NC		Not used
17	DA.VDD		Positive power supply terminal to D/A converter
18	R+	O	Right channel audio data output
19	R-	O	Right channel audio data output
20	L-	O	Left channel audio data output
21	L+	O	Left channel audio data output
22	X.VDD		Positive power supply terminal to crystal oscillation circuit
23	XTAL	O	Crystal oscillator connect pin
24	XTAL	I	Crystal oscillator connect pin
25	X.GND		Crystal oscillation circuit GND
26	VDD		Positive power supply terminal to logic circuit
27	EMPH	O	Output pin for the pre-emphasis data in the sub-Q code
28	FLAG	O	Flag output pin to indicate that audio data currently being output consists of noncorrectable data
29	DIN	I	Serial data input to internal DAC
30	DOUT	O	Serial audio data output
31	SCKIN	I	Serial clock input to internal DAC
32	SCKO	O	Audio data that is output from DOUT changes at rising edge of this clock
33	LRCKIN	I	LRCK signal input to internal DAC
34	LRCK	O	Signals to distinguish the right and left channels of the audio data output from DOUT
35	WDCK	O	Output double the frequency of LRCK
36	TX	O	Digital audio interface data output
37	GND		Logic circuit GND
38	C16M	O	Oscillator clock buffering output
39	LIMIT	I	Status of the pin is output at Bit 5 of the status output
40	VDD		Positive power supply terminal to logic circuit
41	LOCK	O	EFM synchronous detection signal
42	RFCK	O	Frame synchronous signal of XTAL-system
43	WFCK	O	Frame synchronous signal of PLL-system
44	PLCK	O	Monitor pin of bit clock
45	GND		Logic circuit GND
46	C1D1	O	Output pin for indicating the C1 error correction results
47	C1D2	O	Output pin for indicating the C1 error correction results
48	C2D1	O	Output pin for indicating the C2 error correction results
49	C2D2	O	Output pin for indicating the C2 error correction results
50	C2D3	O	Output pin for indicating the C2 error correction results
51	VDD		Positive power supply terminal to logic circuit
52	PACK	O	CD-TEXT PACK synchronous signal
53	TSO	O	CD-TEXT data serial output
54	TSI	I	CD-TEXT control parameter serial input
55	TSCK	I	CD-TEXT serial clock input
56	TSTB	I	CD-TEXT parameter strobe signal input
57	GND		Logic circuit GND
58	TEST	I	Test pin

Pin No.	Pin Name	I/O	Function and Operation
59	ATEST	I/O	Test pin
60	RFMODE	I	Use/not use select for internal RF amplifier
61	A.GND		Analog circuit GND
62	FD	O	Focus drive output
63	TD	O	Tracking drive output
64	SD	O	Sled drive output
65	MD	O	Spindle drive output
66	DACO	O	DAC output for adjustment
67	FBAL	O	DAC output for adjustment
68	TBAL	O	DAC output for adjustment
69	TEVCA	O	DAC output for adjustment
70	A.VDD		Power supply terminal to analog circuit
71	EFM	O	EFM signal output
72	ASY	I	EFM comparator reference voltage input
73	C3T		3T detection capacitor additional pin
74	RFI	I	RF signal input for EFM data regulation
75	AGCO	O	RF signal output of after gain adjustment
76	AGCI	I	RF-AGC amplifier input
77	RFO	O	RF summing amplifier output
78	EQ2		RF amplifier equalizer parts additional pin
79	EQ1		RF amplifier equalizer parts additional pin
80	RF-	I	RF summing amplifier inverted input
81	A.GND		Analog circuit GND
82	A	I	Photo detector A input
83	C	I	Photo detector C input
84	B	I	Photo detector B input
85	D	I	Photo detector D input
86	F	I	Photo detector F input
87	E	I	Photo detector E input
88	A.VDD		Positive power supply terminal to analog circuit
89	REFOUT	O	Reference electric potential output
90	FE-	I	Focus error amplifier inverted input
91	FEO	I/O	Focus error amplifier output
92	TE-	I	Tracking error amplifier inverted input
93	TEO	I/O	Tracking error amplifier output
94	TE2	I/O	Tracking error output of after amplification
95	TEC	I	Tracking comparator input
96	A.GND		Analog circuit GND
97	PD	I	PD detection signal input for LD output monitor
98	LD	O	LD control current output
99	PN	I	APC circuit control polarity set pin
100	A.VDD		Positive power supply terminal to analog circuit

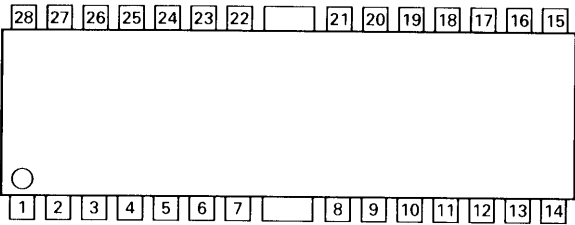
*UPD63710GC



● Pin Functions (BA5985FM)

Pin No.	Pin Name	I/O	Function and Operation
1	FWD	I	Loading driver FWD input
2	OPIN1(+)	I	CH1 pre-amplifier input
3	OPIN1(-)	I	CH1 pre-amplifier inverted input
4	OPOUT1	O	CH1 pre-amplifier output
5	OPIN2(+)	I	CH2 pre-amplifier input
6	OPIN2(-)	I	CH2 pre-amplifier inverted input
7	OPOUT2	O	CH2 pre-amplifier output
8	VCC		Power supply
9	VOL(-)	O	Loading driver negative output
10	VOL(+)	O	Loading driver positive output
11	VO2(-)	O	Driver CH2 negative output
12	VO2(+)	O	Driver CH2 positive output
13	VO1(-)	O	Driver CH1 negative output
14	VO1(+)	O	Driver CH1 positive output
15	VO4(+)	O	Driver CH4 positive output
16	VO4(-)	O	Driver CH4 negative output
17	VO3(+)	O	Driver CH3 positive output
18	VO3(-)	O	Driver CH3 negative output
19	GND		GND
20	BIAS	I	Bias input
21	MUTE		Mute control
22	OPOUT3	O	CH3 pre-amplifier output
23	OPIN3(-)	I	CH3 pre-amplifier inverted input
24	OPIN3(+)	I	CH3 pre-amplifier input
25	OPOUT4	O	CH4 pre-amplifier output
26	OPIN4(-)	I	CH4 pre-amplifier inverted input
27	OPIN4(+)	I	CH4 pre-amplifier input
28	REV	I	Loading driver REV input

BA5985FM

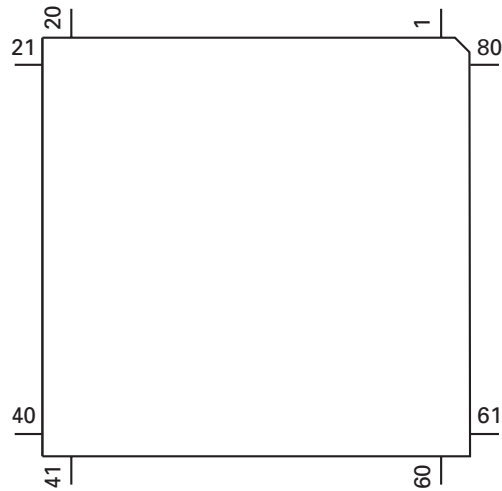


● Pin Functions(PE5011C)

Pin No.	Pin Name	I/O	Format	Function and Operation
1	EJTSNS			Disc eject position sense input
2	DSCSNS			Disc insert position sense input
3	VDSNS			VD power supply short sense input
4	TEMP			Temperature sense input
5-8	NC			Not used VSS
9	AVREF			A/D reference voltage input
10	RESET	I		System reset input
11	XT1	I		VDD
12	XT2			Open
13	IC(VPP)			VSS
14	X1	I		Main clock radiator(8.38MHz)connection
15	X2			Main clock radiator(8.38MHz)connection
16	VDD			Power supply(+5V)
17	VSS			GND
18	XSCK	O	C	CD LSI serial clock output
19	XSO	O	C	CD LSI serial data output
20	XSI	I		CD LSI serial data input
21	BRST			P-Bus reset input
22	PACK			CD-TEXT pack sync signal input
23, 24	NC			Not used Open
25	XA0	O	C	CD LSI data discrimination control signal output
26	XSTB	O	C	CD LSI strobe output
27	XRST	O	C	CD LSI reset output
28	FOK	I		Focus OK input
29	MIRR	I		Specular surface detection input
30	LOCK	I		Spindle lock input
31	CD5VON	O	C	CD +5V power supply control output
32, 33	NC			Not used Open
34	EMPH	O	C	Emphasis information output
35-44	NC			Not used Open
45	VSS			GND
46	VDD			Power supply(+5V)
47	ADENA	O	C	A/D reference voltage supply control output
48	VDCONT	O	C	VD power supply control output
49	NC			Not used Open
50	CSNS	I		Flap close sense input
51	BRXEN	I/O	/C	Input/output by which P-Bus can be received
52	BSRQ	O	C	P-Bus polling request output
53, 54	NC			Not used Open
55	CONT	O	C	Servo driver power supply control output
56	CDMUTE	O	C	CD mute control output
57	CDEJET	O	C	Load/Eject motor Eject control output
58	CDLOAD	O	C	Load/Eject motor Load control output
59	BMUTE	O	C	Bus mute output
60	CLAMP	I		Disc clamp input
61, 62	NC			Not used Open
63-66	NC			Not used VDD or VSS
67	TXARI	I		Tx output set selection input
68	FSCK	O	C	Flash writing clock input(Open)
69	FTXD	O	C	Flash writing data output(Open)
70	FRXD	O	C	Flash writing data input(Open)
71	BSCK	I/O	/C	P-Bus serial clock input/output
72	BDATA	I/O	/C	P-Bus serial data input/output
73	TESTIN	I		Test program start input
74	NC			Not used Open
75	TSTB	O	C	CD-TEXT strobe output
76	NC			Not used Open

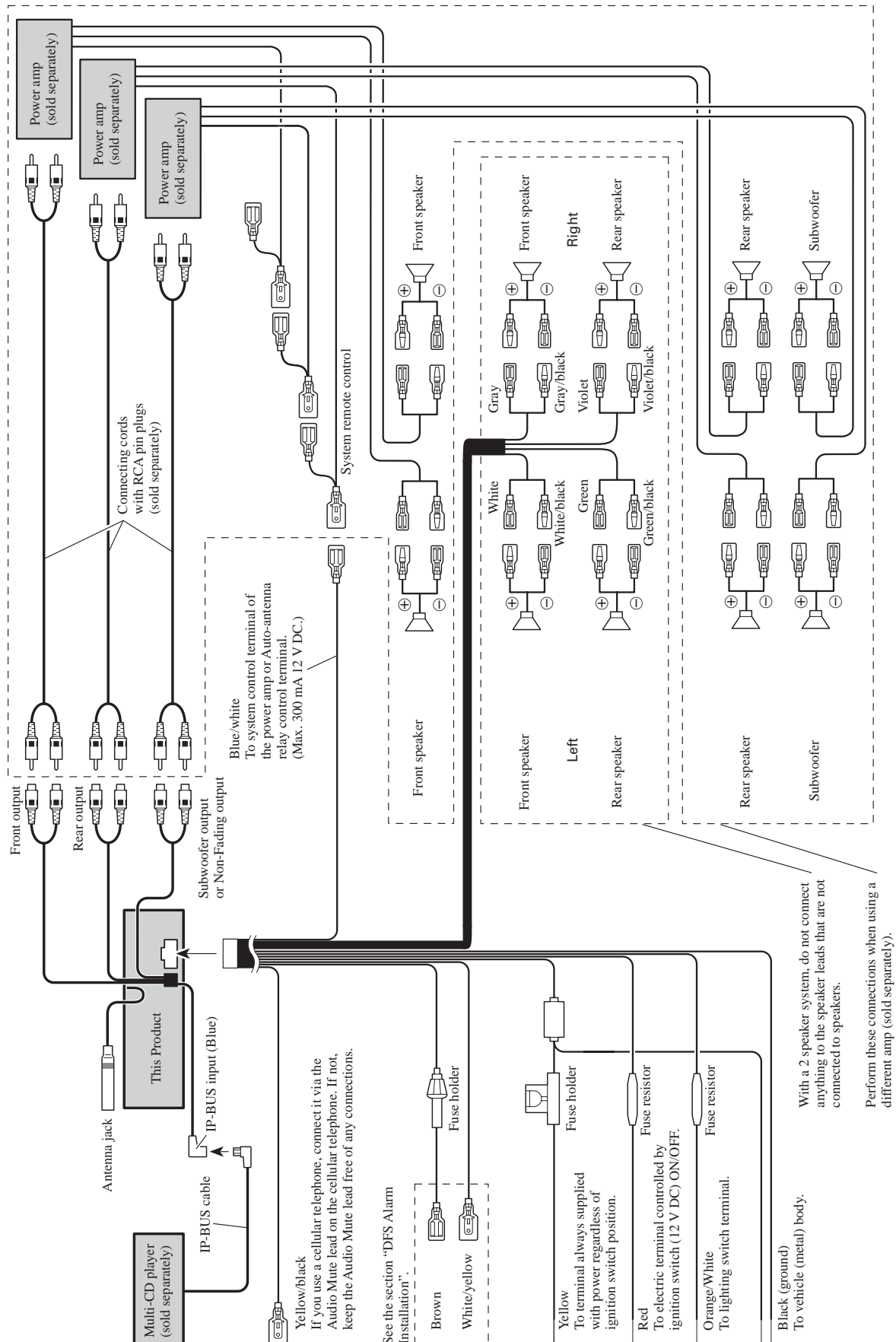
Pin No.	Pin Name	I/O	Format	Function and Operation
77	T $\overline{\text{SCK}}$	O	C	CD-TEXT serial clock output
78	TSO	O	C	CD-TEXT serial data output
79	TSI	I		CD-TEXT serial data input
80	AVSS			A/D GND

*PE5011C



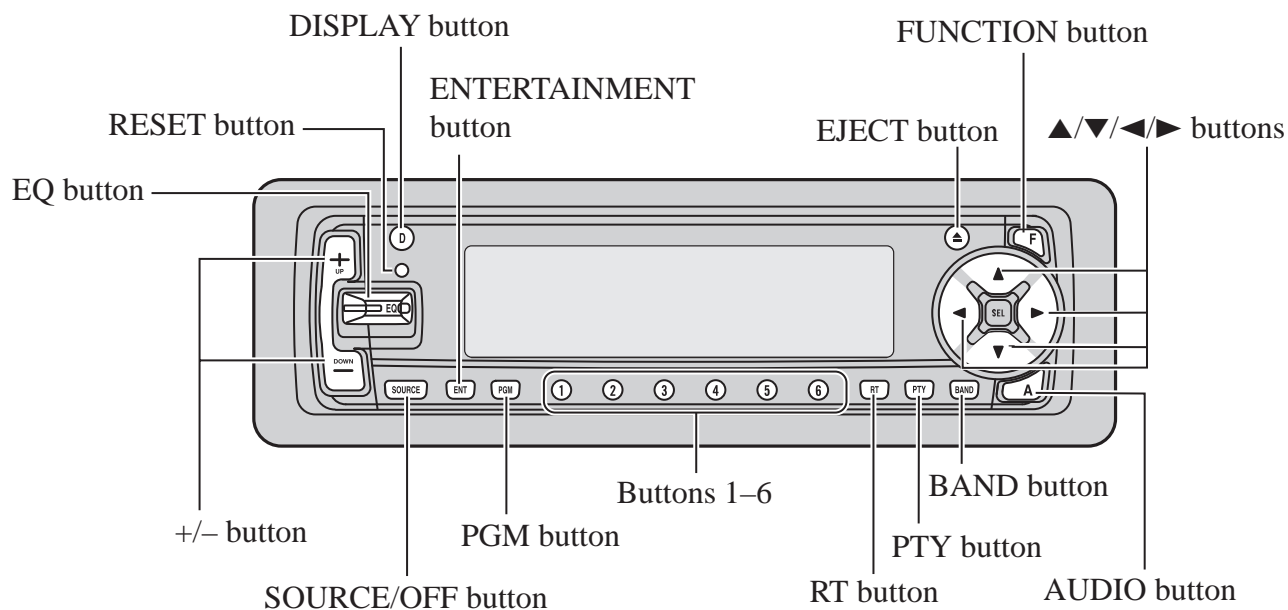
8. OPERATIONS AND SPECIFICATIONS

● Connection Diagram (DEH-P8000R/UC)



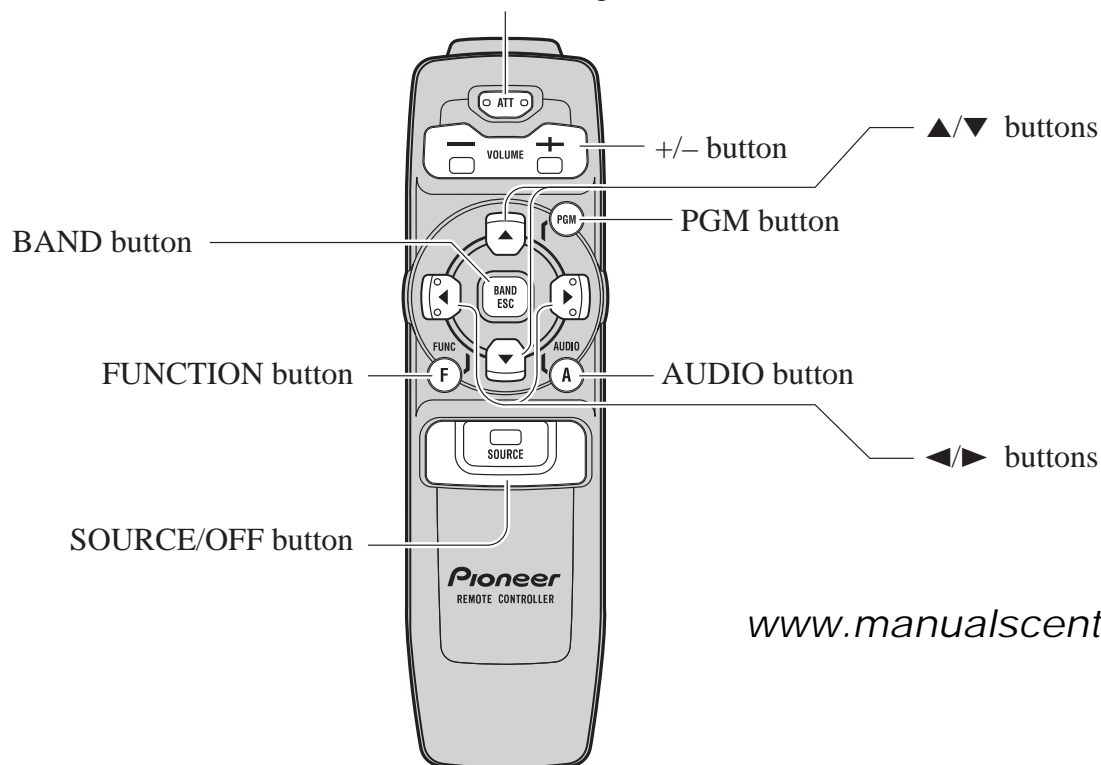


8.1 OPERATIONS (DEH-P8000R/UC))



ATT button

This lets you quickly lower volume level (by about 90%).
Press once more to return to the original volume level.



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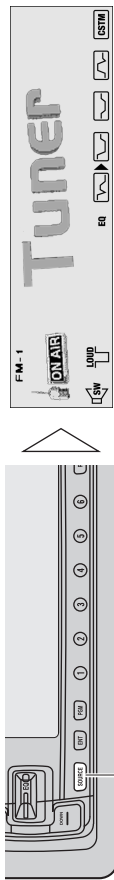
To Listen to Music

The following explains the initial operations required before you can listen to music.

Note:

- Loading a disc in this product.

1. Select the desired source (e.g. Tuner).



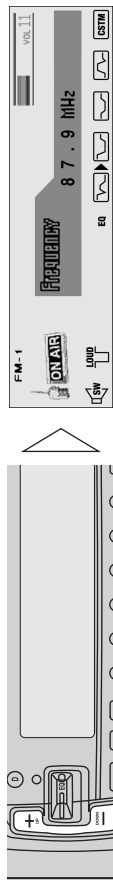
Each press changes the Source ...

Each press of the SOURCE/OFF button selects the desired source in the following order:
Built-in CD player (Compact Disc) → TV (Television) → Tuner → DAB (Digital Audio Broadcasting) Tuner → Multi-CD player → AUX

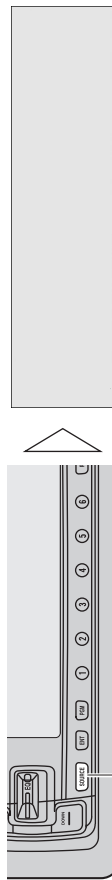
Note:

- In the following cases, the sound source will not change:
 - No TV tuner is connected to this product.
 - No Multi-CD player is connected to this product. (When "Multi-CD" display is OFF.)
 - No DAB tuner is connected to this product.
 - No disc is set in this product.
 - No magazine is set in the Multi-CD player.
 - AUX (external input) is set to OFF.

2. Raise or lower the volume.



3. Source OFF.



Hold for 1 second or more

Basic Operation of Tuner

Manual and Seek Tuning

- You can select the tuning method by changing the length of time you press the ◀/▶ button.

Manual Tuning (step by step)	0.5 seconds or less
Seek Tuning	0.5 seconds or more

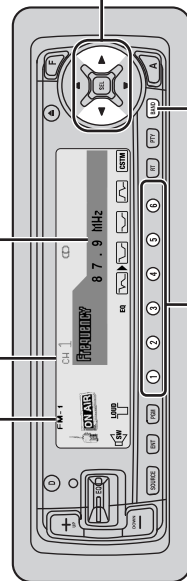
Note:

- If you continue pressing the button for longer than 0.5 seconds, you can skip broadcast stations. Seek Tuning starts as soon as you stop pressing the button.
- "CD" stereo indicator lights when a stereo station is selected.

Preset Number Indicator

Band Indicator

Frequency Indicator



Preset Tuning

- You can memorize broadcast stations in buttons 1 through 6 for easy, one-touch station recall.

Preset station recall	2 seconds or less
Broadcast station preset memory	2 seconds or more

Note:

- Up to 18 FM stations (6 in FM-1, FM-2 and FM-3) and 6 AM stations can be stored in memory.
- You can also use the ▲ or ▼ buttons to recall broadcast stations memorized in buttons 1 through 6.

Basic Operation of Built-in CD Player

Switching the Display

Each press of the DISPLAY button changes the display in the following order:
Playback mode (Play Time)
→ Disc Title

Note:

- If you switch a display when the disc title has not been input, "No Title" is displayed.

Eject

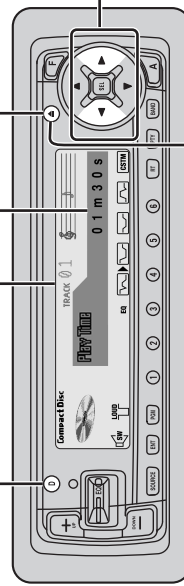
Press the EJECT button, and you can open the front panel before ejection.
In case of opening the front panel, you can just eject a CD.

Note:

- The CD function can be turned ON/OFF with the disc remaining in this product.
- Discs left partially inserted after ejection may incur damage or fall out.

Play Time Indicator

Track Number Indicator



Switching the Display (only for CD TEXT Discs)

Each press of the DISPLAY button changes the display in the following order:
Playback mode (Play Time) → Disc Title → Track Artist
With text longer than 20 letters, you can scroll to see the rest of the text by pressing the DISPLAY button for 2 seconds or more.

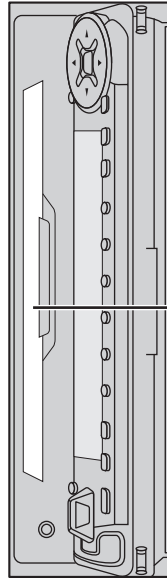
Note:

- A CD TEXT disc is a CD featuring recorded text information such as Disc Title, Artist Name and Track Title.
- If you switch a display when the disc title has not been input, "No Title" is displayed.
- If you switch a display when the disc artist has not been input, "No Artist Name" is displayed.
- If you switch a display when the track title has not been input, "No Title" is displayed.
- If you switch a display when the track artist has not been input, "No Artist Name" is displayed.

Track Search and Fast Forward/Reverse

- You can select between Track Search or Fast Forward/Reverse by pressing the ◀/▶ button for a different length of time.

Track Search	0.5 seconds or less
Fast Forward/Reverse	Continue pressing



Disc Loading Slot

If a CD is inserted, the front panel is closed automatically.
The Built-in CD player plays one standard 12 cm or 8 cm (single) CD at a time. Do not use an adapter when playing 8 cm CD.

Note:

- If a disc cannot be inserted fully or playback fails, make sure the recorded side is down. Push the EJECT button and check the disc for damage before reinserting it.
- If the Built-in CD player cannot operate properly, an error message (such as "ERROR-14") appears on the display.

Open

Press the EJECT button for 1 second or more, and you can open the front panel without ejecting a CD.
In case of opening the front panel, you can close it.

Note:

- When opening the front panel, the 1 to 6 buttons are not available.

WARNING:

- Do not use with the front panel left open. If you do leave it open, it may result in injury in the event of an accident.

Basic Operation of Multi-CD Player

This product can control a Multi-CD player. (With certain old type Multi-CD players, using a multiple connection adapter lets you connect multiple units which you can control with this product.)

Track Search and Fast Forward/Reverse

- You can select between **Track Search or Fast Forward/Reverse** by pressing the ◀/▶ button for a different length of time.

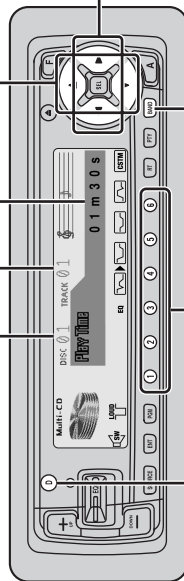
Track Search	0.5 seconds or less
Fast Forward/Reverse	Continue pressing

Track Number Indicator

Disc Number Indicator

Play Time Indicator

Disc Search



Switching the Display

Each press of the **DISPLAY** button changes the display in the following order:

- Playback mode (Play Time)
→ Disc Title

Note:

- If you switch displays when disc titles have not been input, "No Title" is displayed.

Switching the Multi-CD Player

When two or more Multi-CD players are connected using a multiple connection adapter, you can select the Multi-CD player by pressing the **BAND** button.

Magazine 1 → Magazine 2
→ Magazine 3
(Displayed about for 2 seconds.)

Disc Number Search (for 6-Disc, 12-Disc types)

- You can select discs directly with the **1 to 6** buttons. Just press the number corresponding to the disc you want to listen to.

Note:

- When a 12-Disc Multi-CD Player is connected and you want to select disc 7 to 12, press the 1 to 6 buttons for 2 seconds or longer.

Disc Number Rough Search (for 50-Disc type only)

This handy function lets you select discs loaded in a 50-Disc Multi-CD Player using the 1 to 5 buttons. The 50 discs are divided into five blocks, with each of the 1 to 5 buttons assigned to a block.

- Select the desired block with the **1 to 5** buttons.

Note:

- After completing a rough search, use the ▲ and ▼ buttons to select a desired disc.

Note:

- The Multi-CD player may perform a preparatory operation, such as verifying the presence of a disc or reading disc information, when the power is turned ON or a new disc is selected for playback. "READY" is displayed.
- When a magazine is loaded into a 50-Disc type Multi-CD Player, information on all the discs in the magazine is read.
If you start playing a disc on a 50-Disc type Multi-CD Player before reading of information on all discs has been completed, reading of information stops part way through. This will prevent you from using the ITS function. (If you try and use this function, "Not Ready" is displayed.) If this happens, reading of information begins again when you switch to a component other than the 50-Disc Type Multi-CD Player.
- If the Multi-CD player cannot operate properly, an error message such as "ERROR-14" is displayed. Refer to Multi-CD Player Owner's Manual.
- If there are no discs in the Multi-CD player magazine, "No Disc" is displayed.
- "LOADING" will be displayed in the following cases:
 - If the disc in the extra tray is selected.
 - If the disc is moved from the extra tray to the magazine.
(Refer to the 50-Disc Type Multi-CD Player Owner's Manual.)
- You cannot use the "Ejecting a Single Disc", "Frequency Play", "Music Group Play" or "ABC Disc Title Search" functions with this product.

When playing a CD TEXT disc on a CD TEXT compatible Multi-CD Player such as the CDX-P650:

- You can use the following two functions. Refer to Multi-CD Player's Owner's Manual for operation details.
 - Title display switching
 - Title scroll
- You cannot switch to the Disc Title Input mode in the Detailed Setting Menu.

Specifications (DEH-P8000R/UC)

General

Power source	14.4 V DC (10.8 – 15.1 V allowable)
Grounding system	Negative type
Max. current consumption	10.0 A
Dimensions	
(DIN) (chassis)	178 (W) × 50 (H) × 155 (D) mm
[7 (W) × 2 (H) × 6-1/8 (D) in.]	
(nose)	188 (W) × 58 (H) × 20 (D) mm
[7-3/8 (W) × 2-1/4 (H) × 3/4 (D) in.]	
(D)	178 (W) × 50 (H) × 160 (D) mm
[7 (W) × 2 (H) × 6-1/4 (D) in.]	
(nose)	170 (W) × 46 (H) × 15 (D) mm
[6-3/4 (W) × 1-3/4 (H) × 5/8 (D) in.]	
Weight	1.8 kg (4.0 lbs)

Audio

Continuous power output is 22 W per channel min. into 4 ohms, both channels driven 50 to 15,000 Hz with no more than 5% THD.

Maximum power output 45 W × 4
45 W × 2 ch/4 Ω + 70 W × 1 ch/2 Ω (for Subwoofer)

Load impedance 4 Ω (4 – 8 Ω [2 Ω for 1 ch] allowable)

Preout maximum output level/output impedance 4.0 V/100 Ω

AM tuner

Frequency range	530 – 1,710 kHz
Usable sensitivity	18 μV (S/N: 20 dB)
Selectivity	50 dB (±10 kHz)
(Low)	Frequency: 40/80/100/160 Hz Q Factor: 0.35/0.59/0.95/1.15 (+6 dB when boosted)
(Mid)	Frequency: 200/500/1k/2k Hz Q Factor: 0.35/0.59/0.95/1.15 (+6 dB when boosted)
(High)	Frequency: 3.15k/8k/10k/12.5k Hz Q Factor: 0.35/0.59/0.95/1.15 (+6 dB when boosted)
Loudness contour	
(Low)	+3.5 dB (100 Hz), +3 dB (10 kHz)
(Mid)	+10 dB (100 Hz), +6.5 dB (10 kHz)
(High)	+11 dB (100 Hz), +11 dB (10 kHz) (volume: –30 dB)

HPF

Frequency	50/80/125 Hz
Slope	–12 dB/oct.
Subwoofer output	
Frequency	50/80/125 Hz
Slope	–18 dB/oct.
Gain	±12 dB
Phase	Normal/Reverse

Specifications (DEH-P8050/ES)

General

Power source	14.4 V DC (10.8 – 15.1 V allowable)
Grounding system	Negative type
Max. current consumption	10.0 A
Dimensions	
(DIN) (chassis)	178 (W) × 50 (H) × 155 (D) mm
(nose)	188 (W) × 58 (H) × 20 (D) mm
(D)	178 (W) × 50 (H) × 160 (D) mm
(nose)	170 (W) × 46 (H) × 15 (D) mm
Weight	1.8 kg

Audio

Continuous power output is 22 W per channel min. into 4 ohms, both channels driven 50 to 15,000 Hz with no more than 5% THD.

Maximum power output 45 W × 4
45 W × 2 ch/4 Ω + 70 W × 1 ch/2 Ω (for Subwoofer)

Load impedance 4 Ω (4 – 8 Ω [2 Ω for 1 ch] allowable)

Preout maximum output level/output impedance 4.0 V/100 Ω

Equalizer (3-Band Parametric Equalizer)

(Low)	Frequency: 40/80/100/160 Hz Q Factor: 0.35/0.59/0.95/1.15 (+6 dB when boosted)
(Mid)	Frequency: 200/500/1k/2k Hz Q Factor: 0.35/0.59/0.95/1.15 (+6 dB when boosted)
(High)	Frequency: 3.15k/8k/10k/12.5k Hz Q Factor: 0.35/0.59/0.95/1.15 (+6 dB when boosted)
Loudness contour	
(Low)	+3.5 dB (100 Hz), +3 dB (10 kHz)
(Mid)	+10 dB (100 Hz), +6.5 dB (10 kHz)
(High)	+11 dB (100 Hz), +11 dB (10 kHz) (volume: –30 dB)

HPF

Frequency	50/80/125 Hz
Slope	–12 dB/oct.
Subwoofer output	
Frequency	50/80/125 Hz
Slope	–18 dB/oct.
Level	±12 dB
Phase	Normal/Reverse

CD player

System	Compact disc audio system
Usable discs	Compact disc
Signal format	Sampling frequency: 44.1 kHz Number of quantization bits: 16; linear
Frequency characteristics	5 – 20,000 Hz (±1 dB)
Signal-to-noise ratio	95 dB (1 kHz) (IEC-A network)
Dynamic range	94 dB (1 kHz)
Number of channels	2 (stereo)

FM tuner

Frequency range	87.5 – 108 MHz
Usable sensitivity	10 dBf (0.9 μV/75 Ω, mono, S/N: 30 dB)
50 dB quieting sensitivity	15 dBf (1.5 μV/75 Ω, mono)
Signal-to-noise ratio	70 dB (IEC-A network)
Distortion	0.3% (at 65 dBf, 1 kHz, stereo)
Frequency response	30 – 15,000 Hz (±3 dB)
Stereo separation	40 dB (at 65 dBf, 1 kHz)

AM tuner

Frequency range	531 – 1,602 kHz (9 kHz)
Usable sensitivity	530 – 1,710 kHz (10 kHz) 18 μV (S/N: 20 dB)
Selectivity	50 dB (±9 kHz) 50 dB (±10 kHz)

Service Manual

ORDER NO.
CRT2300

CD MECHANISM MODULE

CX-916

- This service manual describes the operation of the CD mechanism incorporated in models listed in the table below.
- When performing repairs use this manual together with the specific manual for model under repair.

Model	Service Manual	CD Mechanism Module	Mechanism Unit
DEH-P400/X1N/UC DEH-P4000/X1N/UC DEH-P4050/X1N/ES	CRT2308	CXK5200	CXB3100
DEH-P3000R/X1N/EW	CRT2309	CXK5200	CXB3100
DEH-P200/X1N/UC DEH-P300/X1N/UC DEH-P3000/X1N/UC	CRT2310	CXK5200	CXB3100
DEH-P20/X1N/UC DEH-P2000/X1N/UC DEH-P2050/X1N/ES	CRT2311	CXK5200	CXB3100
DEH-2000R/X1N/EW DEH-2020R/X1N/GR DEH-2030R/X1N/EW	CRT2312	CXK5200	CXB3100
DEH-10/X1N/UC DEH-1000/X1N/UC DEH-1050/X1N/ES	CRT2313	CXK5200	CXB3100

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2. MECHANISM DESCRIPTIONS.....	17
3. DISASSEMBLY	18

PIONEER ELECTRONIC CORPORATION 4-1, Meguro 1-Chome, Meguro-ku, Tokyo 153-8654, Japan
PIONEER ELECTRONICS SERVICE INC. P.O.Box 1760, Long Beach, CA 90801-1760 U.S.A.
PIONEER ELECTRONIC [EUROPE] N.V. Haven 1087 Keetberglaan 1, 9120 Melsele, Belgium
PIONEER ELECTRONICS ASIACENTRE PTE.LTD. 253 Alexandra Road, #04-01, Singapore 159936

1. CIRCUIT DESCRIPTIONS

The LSI (UPD63710GC) used on this unit comprises five main blocks ; the pre-amp section, servo, signal processor, DAC and CD text decoder (not used on this model). It also equips with nine automatic adjustment functions.

1.1 PRE-AMP SECTION

This section processes the pickup output signals to create the signals for the servo, demodulator and control.

The pickup output signals are I-V converted by the pre-amp with the built-in photo-detector in the pickup, then added by the RF amp to obtain RF, FE, TE, TE zero cross and other signals.

This pre-amp section is built in the servo LSI UPD63710GC (IC201). The following describes function of each section.

Since this system has a single power supply (+5V), the reference voltage for this LSI and pickup are set to REFO (2.5V). The REFO is obtained by passing the REFOUT from the LSI through the buffer amplifier. The REFO is output from Pin 89 of this LSI. All measurements are done using this REFO as reference.

Note : During the measurement, do not try to short the REFO and GND.

1) APC Circuit (Automatic Power Control)

When the laser diode is driven with constant current, the optical output has large negative temperature characteristics. Thus, the current must be controlled from the monitor diode so that the output may be constant. APC circuit is for it. The LD current is obtained by measuring the voltage between LD1 and V+5. The value of this current is about 35mA.

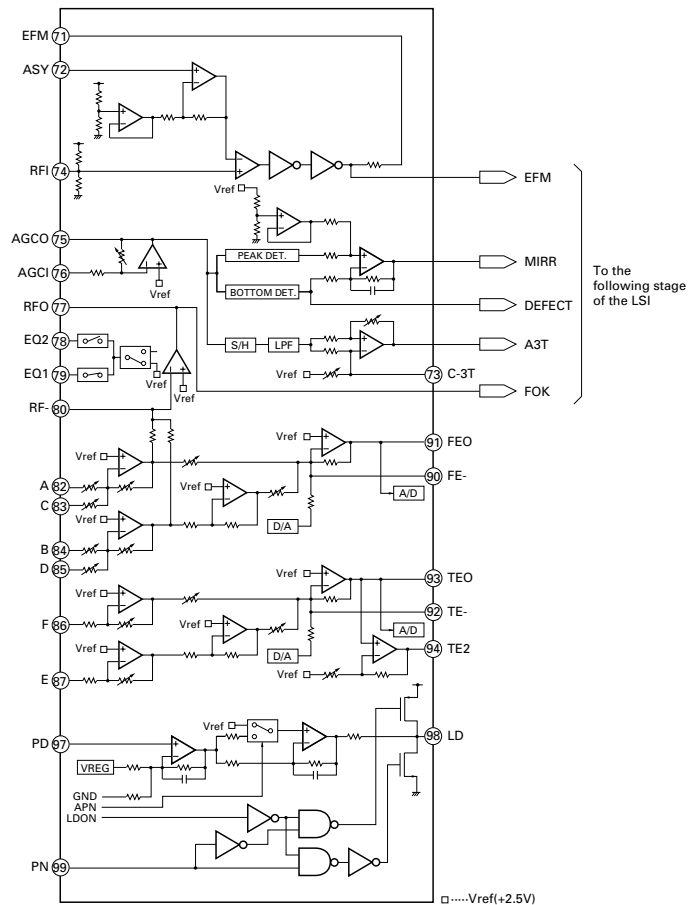


Fig.1 : BLOCK DIAGRAM OF BUILT-IN RF AMPLIFIER

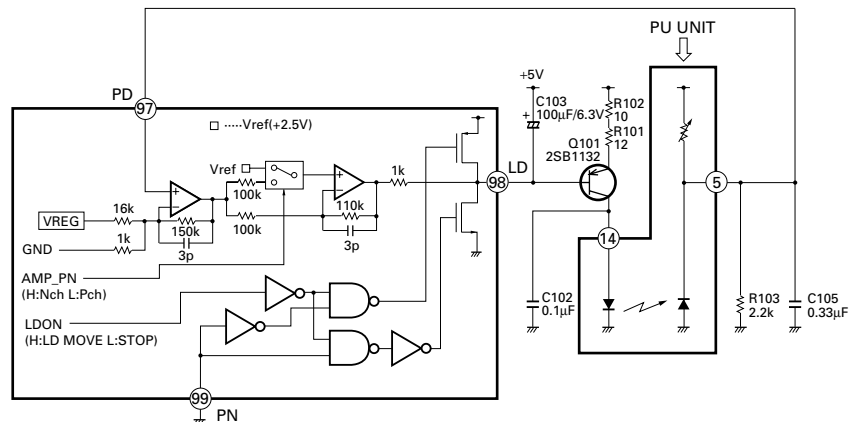


Fig.2 : APC CIRCUIT

2) RF Amplifier and RFAGC Amplifier

The photo-detector outputs (A + C) and (B + D) are added, amplified and equalized on this LSI and then output to the RFI terminal as the RF signal. (The eye pattern can be checked by this signal.)

The RFI voltage low frequency component is :

$$RFI = (A + B + C + D) \times 3.2$$

RFI is used on the FOK generator circuit and RF offset adjusting circuit.

R214 is an offset resistor for maintaining the bottom reference voltage of the RFI signal at 1.5 VDC. The D/A output used for the RF offset adjustment (to be described later) is entered via this resistor.

After the RFI signal from Pin 77 is externally AC coupled, entered to Pin 76 again, then amplified on the RFAGC amplifier to obtain the RFO signal.

The RFAGC adjustment function (to be described later) built-in the LSI is used for switching feedback gain of the RFAGC amplifier so that the RFO output may go to $1.5 \pm 0.3V_{pp}$.

The RFO signal is used for the EFM, DFCT, MIRR and RFAGC adjustment circuits.

3) RFOK Circuit

This circuit generates the signal that is used for indicating the timing of closing the focus or state of the focus close currently being played. This signal is output from Pin 4 as the FOK signal. It goes high when the focus close and in-play.

The RFOK signal is generated by holding DC level of the RFI at its peak with the succeeding digital section, then comparing it at a specific threshold level. Thus, the RFOK signal goes high even if the pit is absent. It indicates that the focus close can take place on the disc mirror surface, too.

This signal is also supplied to the micro computer via the low pass filter as the FOK signal and used for the protection and the RF amplifier gain switching.

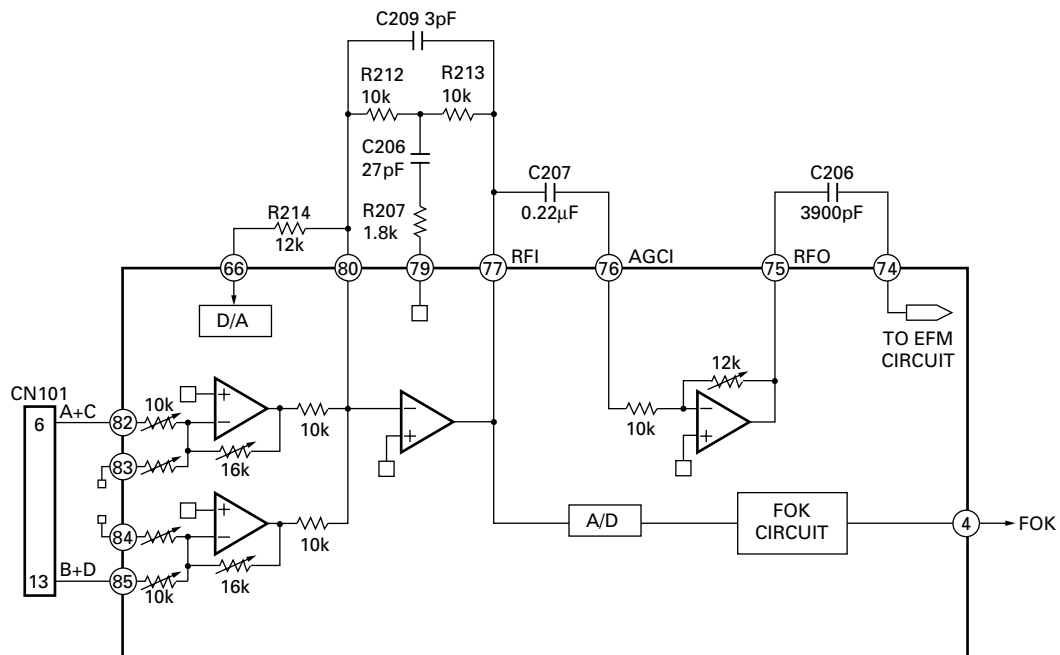


Fig.3 : RFAMP, RFAGC AND FOK CIRCUIT

4) Focus Error Amplifier

The photo-detector outputs (A + C) and (B + D) are passed through a differential amplifier and an error amplifier, and then (A + C - B - D) is output from Pin 91 as the FE signal.

The FE voltage low frequency component is :

$$FE = (A + C - B - D) \times \frac{16k}{10k} \times \frac{(80k/300k)}{20k}$$

$$= (A + C - B - D) \times 5$$

Using REFO as the reference, an S-curve of approximately 1.5 Vpp is obtained for the FE output. The final-stage amplifier cutoff frequency is 11.4 kHz.

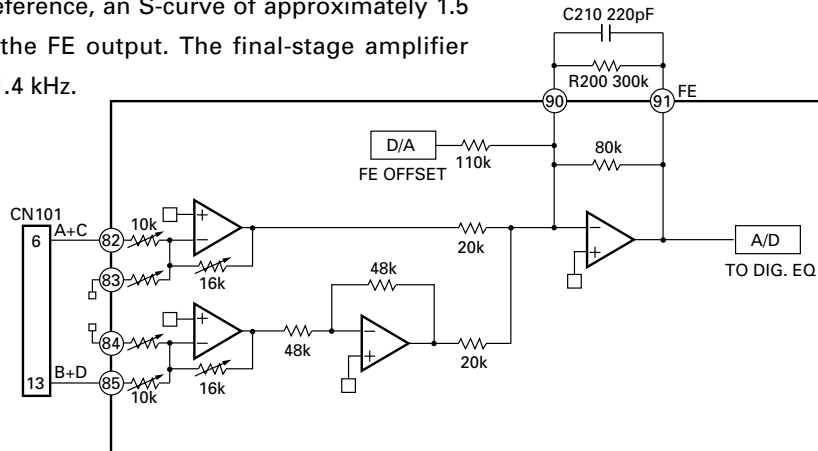


Fig.4 : FOCUS ERROR AMPLIFIER

5) Tracking Error Amplifier

The photo-detector outputs E and F are passed through a differential amplifier and an error amplifier, and then (E - F) is output from Pin 93 as the TE signal. The TE voltage low frequency component is :

$$TE = (E - F) \times \frac{224k}{(56k+27k)} \times \frac{80k}{38k}$$

$$= (E - F) \times 5.7 \text{ (Effective LSI output is 5.0).}$$

Using REFO as the reference, the TE waveform of approximately 1.3 Vpp is obtained for the TE output. The final-stage amplifier cutoff frequency is 20 kHz.

6) Tracking Zero Crossing Amplifier

TEC signal (the tracking zero crossing signal) is obtained by multiplying the TE signal four times. It is used for locating the zero crossing points of the tracking error. The zero cross point detection is done for the following two reasons :

- ① To count tracks for carriage moves and track jumps.
- ② To detect the direction in which the lens is moving when the tracking is closed (it is used on the tracking brake circuit to be described later).

The TEC signal frequency range is 300 Hz to 20 kHz.

$$TEC \text{ voltage} = TE \text{ level} \times 4$$

Theoretical TEC level is 5.2V. The signal exceeds D-range of the operational amplifier and thus is clipped. It, however, can be ignored since this signal is used by the servo LSI only at the zero crossing point.

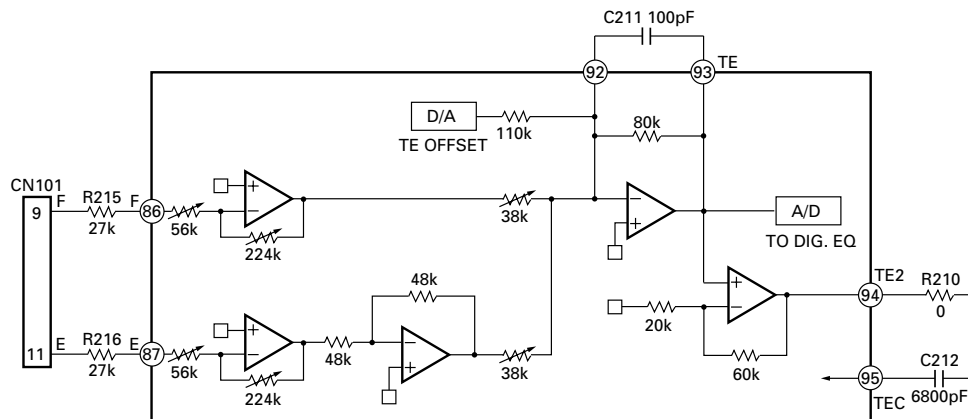


Fig.5 TRACKING ERROR AMPLIFIER AND TRACKING ZERO CROSSING AMPLIFIER

7) DFCT (Defect) Circuit

The DFCT signal is used for detecting defects on the mirrored disc surface. It allows monitoring from the HOLD pin (Pin 2). It goes high when defects are found on the mirrored surface.

The DFCT signal is generated by comparing the RF amplified signal (which is obtained by bottom holding the RFO signal) at a specific threshold level by the succeeding digital section.

Stains or scratches on the disc can constitute the defects on the mirrored disc surface. Thus, as long as the DFCT signal remains high in the LSI, the focus and tracking servo drives are held in the current state so that a better defect prevention may be ensured.

8) 3TOUT Circuit

The 3TOUT signal is generated by entering disturbance to the focus servo loop, comparing phase of fluctuations of the RF signal 3T component against that of the FE signal at that time, then converting the signal to DC level. This signal is used for adjusting bias of the FE signal (to be described later). This signal is not output from the LSI, thus its monitoring is not available.

9) MIRR (Mirror) Circuit

The MIRR signal shows the on track and off track data, and is output from Pin 3.

When the laser beam is

On track : MIRR = "L"

Off track : MIRR = "H"

This signal is used on the brake circuit (to be described later) and also as the trigger to turn on track counting when jumping take place.

The MIRR signal is supplied to the micro computer, too, for the protection purpose.

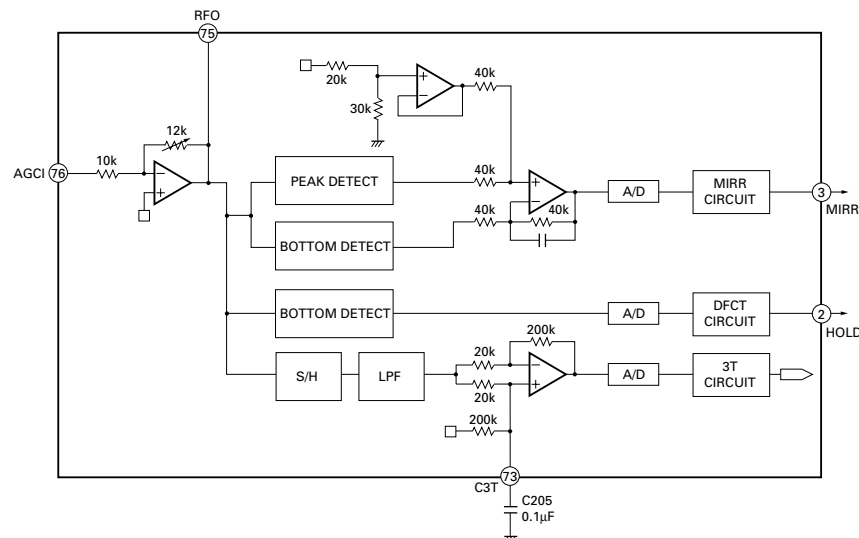


Fig.6 : DFCT, MIRR AND 3T DETECTION CIRCUIT

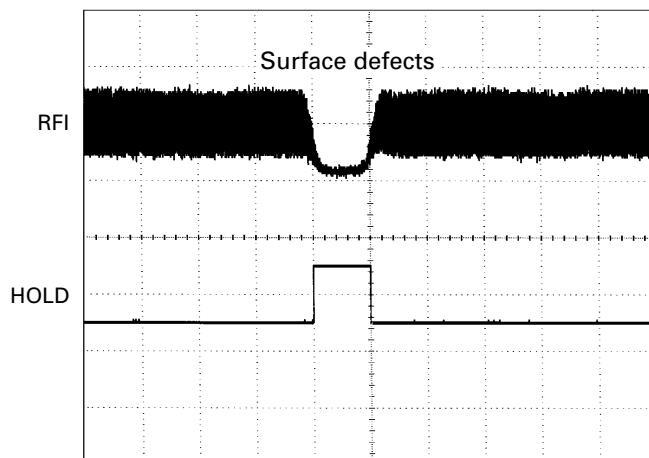


Fig.7 : HOLD OUTPUT WAVEFORM
(When surface defects are present)

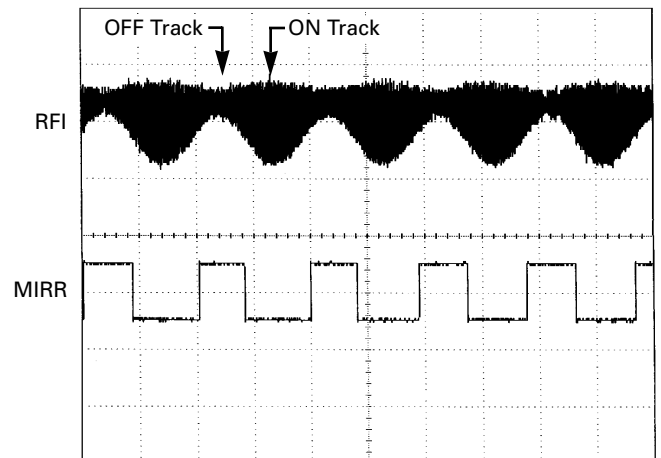


Fig.8 : MIRR OUTPUT WAVEFORM
(When an access is made)

10) EFM Circuit

This circuit is used for converting the RF signal to digital signal consisting of "0" and "1". The RFO signal from Pin 75 is externally AC coupled, entered to Pin 74, then applied to the EFM circuit.

Loss of the RF signal due to scratches or stains on the disc, or vertical asymmetry of the RF due to variations in the discs manufactured can't be eliminated by AC coupling alone. This circuit, therefore, controls the reference voltage ASY on the EFM comparator by use of the fact that "0" and "1" appear fifty fifty in the EFM signal. By this arrangement, the compare level is constantly maintained at almost center of the RFO signal level. The reference voltage ASY is generated when the EFM comparator output is passed through the low pass filter. The EFM signal is output from Pin 71. It is a 2.5 Vp-p amplitude signal centering on REFO.

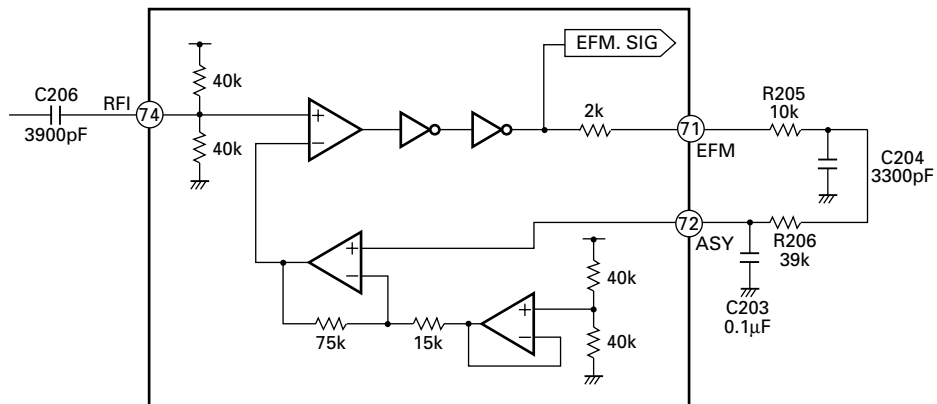


Fig.9 : EFM CIRCUIT

1.2 SERVO SECTION (UPD63710GC : IC201)

The servo section controls the operations such as error signal equalizing, in focus, track jump and carriage move. The DSP is the signal processing section used for data decoding, error correction and interpolation processing, among others.

This circuit implements analog to digital conversion of the FE and TE signals generated on the pre-amplifier, then outputs them through the servo block as the drive signal used on the focus, tracking and carriage system. The EFM signal is decoded on the signal processing section and finally output via the D/A converter as the audio signal. The decoding process also generates the spindle servo error signals which is fed to the spindle servo block to generate the spindle drive signal.

The focus, tracking, carriage and spindle drive signals are then amplified on the driver IC BA5985FM (IC301) and fed to respective actuators and motors.

1) Focus Servo System

The focus servo main equalizer is consisted of the digital equalizer. Fig.10 shows the focus servo block diagram.

When implementing the focus close on the focus servo system, the lens must be brought within the in-focus range. Therefore, the lens is moved up and down according to the triangular focus search voltage to find the focus point. During this time, the spindle motor is kicked and kept rotating as a set speed.

The servo LSI monitors the FE and RFOK signals and automatically carries out the focus close at an appropriate point.

The focus closing is carried out when the following three conditions are met :

- ① The lens approaches the disc from its current position.
- ② RFOK = "H"
- ③ The FZC signal is latched at high after it has once crossed the threshold set on the FZD register (Edge of the FZD).

As the result, the FE (= REFO) is forced to low.

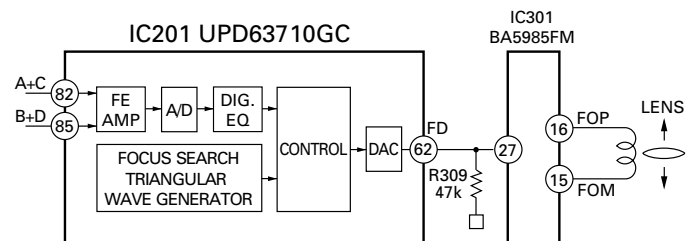


Fig.10 : FOCUS SERVO BLOCK DIAGRAM

When the above conditions are all met and the focus is closed, the XSI pin goes to low from the current high, then 40 ms later, the microcomputer begins to monitor the RFOK signal after it that has been passed through the low pass filter.

When the RFOK signal is recognized as low, the micro computer carries out various actions including protection.

Fig.11 a series of operations carried out relevant to the focus close (the figure shows the case where focus close is not available).

You can check the S-curve, search voltage and actual lens behavior by selecting the Display 01 for the focus mode select in the test mode, and then pressing the focus close button.

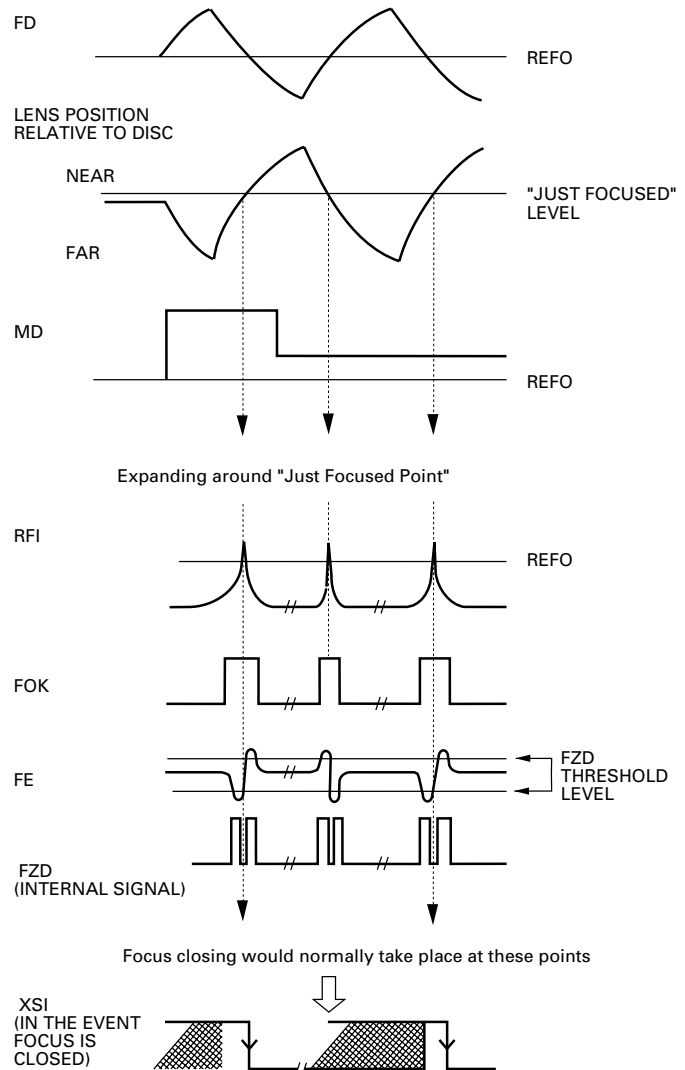


Fig.11 : FOCUS CLOSE SEQUENCE

2) Tracking Servo System

The digital equalizer is employed for the main equalizer on the tracking servo. Fig.12 shows the tracking servo block diagram.

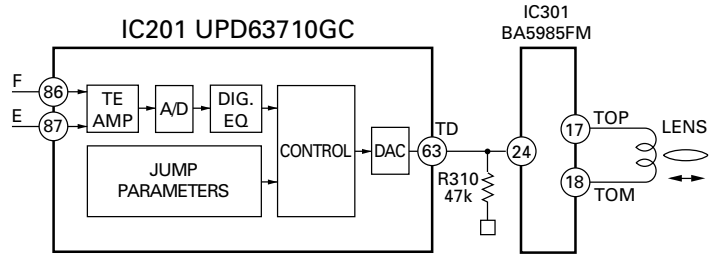


Fig.12 : TRACKING SERVO BLOCK DIAGRAM

a) Track jump

When the LSI receives the track jump command from the microcomputer, the operation is carried out automatically by the auto sequence function of the LSI. This system has five types of track jumps used for the search : 1, 4, 10, 32 and 32×3 . In the test mode, in addition to three jumps (1, 32 and 32×3), move of the carriage can be check by mode selection. For track jumps, the microcomputer sets almost half of tracks (5 tracks for 10 tracks, for instance) and counts the set number of tracks using the TEC signals. When the microcomputer has counted the set number of tracks, it outputs the brake pulse for a fixed period of time (duration can be specified with the command) to stop the lens. In this way, the tracking is closed and normal play is continued.

To improve the servo loop retracting performance just after the track jump, the brake circuit is turned on for 50 ms after the brake pulse has been terminated to increase gain of the tracking servo.

Fast forward and reverse operations are realized by through consecutive signal track jumps. The speed is about 10 times as fast as that in the normal mode.

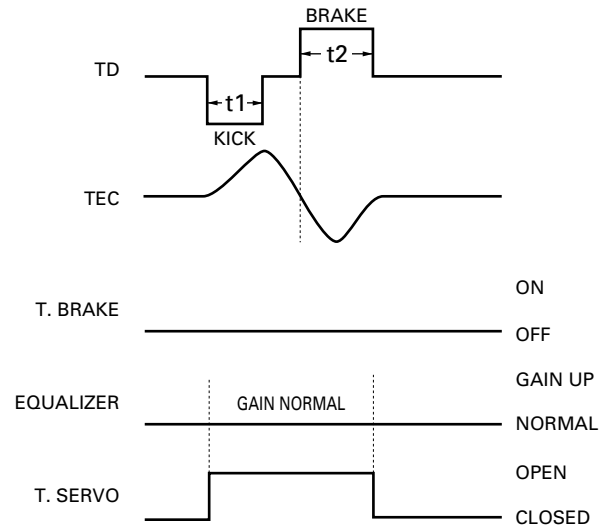


Fig.13 : SINGLE TRACK JUMP

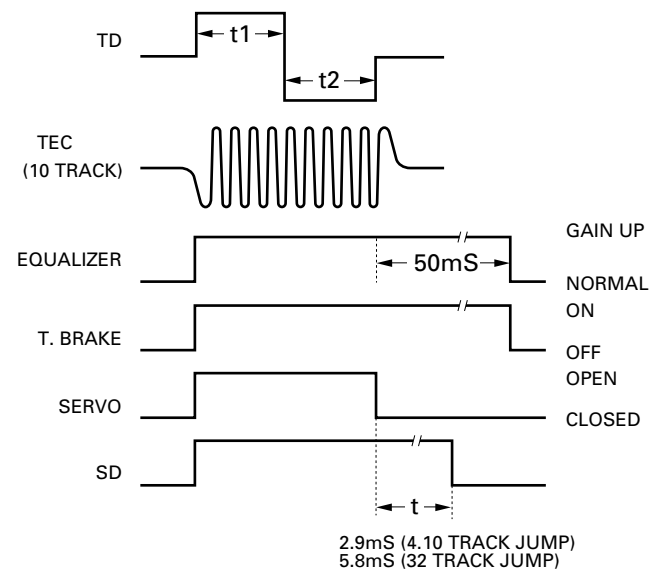
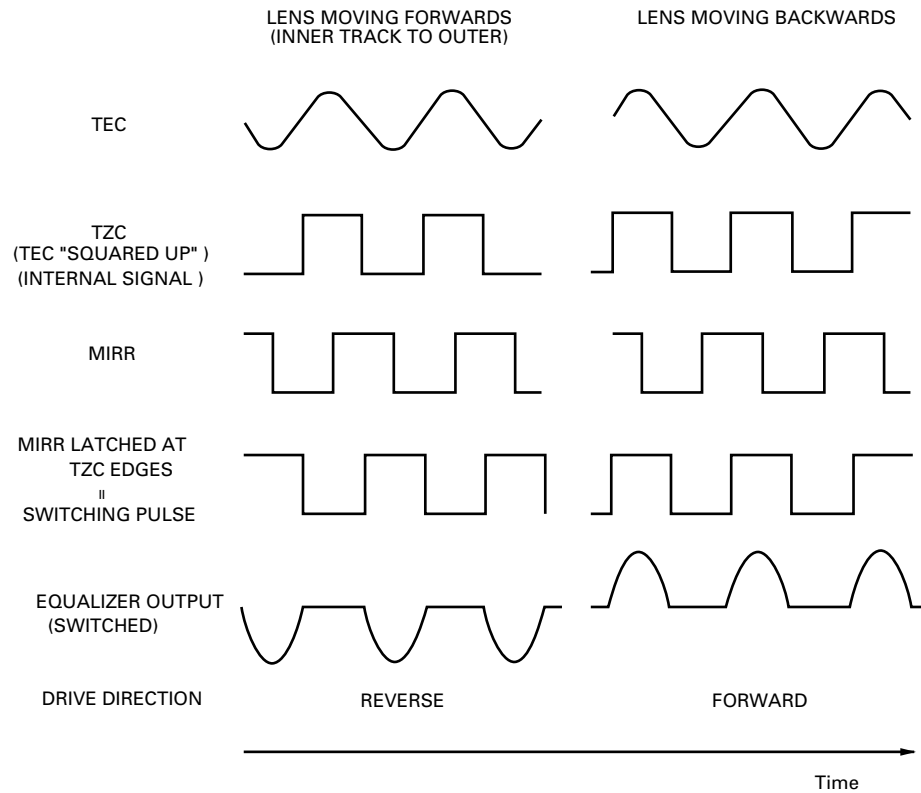


Fig.14 : MULTI-TRACK JUMP

b) Brake Circuit

The servo retracting performance can be deteriorate during the setup or track jump operation. In this connection, the brake circuit is used to ensure steady retract of the tracking servo. The brake circuit detects in which direction the lens is moving, then slows down its move by outputting the drive signal that moves the lens into the opposite direction alone. Track slippage direction is determined by referencing the TEC and MIRR signals and their phase.



Note : Equalizer output assumed to have same phase as TEC.

Fig.15 : TRACKING BRAKE CIRCUIT

3) Carriage Servo System

The carriage servo supplies the tracking equalizer's low-frequency component (lens position data) output to the carriage equalizer, then, after providing a fixed amount of gain to it, outputs the drive signal from the LSI. This signal is then applied to the carriage motor via the driver IC.

When the lens offset reaches a certain level during play, the entire pickup must be moved into the forward direction. Therefore, the equalizer gain is set to the level that allows to generate a voltage higher than the carriage motor starting voltage. In actual operations, a certain threshold level is set for the equalizer output by the servo LSI so that the drive voltage may be output from the servo LSI only when the equalizer output exceeds the threshold level. This arrangement helps reducing power consumption. Also, due to disc eccentricity or other factors, the equalizer output may cross the threshold level a number of times. In this case, the drive voltage output from the LSI will have pulse-like waveform.

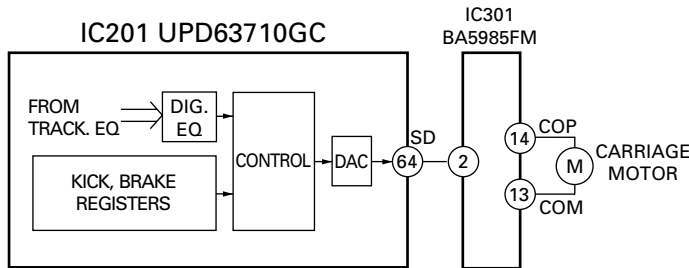


Fig.16 : CARRIAGE SERVO BLOCK DIAGRAM

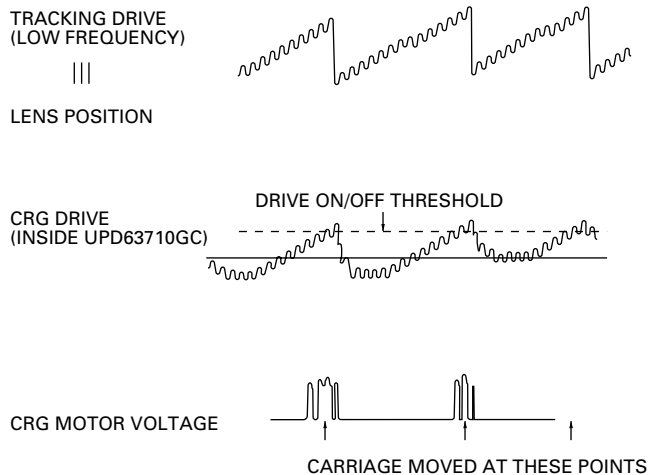


Fig.17 : CARRIAGE SIGNAL WAVEFORM

4) Spindle Servo System

The spindle servo has the following modes.

① Kick :

This mode is used for accelerating the disc rotation during setup.

② Offset :

(a) After the kick is over in the setup, this mode is turned on until changing to rough servo mode.

(b) When focus is lost during play, this mode is turned on until the focus is restored.

Both of the above are used for maintaining the disc rotation rate near to the specified rate.

③ Applicable servo :

The CLV servo mode is turned on for the normal operations.

In the EFM demodulation block, the frame sync signal and internal counter output signal are sampled for every WFCK/16 and a signal is produced for indicating whether or not they are matching.

They are determined to be asynchronous only when this signal fails to match 8 times in succession. In all other cases, above two signals are assumed to be synchronous. In the applicable servo mode, the retracting servo is automatically selected if the two signals are synchronous. If not, the regular servo is automatically selected.

④ Brake :

This mode is turned on when stopping the spindle motor.

The microcomputer outputs the brake voltage through the servo LSI. The LSI monitors the EFM waveform and, if its longest pattern exceeds a certain interval (if the rotation is sufficiently slow), the flag is set the LSI and the microcomputer turns off the brake voltage. When the flag is not up within a specified period time, the microcomputer switches the mode from the brake to the stop mode, and maintains this mode for a fixed period of time. If this stop mode is continued for a fixed period of time, the disc will be ejected.

⑤ Stop :

This mode is used for powering on the system and the eject operation. When this mode is turned on, voltage across the spindle motor is 0V.

⑥ Rough servo :

This mode is used for when the carriage feed (carriage mode for the long search, etc.) is turned on. The linear speed is calculated from the EFM waveform and high or low level is entered to the spindle equalizer. In the test mode, this mode is also used for the grating check.

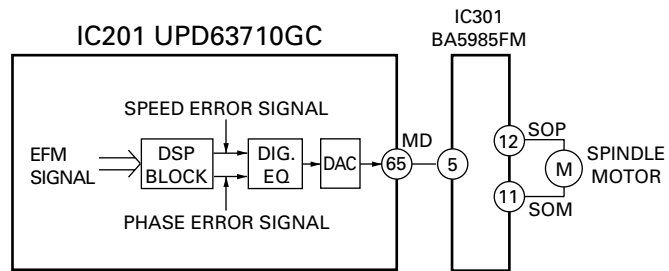


Fig.18 : SPINDLE SERVO MOTOR BLOCK DIAGRAM

1.3 AUTOMATIC ADJUSTMENT FUNCTIONS

Every circuit adjustment on the CD-LSI of this system is automated.

Every circuit adjustment is automatically implemented when the disc is inserted or the CD mode is selected from the source key. The following describes how the adjustments are executed.

1) FZD Cancel Setting

This setting is used for executing the focus close operation without fail.

When power is turned on, the FE offset level is read and a voltage opposite to this offset value is written to the CRAM on the IC to cancel the offset. In this manner, the FZD threshold level can be set to a constant value (+240mV), thereby ensuring to meet one of the requirements for the IC to execute the focus close that "the FZD signal is latched at high".

2) Automatic Adjustment of TE, FE and RF Offset

Using REFO as the reference, this function adjusts the pre-amp TE, FE and RF offsets to the respective target value when power is turned on (targets values of the TE, FE and RF are 0, 0 and -1V, respectively).

The following is the adjustment procedure :

- (1) Respective offset (LD off) is read by the microcomputer via the servo LSI.
- (2) The microcomputer calculates the voltages to be corrected from the read values, then sets them to the specified field.

3) Automatic Adjustment of Tracking Balance (T. BAL)

This adjustment is used for eliminating differences between the pickup E and F channels outputs by adjusting gain of the amplifier on the LSI. In the actual operation, the TE waveform is adjusted so that it may be vertically symmetric with REFO.

The following is the adjustment procedure :

- (1) Make sure the focus close is complete.
- (2) Kick the lens in the radial direction to generate the TE waveform.
- (3) At this time, the microcomputer reads the TE signal offset value (via the servo LSI) being calculated by the LSI.

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- (4) The microcomputer determines if the read offset value is positive, negative or zero.

If the offset value = 0, the adjustment is terminated.

If the offset value = A positive or negative value, gain of the E and F channels amplifiers are modified according the predetermined rule.

Then above steps (2) through (4) are repeated until the "Offset value = 0" or "Specified limit count" is reached.

4) Automatic Adjustment of FE Bias

This adjustment is intended at maximizing the RFI level by optimizing the focus point in-play. This adjustment utilizes the phase difference between the RF waveform 3T level and the focus error signal when disturbance is applied.

Since disturbance is applied to the focus loop, this adjustment is designed to take place in the same timing as the auto gain control (to be described later).

The following is the adjustment procedure :

- (1) Disturbance is injected to the focus loop by the command from the microcomputer (within the servo LSI).
- (2) The LSI detects fluctuation of the RF signal 3T component level.
- (3) The LSI determines relationship between fluctuation of the 3T component and the injected disturbance to detect magnitude and direction of the off-focus introduced.
- (4) The microcomputer reads the detected results from the LSI.
- (5) The microcomputer calculates necessary correction, then hands the calculated value to the bias adjustment term set on the LSI.

This adjustment is repeated several times, as it is so with the auto gain control, to ensure higher accuracy.

5) Focus and Tracking Automatic Gain Control

This function is used for implementing automatic control of the focus and tracking loop gain.

The following is the adjustment procedure :

- (1) Inject disturbance to the servo loop.
- (2) Extract the error signal (FE and TE) generated at when the disturbance is applied to obtain the signals G1 and G2 via the B.P.F.
- (3) The microcomputer reads the G1 and G2 signals via the LSI.
- (4) Based on the necessary correction calculated by the microcomputer, the LSI performs the loop gain adjustment.

Above adjustments are repeated several times to ensure higher adjustment accuracy.

6) Automatic RF Level Adjustment (RFAGC)

This adjustment is used for implementing intended signal transmission successfully by adjusting unevenness of the RF signal (RFO) levels, that results from disc and machine relevant factors, to a target value. The adjustment is actually done by varying gain of the amplifier provided between the RFI and RFO.

The following is the adjustment procedure :

- (1) Using the command, the microcomputer reads the output from the RF level detection circuit on the servo LSI.
- (2) Based on the read value, the microcomputer calculates an amplifier gain that will produce the target RFO level.
- (3) The microcomputer sends the corresponding command to the servo LSI so that the above gain value may be set.

This adjustment takes place at the following timing :

- When the focus close alone is completed during the setup process.
- Just before the setup is completed (just before the play takes place).
- After the off-focus has been corrected during the play.

7) Adjustment of Pre-Amp Stage Gain

It is used for adjusting the entire RFAMP (FE, TE and RF amplifiers) to +6dB or +12dB depending on given gain level when reflected light from the disc is significantly below the required level due to stained lens. This phenomena can be noticed when playing back the CD-RW.

The following is the adjustment procedure :

When reflected light from disc is judged to be significantly below the required level during the setup, set the entire RFAMP to +6dB or +12dB. In this case, if the gain is modified, the setup have to be repeated from the first step.

Through the adjustment, if you judged the play becomes available by setting the entire RFAMP to +6dB, +6dB should be selected for the setup next time on.

See the figure below :

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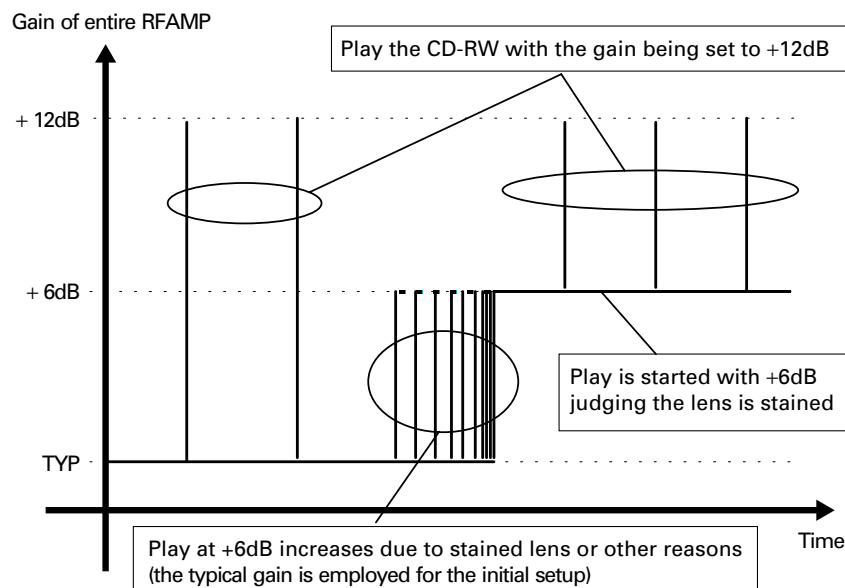


Fig.19 : CONCEPTUAL DIAGRAM OF PRE-AMP GAIN ADJUSTMENT

8) Initial Adjusting Values

All the automatic adjustments are implemented using the previous adjustment values as the initial values unless the microcomputer power (the backup power) is not turned off (though there are some exceptions).

When the backup is turned off, automatic adjustment is executed based on the initial values rather than the previous adjustment values.

9) Displaying Coefficients After Adjustment

You can display and check results of some automatic adjustments (FE and RF offset, FZD cancel and F / T / RFAGC) from the test mode. The following coefficients are displayed in each automatic adjustment :

(1) FE and RF offset and FZD cancel

Reference value = 32 (The coefficient of 32 indicates that no adjustment was required).

The results are displayed in multiples of approximately 40 mV.

An example : When FZD cancel coefficient = 35

$$35 - 32 = 3$$

$$3 \times 40 \text{ mV} = 120 \text{ mV}$$

Since the corrected value is approximately +120 mV, the FE offset before adjustment was -120 mV.

(2) F and T gain adjustment

Reference value = Focus/Tracking = 20

A coefficient displayed indicates an amount of adjustment conducted on the reference value.

An example : When AGC coefficient = 40

$40/20 = \text{Overall gain has been doubled (+6dB)}$. (The original loop gain of 1/2 has been doubled to have the targeted overall gain.)

(3) RF level adjustment (RFAGC)

Reference value = 8

Coefficient = 9 to 15 The direction in which the RF level is increased (the gain is increased).

Coefficient = 7 to 0 The direction in which the RF level is decreased (the gain is decreased).

Incrementing or decreasing the coefficient by "1" varies the gain by 0.7 to 1dB.

Maximum gain = Typically +6.5dB. Coefficient at this time is 15.

Minimum gain = Typically -6.0dB. Coefficient at this time is 0.

1.4 POWER SUPPLY AND LOADING SECTION

The power supply of the system uses VD (8.3V) from the mother board. VD is fed to 5 channel CD driver IC, 5V Reg IC and disc detection LED.

The microcomputer turns on or off the CD driver and the 5V using "CONT" and "CD5VON", respectively. The loading drive is turned on or off by the input signals "CDEJET" and "CDLOAD". No control terminal is provided for turning the loading drive on or off.

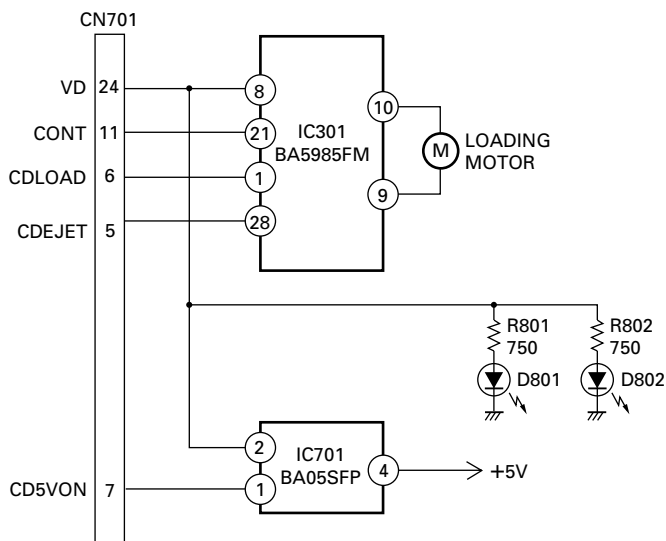
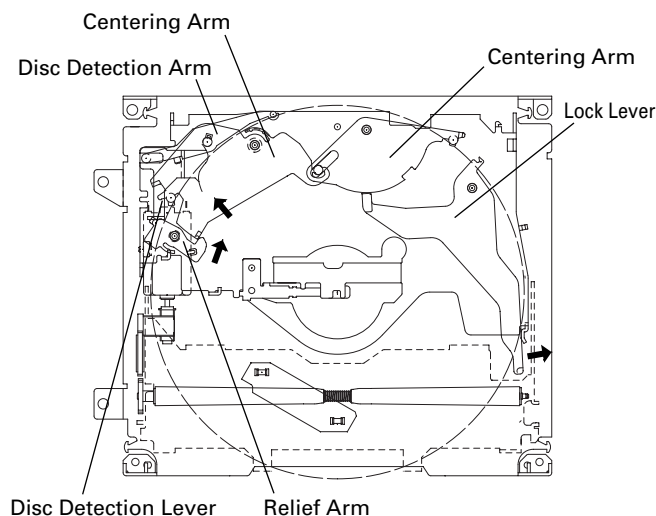


Fig.20 : POWER SUPPLY AND LOADING SECTION

2. MECHANISM DESCRIPTIONS

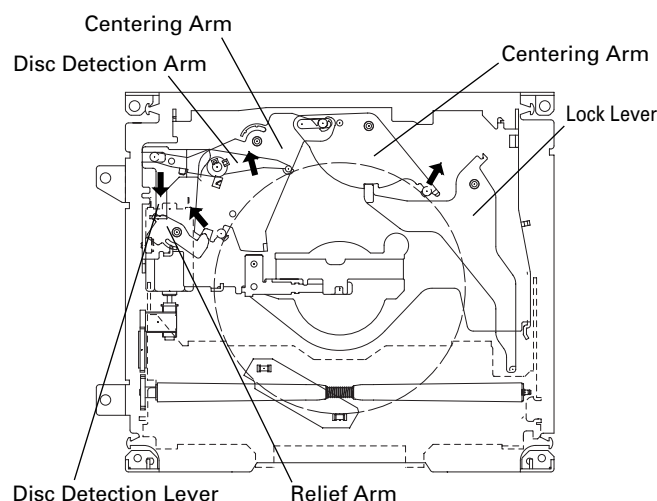
● Loading Operation (when a 12 cm disc is used)

1. Insert a 12 cm disc (the sensor turns on the motor revolution).
2. The disc pushes the Lock Lever in, thereby resetting the lock currently applied to the Centering Arms.
3. The disc further pushes the Centering Arms in.
4. The right side and left side arms are engaged to perform centering of the disc.
5. The disc pushes the Disc Detection Arm in, thereby pushing the Disc Detection Lever forward.
6. Clamping action retracts the Disc Detection Lever toward forward side, thereby rotating the Relief Arm.
7. The Relief Arm further pushes the Centering Arm in, thus detaching it from the disc.



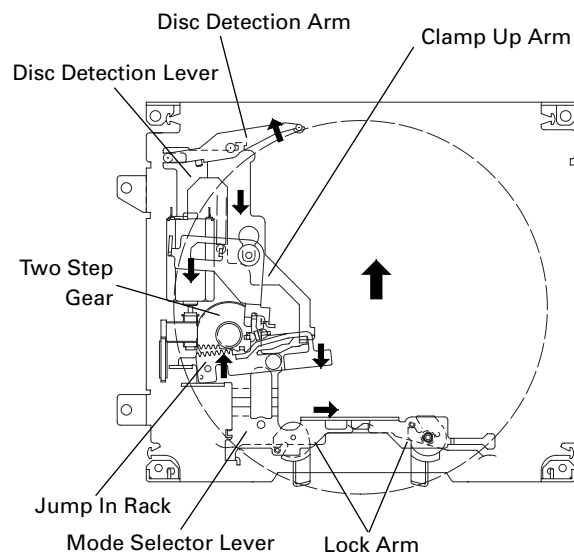
● Loading Operation (when a 8 cm disc is used)

1. Insert an 8 cm disc (the sensor turns on the motor revolution).
2. The disc does not contact against the Lock Lever, thus centering of the disc is performed by the Centering Arm being locked.
3. When the right side slot is used, the lock currently applied to the Centering Arm remains turned on even if the disc may touch the Lock Lever because the disc leaves the lever before it reaches the Centering Arm.
4. Succeeding procedures are the same as that for 12 cm discs.



● Clamping Operation

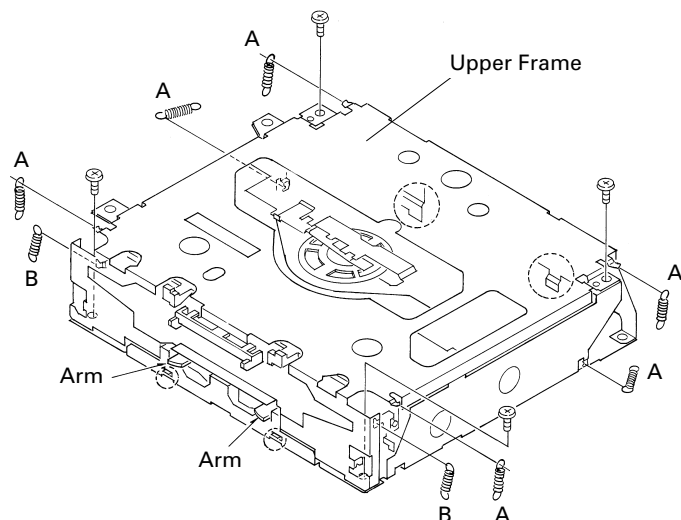
1. Insert a disc.
2. The Detection Arm pushed forward by the Detection Lever turns on rotation of the Jump In Rack.
3. The Jump In Rack then engages with the Two Step Gear and moves toward right.
4. At the same time, the Mode Selector Lever connected to the Jump In Rack starts moving toward right, thereby rotating the Lock Arm and resetting the mechanical lock. The Clamp Up Arm too is rotated by the above action and, thus, the Clamp Up Arm now being lifted by shape of the cam of the Clamp Arm is lowered. And, the Guide Arm is also moved down because of shape of the cam of the Mode Selector Lever.
5. By use of the cam shape, the Jump In Rack being moved toward right retracts the Disc Detection Lever in forward direction, thereby turning on rotation of the Relief Arm.



3. DISASSEMBLY

● Removing the Upper Frame

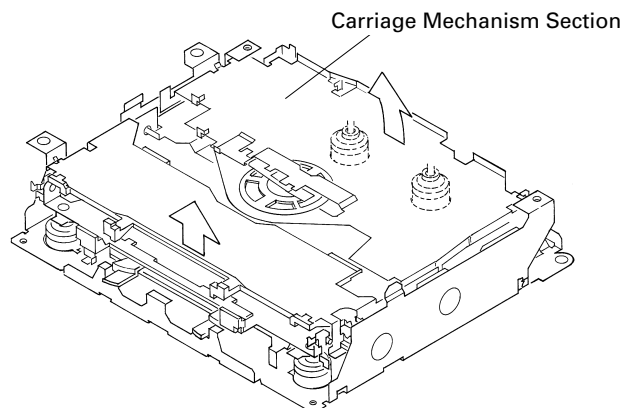
1. Remove six Springs A, two Springs B and four Screws.
2. Remove two Tabs situated on rear side of the Upper Frame, remove two Arms on the front side, then remove two Tabs on the front side.



● Removing the Carriage Mechanism

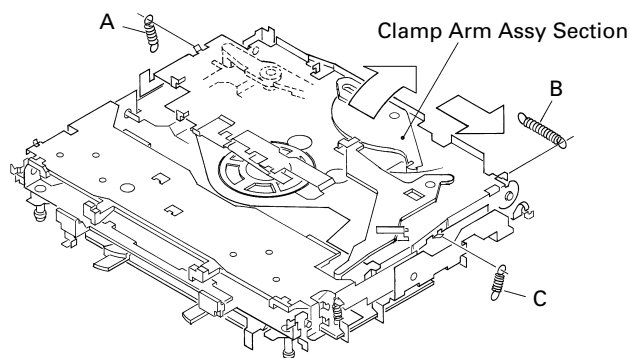
1. Disengage the Carriage Mechanism from the two dampers situated in the front side by driving it up, then disengage and remove the mechanism from the two dampers by driving it up aslant into front side direction.

Note : When assembling the Carriage Mechanism, coat the dampers with alcohol prior to the assembly.



● Removing the Clamp Arm Assy

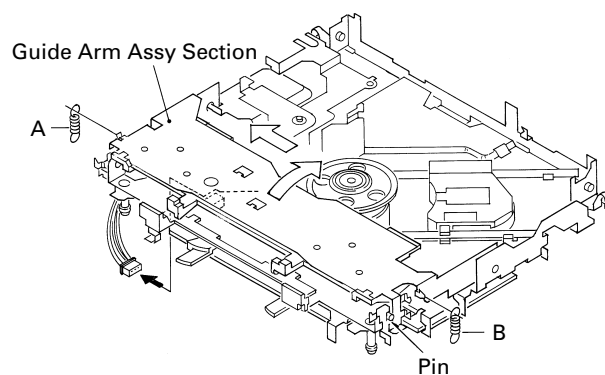
1. Remove a Spring A, a B and a Spring C.
2. Drive the Clamp Arm Assy up into rear side direction, then disengage the arm from its current position. Finally, drive the assembly approximately 45 degrees upward, then slide the assembly toward right side to remove it.



● Removing the Guide Arm Assy

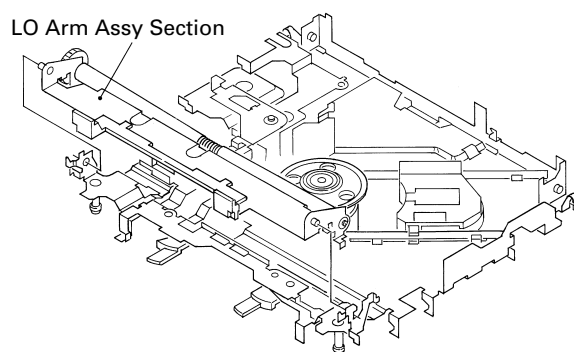
1. Remove a connector, a spring A and B
2. Drive the Guide Arm Assy up aslant into rear side direction, then remove it from a Pin. Finally, drive the assembly approximately 45 degrees upward, then slide the assembly toward left side to remove it.

Note : When assembling the guide arm assembly, route the cord inside the assembly. In this operation, care must be exercised so that cord may be caught by the gear.



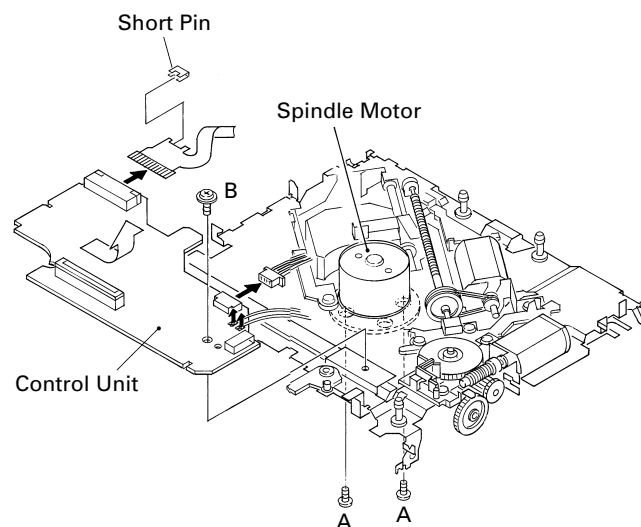
● Removing the LO Arm Assy

1. Remove two Pins to dismount the LO Arm Assy.



● Removing the Control Unit and the Spindle Motor

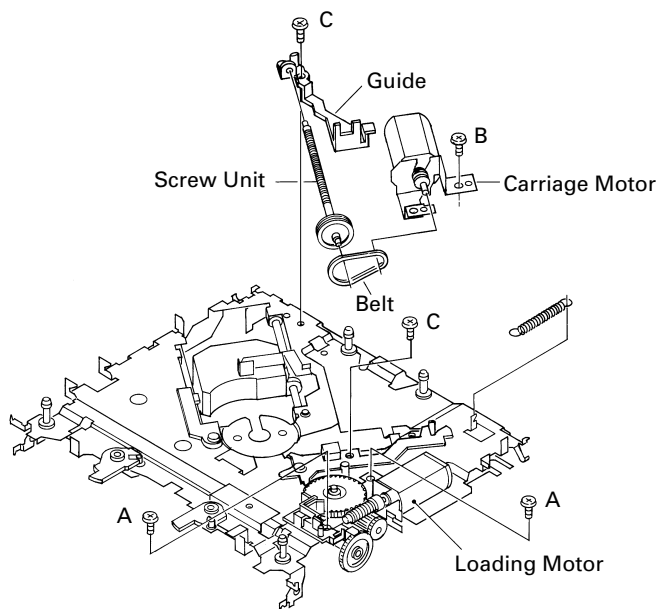
1. Remove from the connector after mounting the short pin on the flexible PCB of the pickup unit.
2. Remove two Soldered joints, then remove two Screws A.
3. Remove two connectors and a Screw B.
4. Disengage the Control Unit from two Tabs, then dismount the unit by sliding it toward left.
5. Dismount the Spindle Motor.



● Removing the Loading Motor and Carriage Motor

1. Remove the Spring and two Screws A.
2. Dismount the Loading Motor.
3. Remove the Belt, a Screw B, two Screws C, a Guide and a Screw Unit.
4. Dismount the Carriage Motor.

Note : When assembling the Belt, use care so that it may not be contaminated by grease.



● Removing the Pickup Unit

1. Remove two Screws and a Shaft.
2. Dismount the Pickup Unit.

